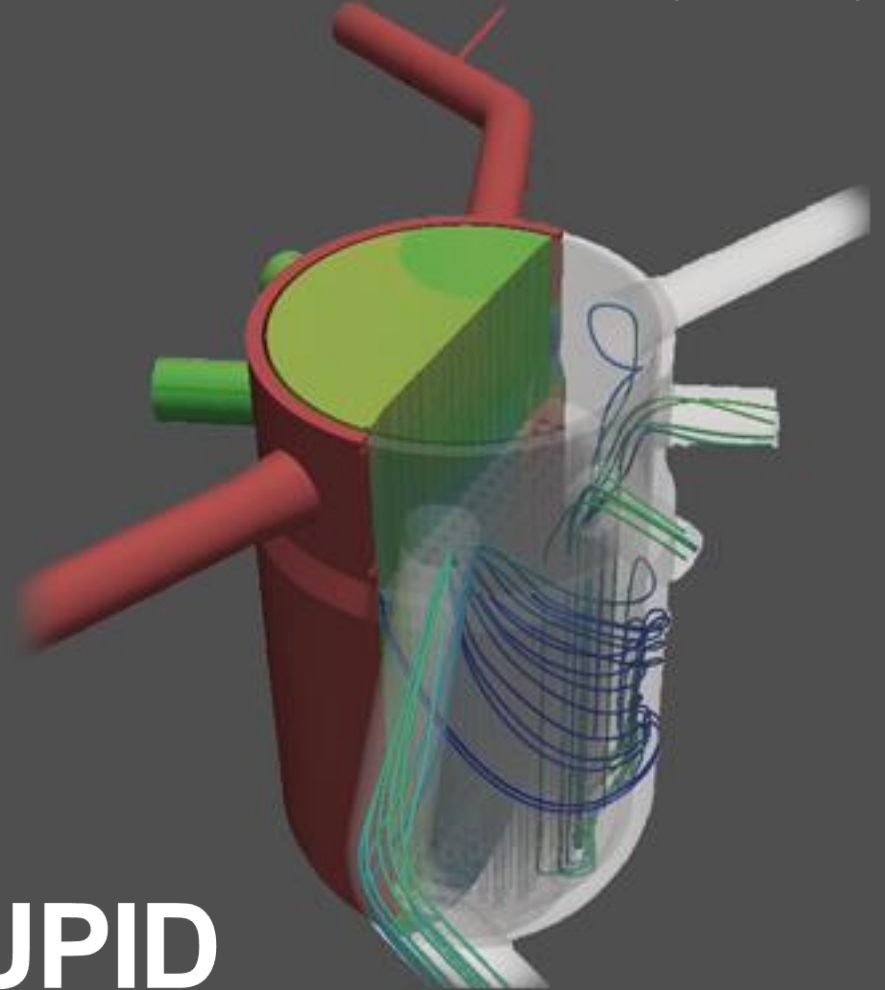


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01. Introduction to CUPID.....	1
02. Fast and accurate 2-phase flow solution scheme.....	25
03. Highly scalable iterative solver (Geometric multi-grid method for unstructured mesh).....	45
04. Unique multi-scale coupling method for a transient calculation.....	69
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06. Reactor vessel 3D mesh generation for safety analysis.....	132
07. Pin-wise full core safety analysis of OPR 1000.....	151



CUPID Workshop

Introduction to CUPID

Han Young Yoon
March 04, 2022

CUPID Workshop

CONTENTS

- ▶ 01 Main Features of CUPID
- ▶ 02 Numerical Models
- ▶ 03 V&V and QA Programs
- ▶ 04 Major Applications
- ▶ 05 CUPID User Group

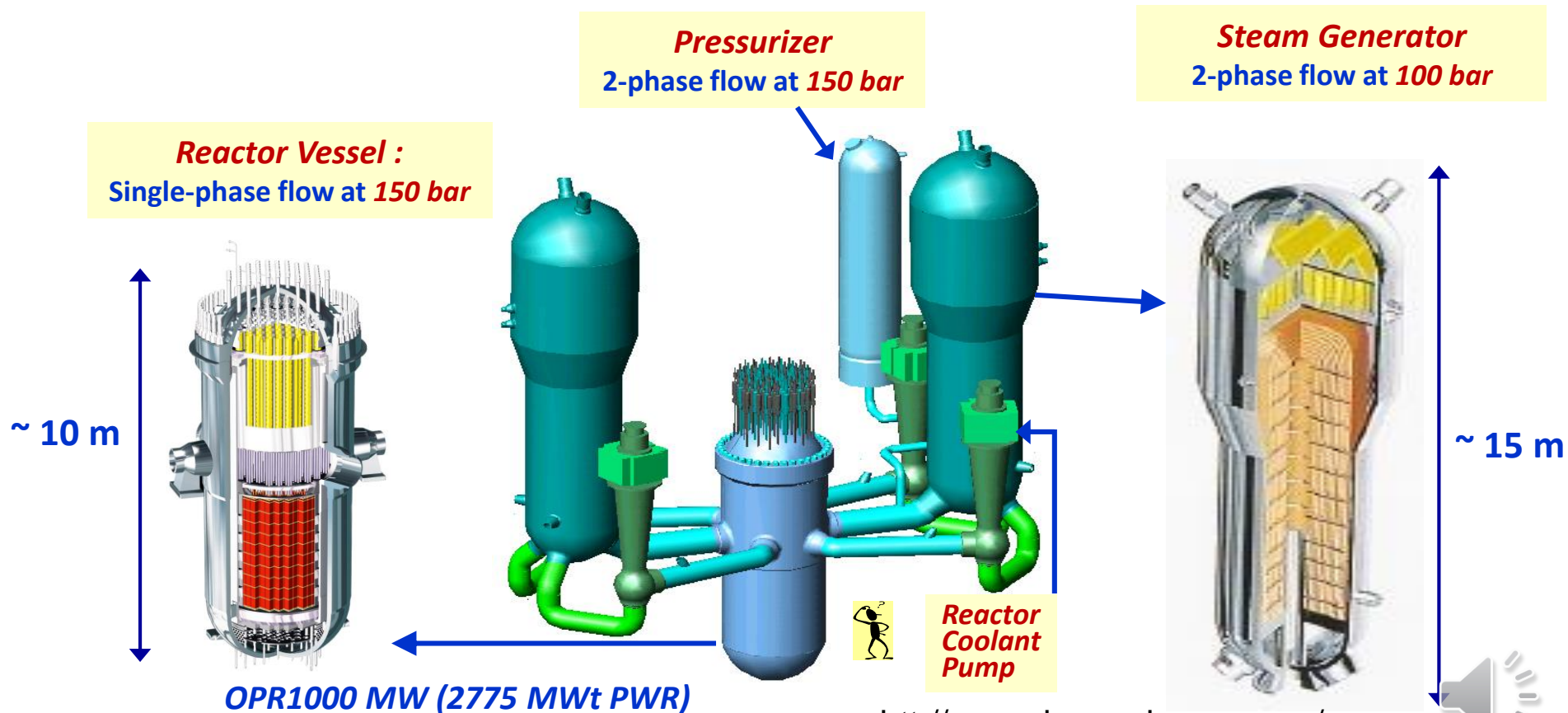
Main Features of CUPID

- Fast and Robust 3D 2-Phase Flow Solver
- Scalable Iterative Solver for a Large-scale Computing
- Multi-scale Simulation for a Fast Transient
- Multi-physics Simulation (TH/NK/FP)

TH: Thermal Hydraulics
NK: Neutron Kinetics
FP: Fuel Performance

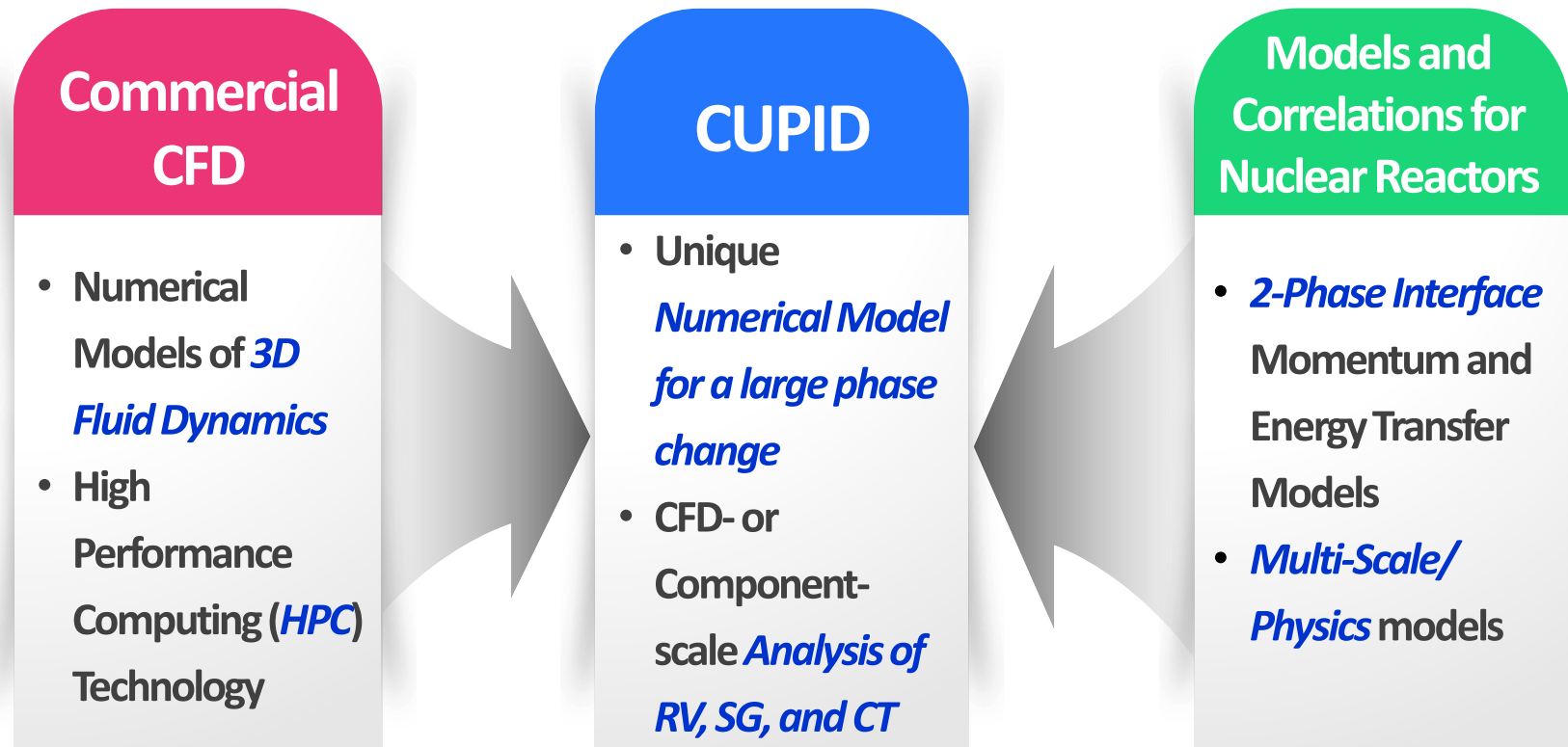
Fast and Robust 3D 2-Phase Flow Solver (1/2)

- » **Big and complicated** systems with transient **2-phase flows** (1~150 bar)
- » The **CUPID** code has been developed for **steady-state and transient analyses** of **single- and two-phase flows** in nuclear reactor in **component- or CFD-scale**



Fast and Robust 3D 2-Phase Flow Solver (2/2)

- » Commercial CFD mainly focuses on 3D fluid dynamics and *has limited applications for 2-phase flows especially when a large phase change is involved*



RV: Reactor Vessel, SG: Steam Generator, CT: Containment

Scalable Iterative Solver for a Large-scale Computing

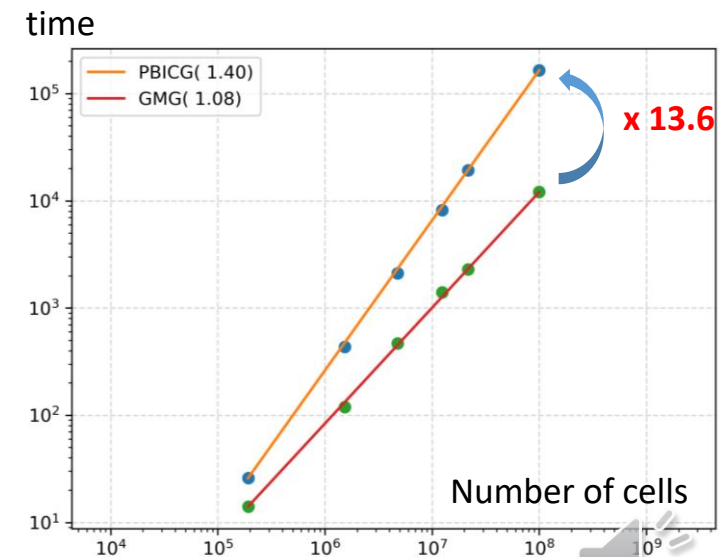
» The most time-consuming part in CUPID is the **“Pressure equation”** solving module

- The pressure equation takes more than **90%** of total computing time depending on the number of cells
- The Conjugate Gradient (**CG**) solver is **not scalable** and we need to develop a **new iterative solver** which is **scalable** w.r.t the number of cells

» Development of a **Geometric Multi-Grid (GMG)** solver for **unstructured mesh**

- **CG solver:** $\text{Time}_{\text{CG}} \propto N^{1.4}$
- **GMG solver:** $\text{Time}_{\text{GMG}} \propto N^{1.0}$
- The new GMG solver is **Easy to use** since the unstructured **coarse meshes** are **generated automatically**

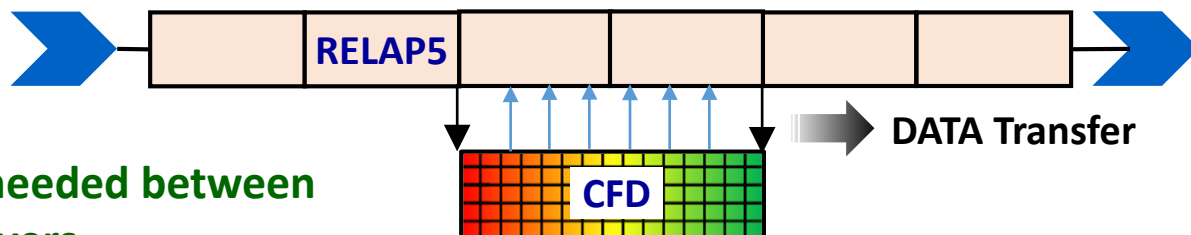
Number of Cells	time_pressure / time_total (%)
191,800	78.8
1,533,600	75.7
4,773,600	81.6
12,357,600	86.2
21,683,700	90.2
107,968,000	92.9



Multi-Scale Simulation for a Fast Transient

Domain Overlapping

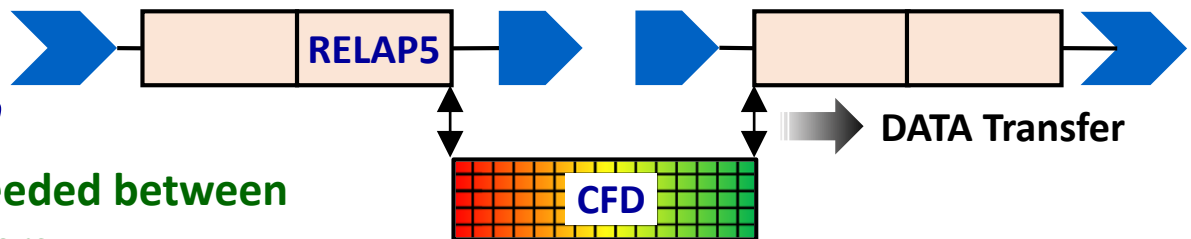
Data Transfer is needed between
Two separate solvers



Ex)
RELAP5/
CFX,
FLEUNT,
STAR-CCM+

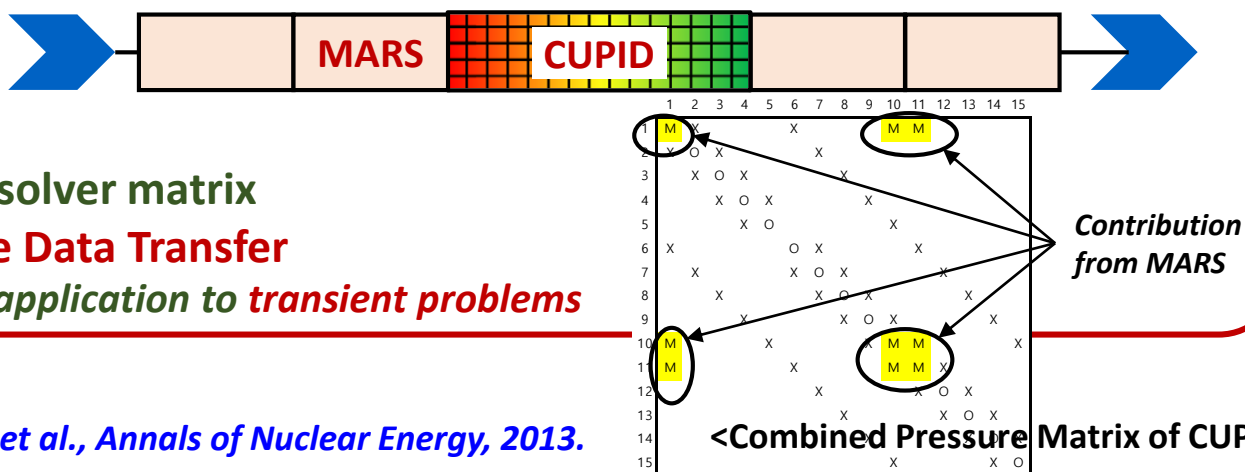
Domain Decomposition

Data Transfer is needed between
Two separate solvers



Single Domain

Single pressure solver matrix
: **No need for the Data Transfer**
→ *Versatile application to transient problems*

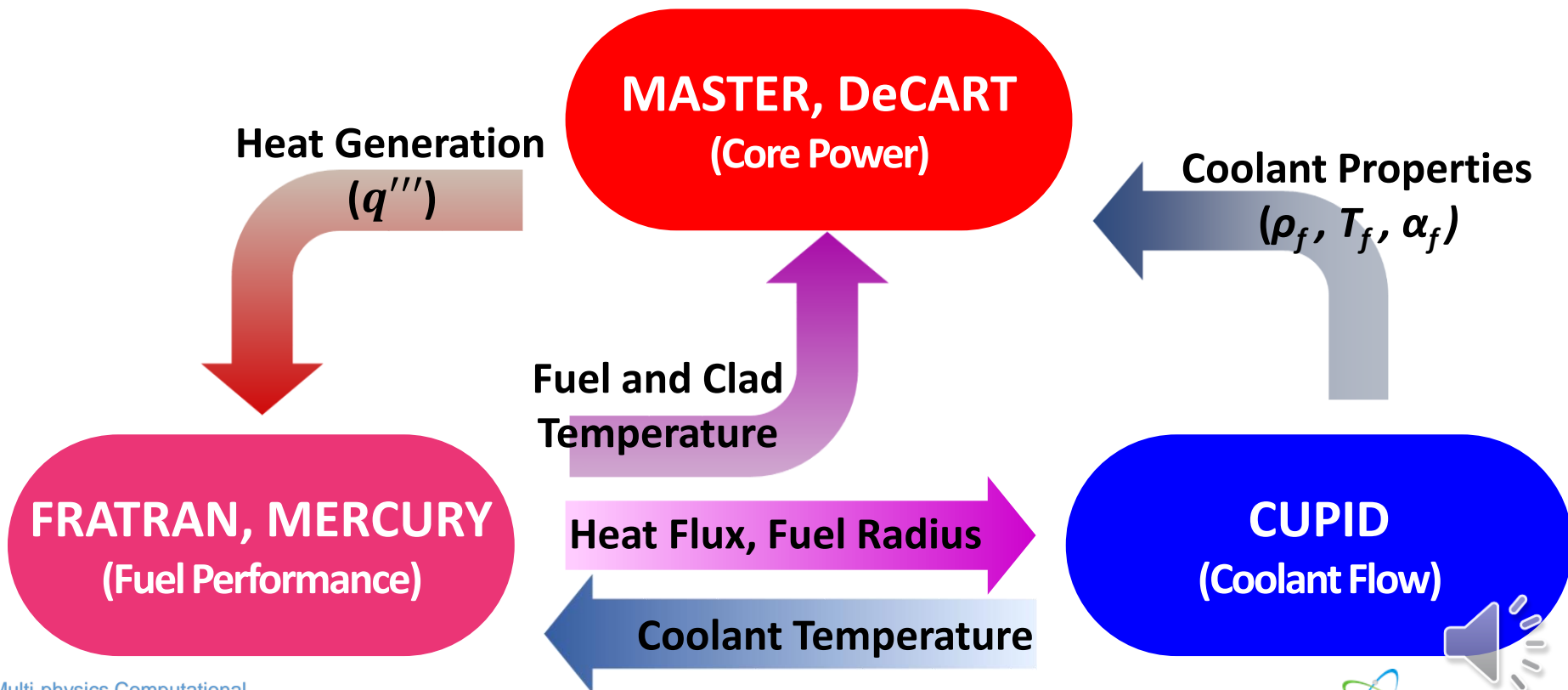


* I.K.Park et al., Annals of Nuclear Energy, 2013.

Multi-Physics Simulation (TH/NK/FP)

» Coupling of Multi-Physics Codes

- Neutron Kinetics Codes: *MASTER, DeCART*
- Thermal Hydraulics Code: *CUPID*
- Fuel Performance Codes: *FRAPTRAN, MERCURY*



Numerical Models

- Mathematical Models
- Parallel Computation
- Pre/Post Processors



Mathematical Models

Field Equations

- 3-Dimensional **2-Fluid & 3-Field** Mass, Mom., Eng. Equations
- Non-condensable Gas Equations (**He, H₂, N₂, Kr, Xe, Air, Ar, SF₆**)
- 3-Dimensional **Solid Conduction** Equation
- **Boron** Transport Equation
- Interfacial Area Transport Equation

Numerical Methods

- Finite Volume Method (**FVM**)
 - **Unstructured Mesh**
 - Semi-Implicit/**Fully-Implicit** Scheme
 - Pressure Solver: Bi-Conjugate Gradient (**BICG**), Multi-Grid (**MG**)
 - **Compressibility** is considered
- * H.Y.Yoon et al.,
Numerical Heat Transfer,
2016.

Physical Models

- CFD-Scale**
- Turbulence Model: **k-e, SST, LES**
 - **2-Phase Topology** Map,
 - **Drag, Lift Force, Interface Heat Transfer** Models
 - **Radiation Heat Transfer** Model

- Component-Scale**
- **Porous Medium** Model
 - 2-Phase Flow Regime
 - **Models and Correlations**
Package for the safety Analysis
 - **Sub-channel Model**

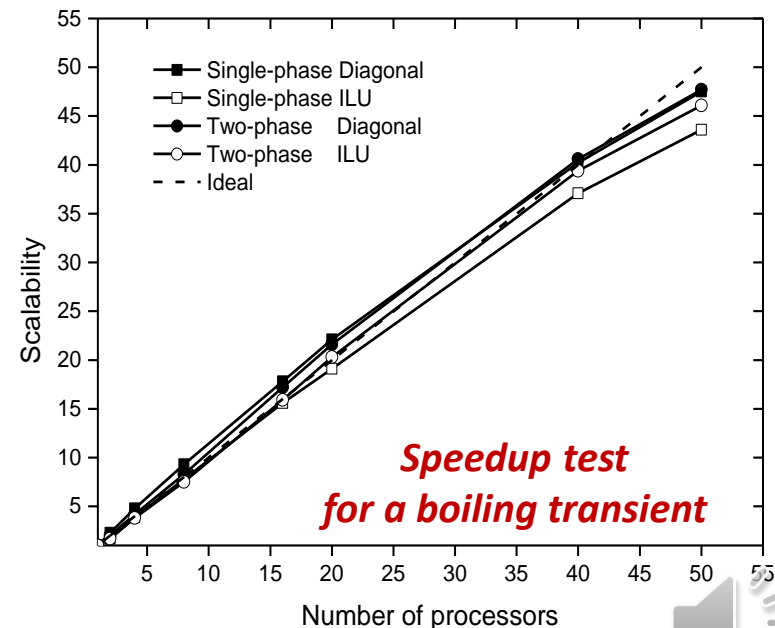
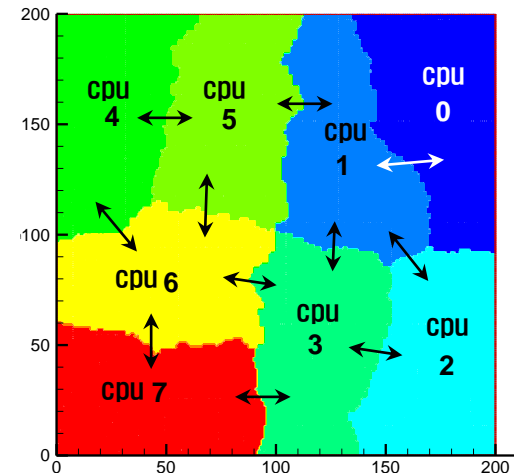
Parallel Computation

» Domain Decomposition

- Automatic domain decomposition using the **METIS Library**
- Manual decomposition

» **MPI functions** are used for the communication between different domains

» **Highly Scalable** parallel computing performance as the number of CPU increases



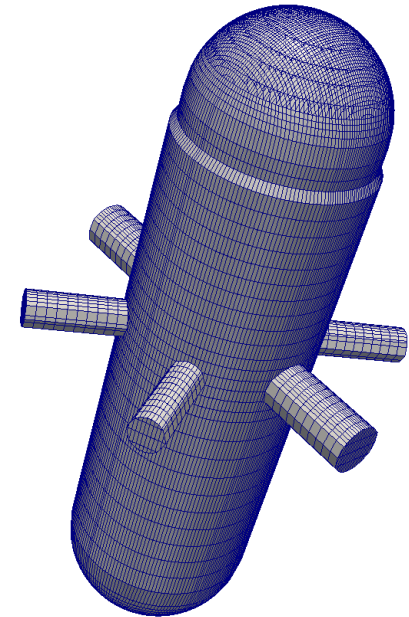
* J.R.Lee et al., *Journal of Mechanical Science and Technology*, 2016.

Pre/Post Processors

» Mesh Generation

- Mesh Input Data Structure:
OpenFOAM Format
- CFD-Scale Mesh Generation:
SALOME (EDF)
- *Reactor Vessel Mesh* Generation
at a Sub-channel Scale
 - *RVMesh-3D*

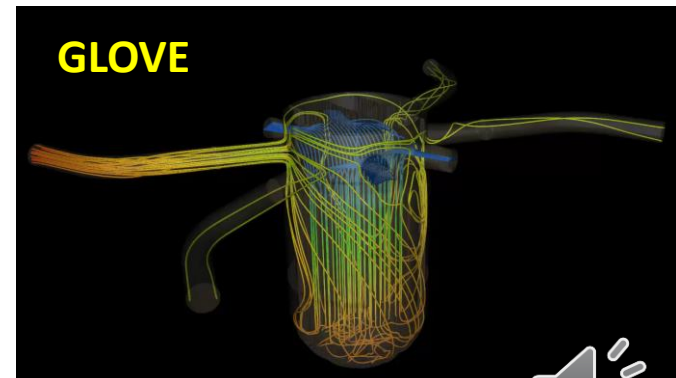
RVMesh-3D



» Post Processing

- Open Source Program: *Paraview*
- Parallel Post Processing:
GLOVE (KISTI)

GLOVE



V&V and QA Programs

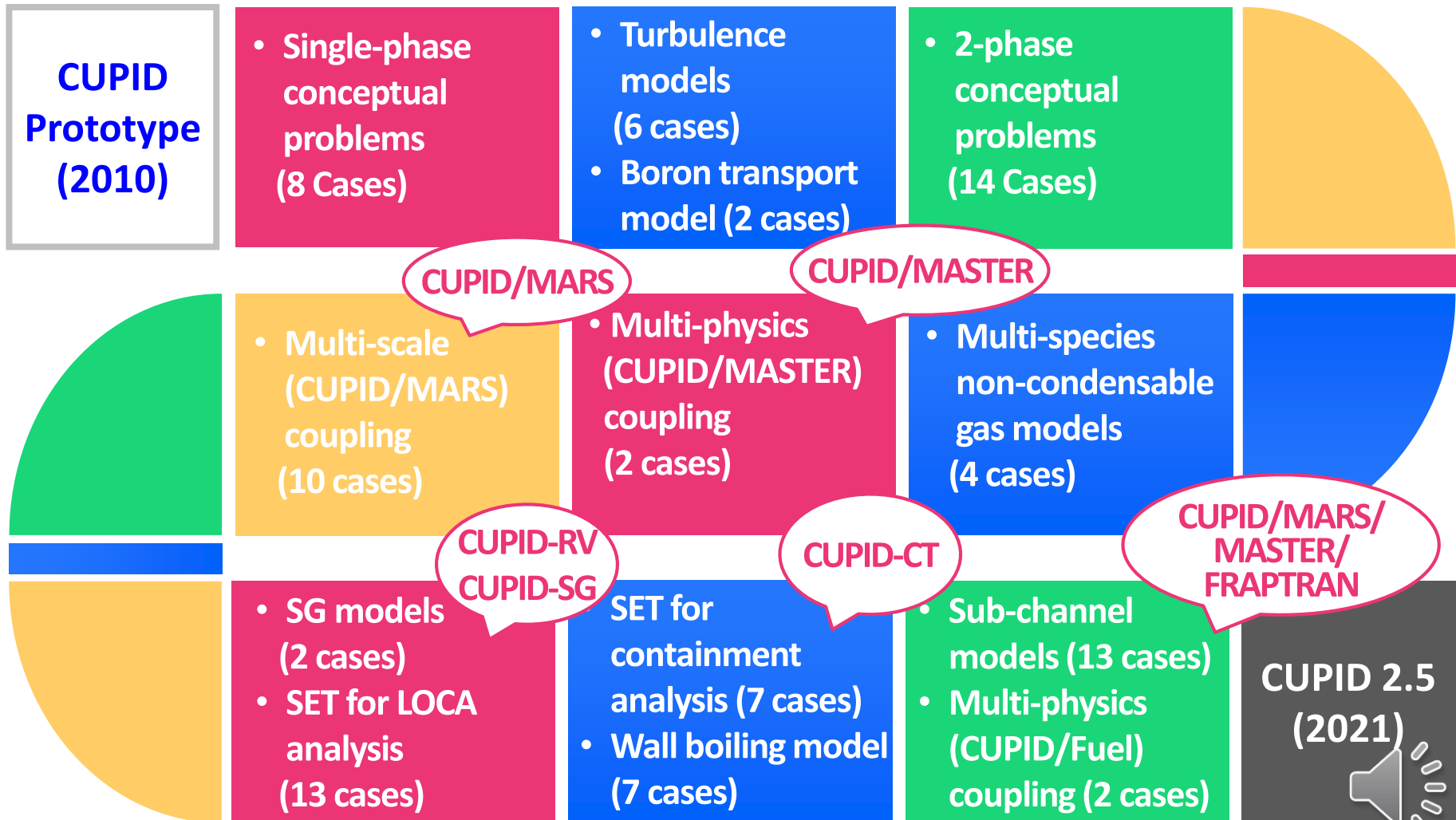
3

- V&V Program
- QA Program



Verifications & Validations

» Extensive *Verification and Validation Consisting of 90 Test Problems*



Quality Assurance

» ASME NQA-1 (KEPIC-QAP)

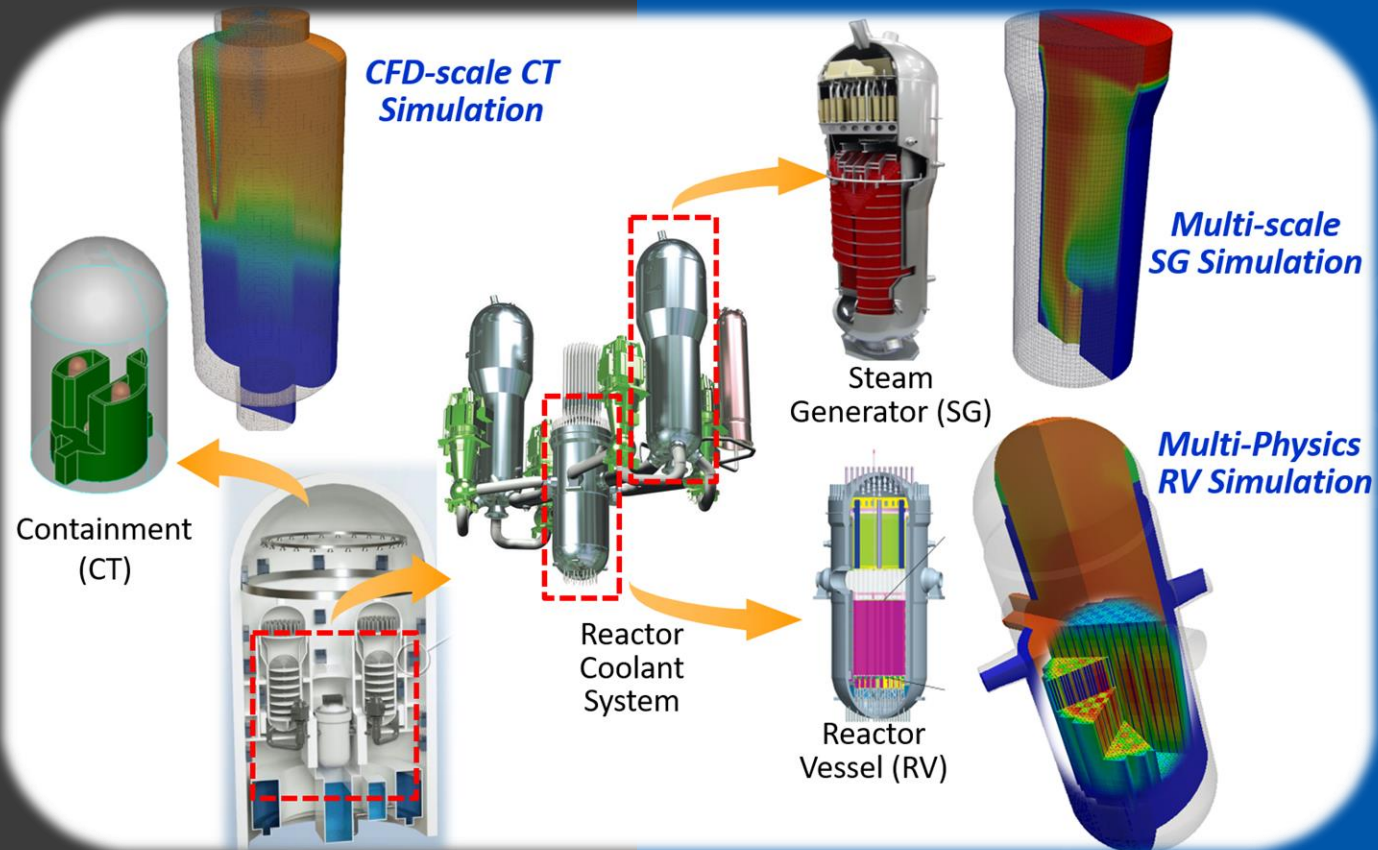
» Documentation for QA

» CUPID Code Version Control System

- **SVN (*Subversion*)** server/client type system
 - Centralized Version Control System (CVCS)
- Store CUPID code and related documents to SVN server (Repository)
- **Download** CUPID from SVN server (Checkout, Updated)
- **Upload** newly developed coding to SVN server (Commit)
 - **V&V Calculation** → V&V brief per **3 month**, SVVR **per 1 year**
- All records are stored, traced back freely (**Traceback**)

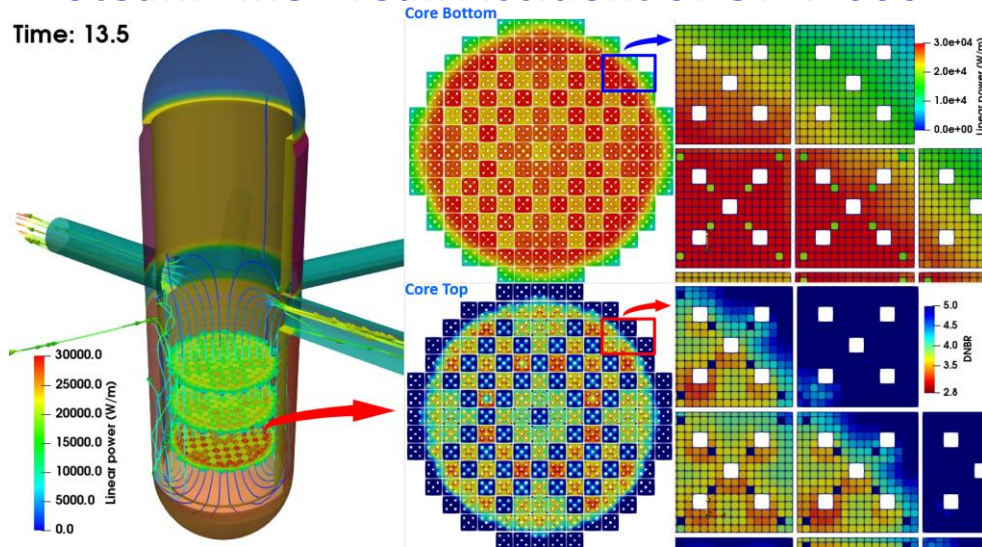
Major Applications

- Reactor Vessel
- Steam Generator
- Containment
- Special Components (SIT, PAFS)



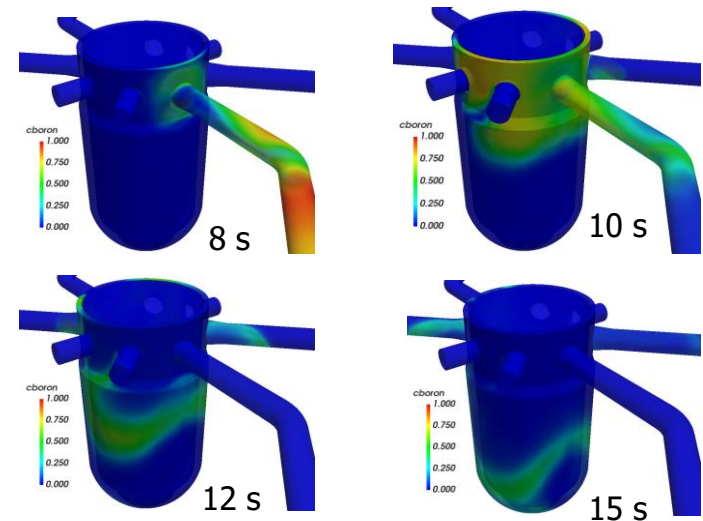
Reactor Vessel

» Full Core Pin-wise Simulation of the Steam Line Break Accident of OPR1000



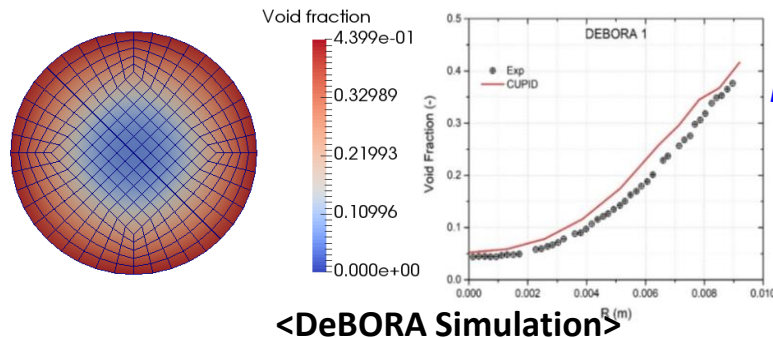
* H.Y.Yoon et al., Nuclear Science and Engineering, 2020.

» Simulation of the *ROCOM (HZDR) flow mixing experiment* (IAEA/CRP)

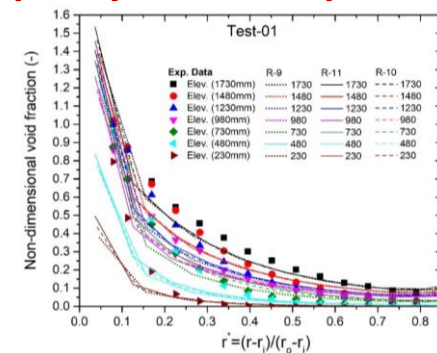


* Y.J.Cho et al., Nuclear Engineering and Design, 2019.

» Validation of wall boiling models against *DeBORA (CEA), F-SUBO(KAERI)*



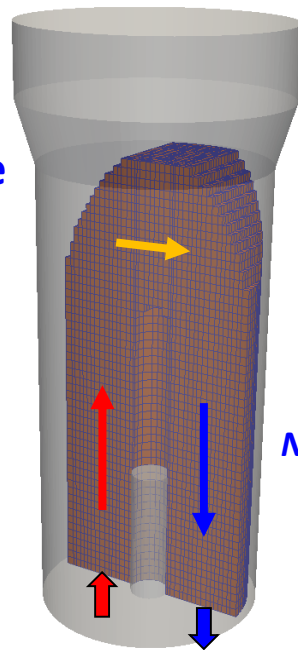
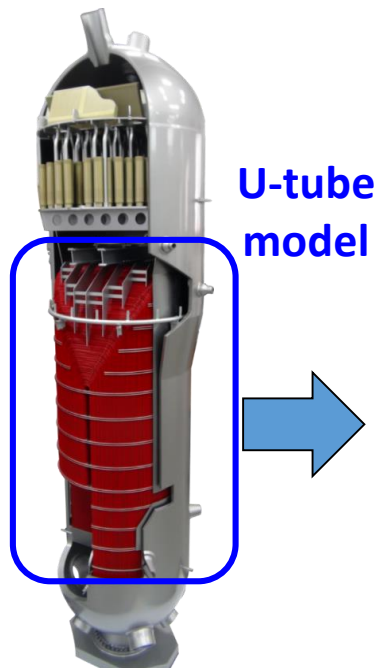
* Y. Alatrash et al., Nuclear Engineering and Technology, 2021.



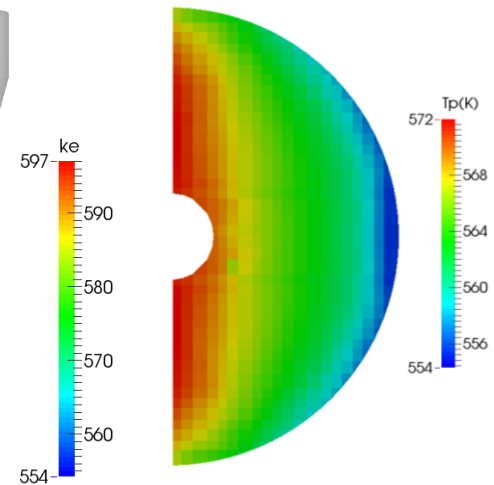
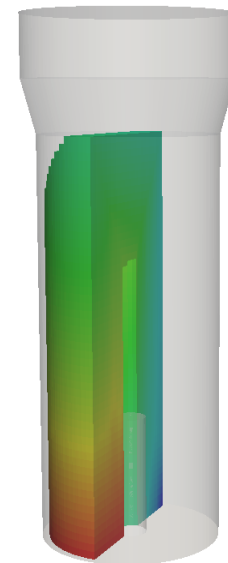
<F-SUBO Simulation>

Steam Generator

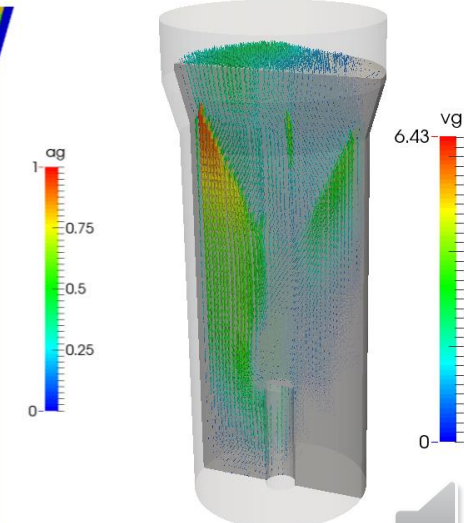
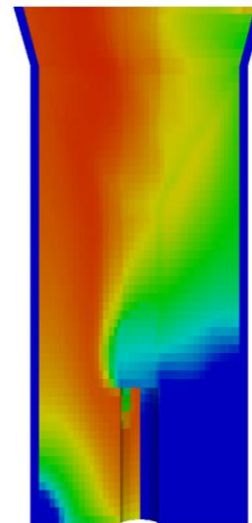
- » PWR SG analysis code (*CUPID-SG*) has been developed based on the CUPID code
- » All regions for *riser, downcomer, separator, and steam dome* are modeled
- » A *U-tube model* has been developed where all U-tubes are grouped and connected with the secondary fluid cells



* H.Y.Yoon et al.,
NURETH-17, 2017.



<Primary Coolant Temperature>



<Secondary Side Void Fraction and Velocity Vectors>

Containment

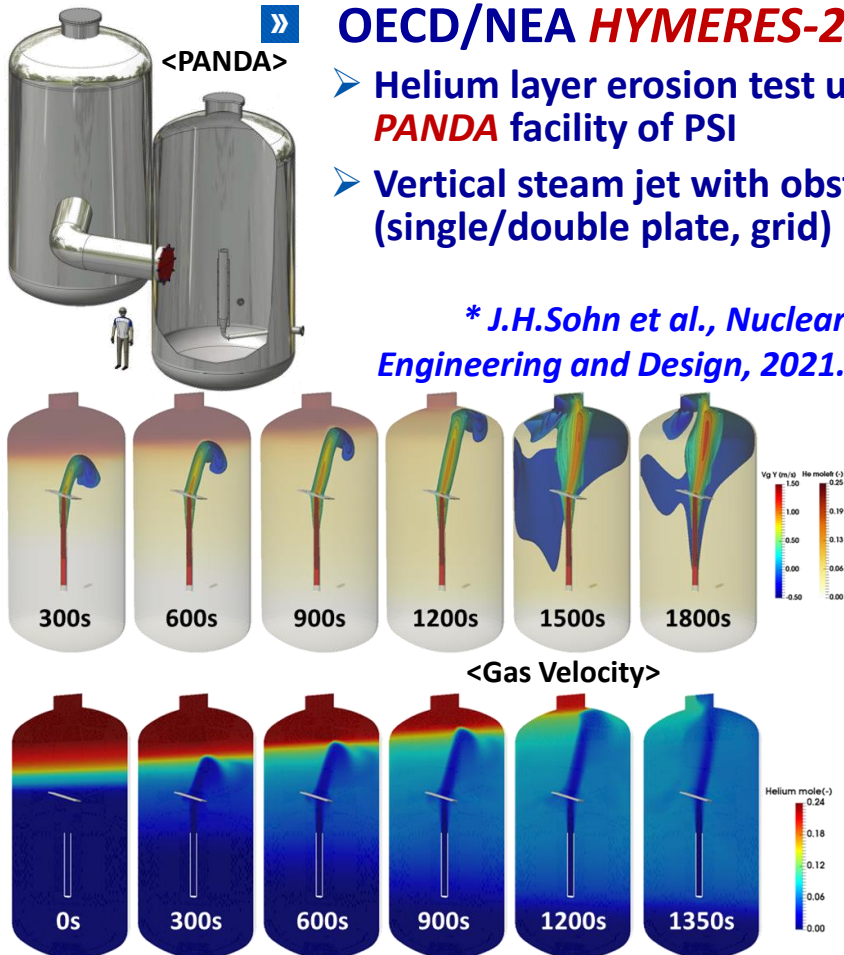
» Containment Analysis Models

- **Non-condensable gas, Condensation** models
- **Radiation** model

» OECD/NEA **HYMERES-2**

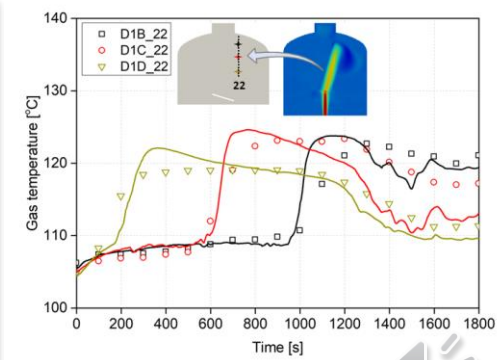
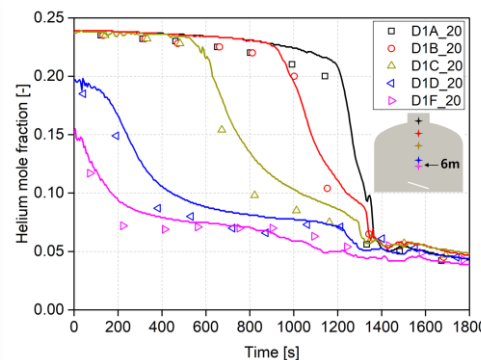
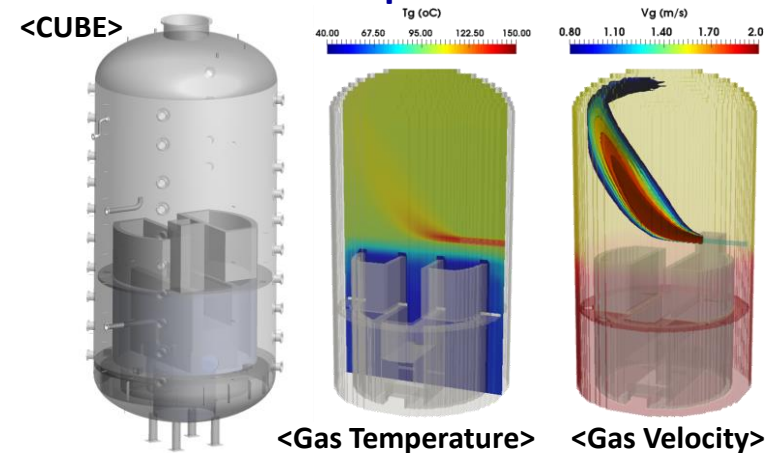
- Helium layer erosion test using **PANDA** facility of PSI
- Vertical steam jet with obstructions (single/double plate, grid)

** J.H.Sohn et al., Nuclear Engineering and Design, 2021.*

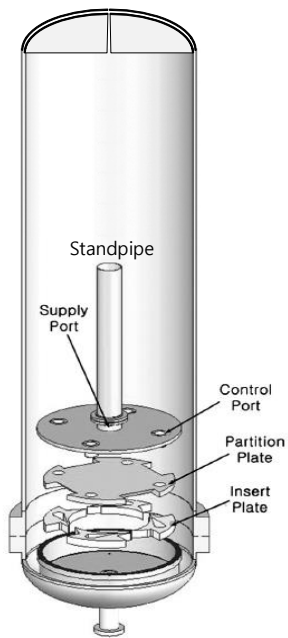


» ATLAS-CUBE (KAERI)

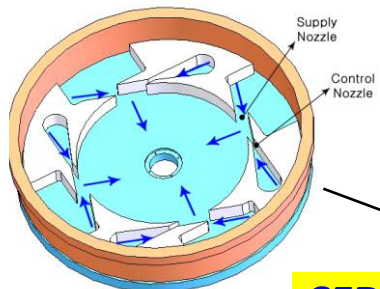
- Steam injection test using **CUBE** facility connected with **ALTAS**
- Thermal stratification / Effect of structures as a passive heat sink



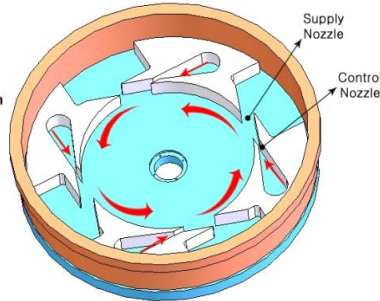
Special Component – Advanced SIT (APR1400)



(a) The internal structure



(b) High flow mode

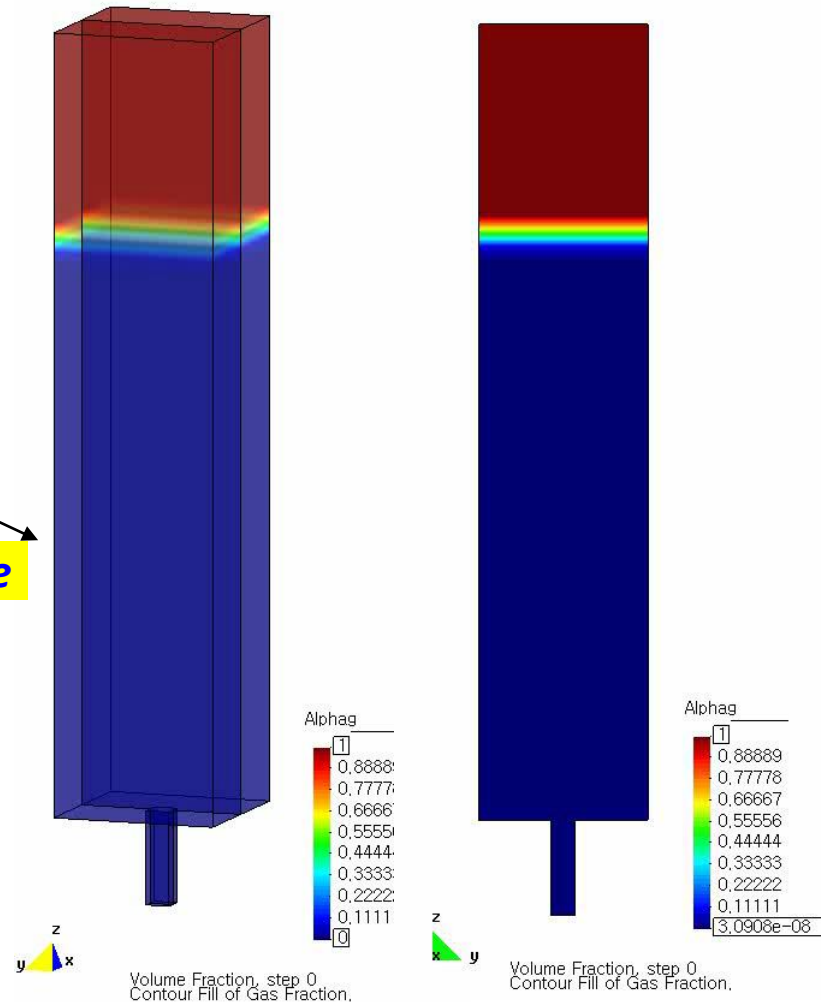
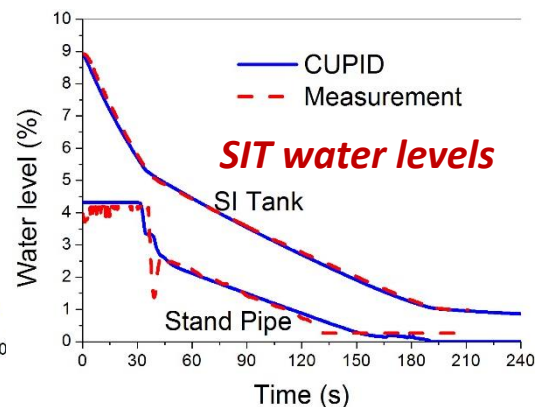
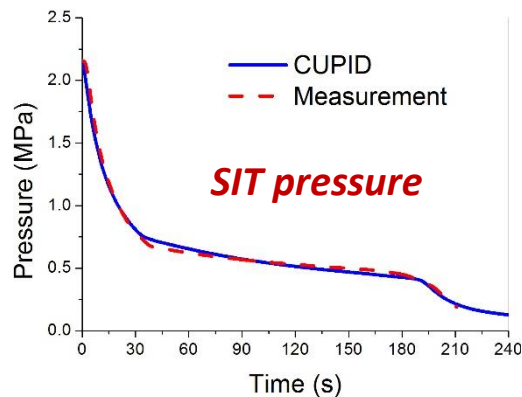


(c) Low flow mode

CFD-scale

Component-scale

Comparison to the VAPER experiment (KAERI)



* H.Y.Yoon et al., *Annals of Nuclear Energy*, 2013.

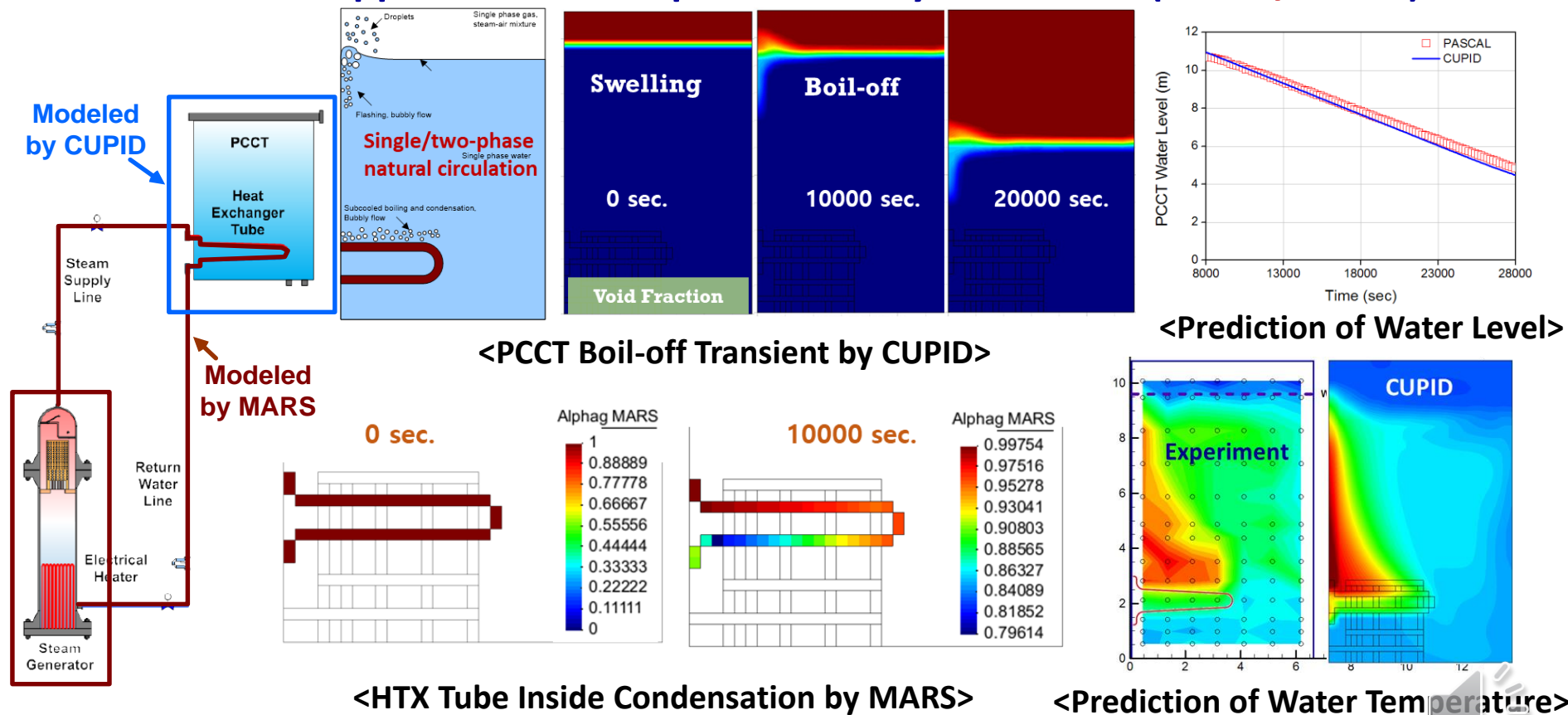
Special Component – PAFS (APR+)

» PAFS (Passive Auxiliary Feedwater System)

- Removes residual heat by a *natural circulation loop*
- Validation Experiment: **PASCAL (KAERI)**

* H.K.Cho et al., *Nuclear Engineering and Design*, 2014.

» Simultaneous application of component and system scales (**CUPID/MARS**)



CUPID User Group

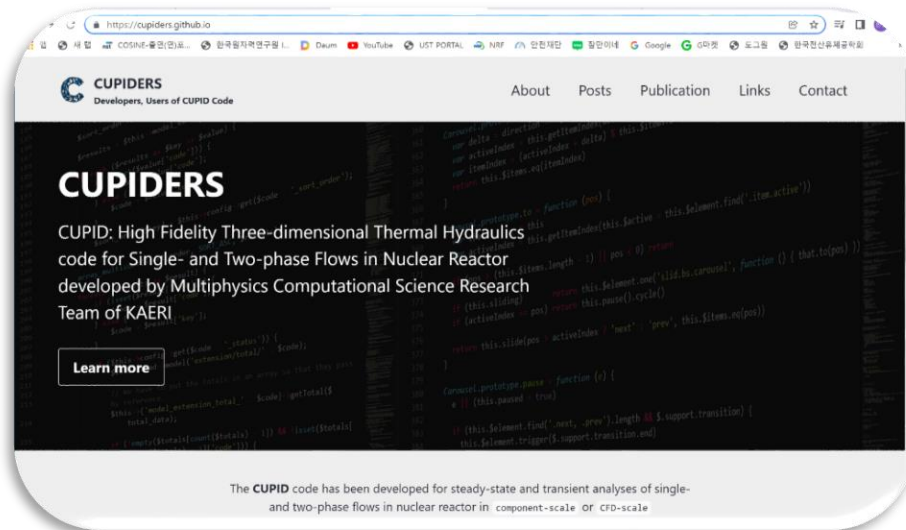
5



CUPID User Group

<http://cupiders.github.io>

Domestic Univ. & Research Inst.



Industries



User Agreement

User Contract

User Agreement

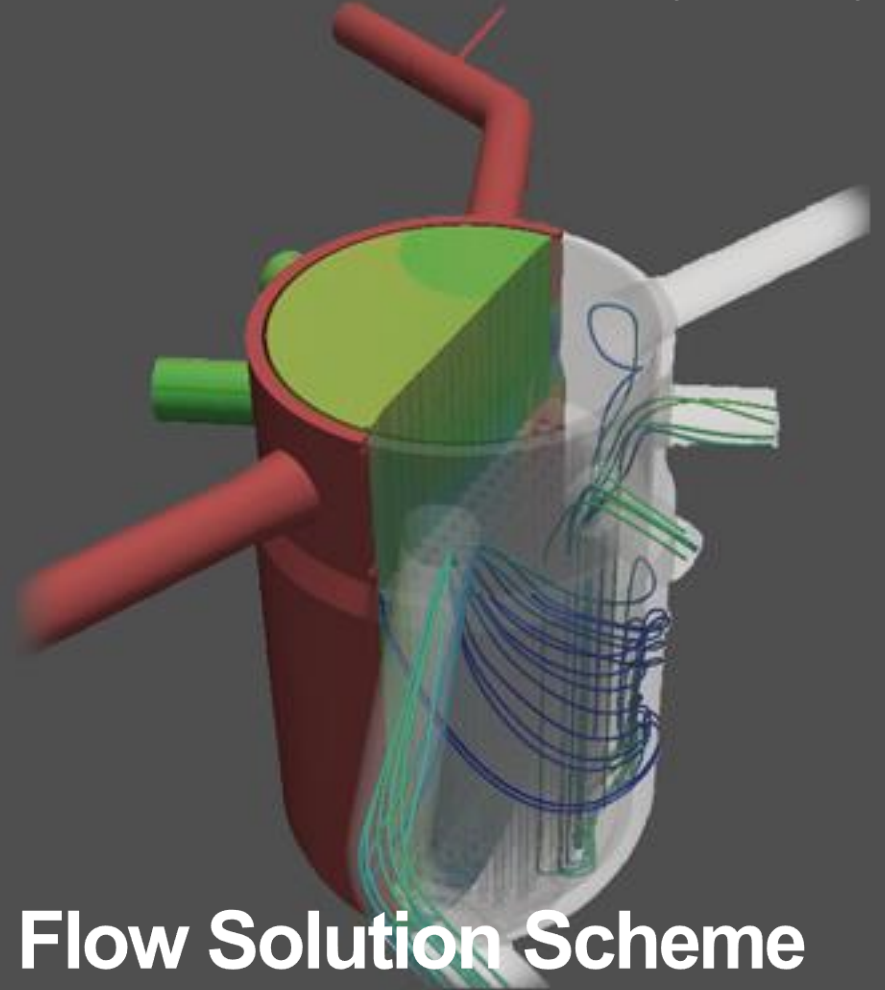
Foreign Univ.



THANK YOU

hyyoon@kaeri.re.kr





CUPID Workshop

Fast and Accurate 2-phase Flow Solution Scheme

Han Young Yoon
March 04, 2022

CUPID Workshop

CONTENTS

- ▶ 01 Development Strategy
- ▶ 02 Discretization Scheme
- ▶ 03 Solution Schemes
- ▶ 04 Verification & Validation
- ▶ 05 Summary

Development Strategy

1

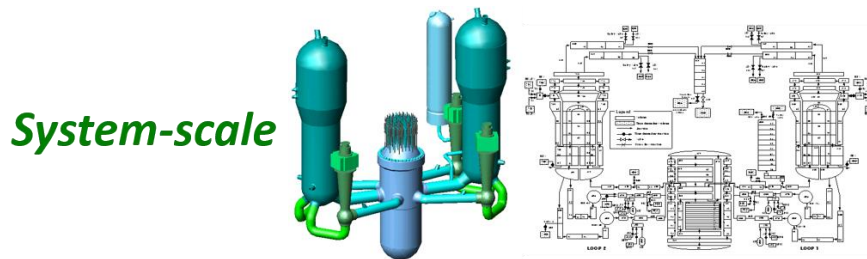
- Requirement for the Development
- Review of the Previous Methods



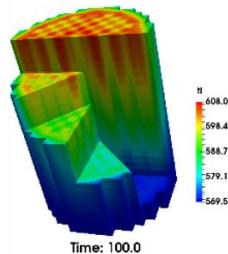
Requirement for the Development

» Analysis Scale

- CFD-Porous (Sub-channel), CFD-RANS, CFD-LES



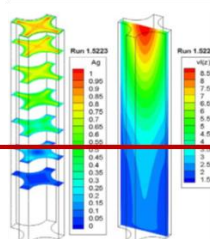
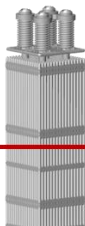
*CFD-Porous
(subchannel-scale)*



CFD-RANS

CFD-LES

CFD-DNS



» Major Applications

- Nuclear Reactor Safety and Performance Analysis
 - *2-phase 3D TH model* to deal with large phase change (150bar ~ 1bar)
 - *High-resolution 1-phase 3D flow model* with relevant turbulence models
- 3D TH Models for
 - *Reactor Vessel*
 - *Steam Generator*
 - *Containment*

Review of the Previous Methods

Analysis Code	Solution Methods	Limitations for Nuclear Reactor 3D Analysis	Adopted Features for CUPID
System Analysis Code: RELAP5(NRC), MARS(KAERI), SPACE(KHNP)	<ul style="list-style-type: none"> FDM for staggered mesh Semi-implicit Scheme <i>Pressure equation with phase change terms</i> <i>2-phase models and correlations</i> 	<ul style="list-style-type: none"> Staggered mesh is <i>hard to apply for a 3D geometry</i> Semi-implicit scheme is <i>not efficient for a large calculation</i> 	<ul style="list-style-type: none"> Pressure equation with phase change terms 2-phase models and correlations
CFD Code: FLUENT, STAR-CCM+, OpenFOAM	<ul style="list-style-type: none"> <i>FVM for unstructured mesh</i> <i>Implicit Scheme</i> Incompressible pressure equation <i>Turbulence Models</i> 	<ul style="list-style-type: none"> <i>Limited application to 2-phase flows with large phase change</i> 	<ul style="list-style-type: none"> FVM for unstructured mesh Implicit Scheme Turbulence Models



Discretization Scheme

- Finite Volume Method with Unstructured Mesh



Finite Volume Method with Unstructured Mesh

» Useful for **Complicated Geometries**

» Used in most of **current CFD codes**

» Limitations

➤ **Good mesh quality** is important for an accurate calculation

➤ Difficult to apply a **higher-order scheme**

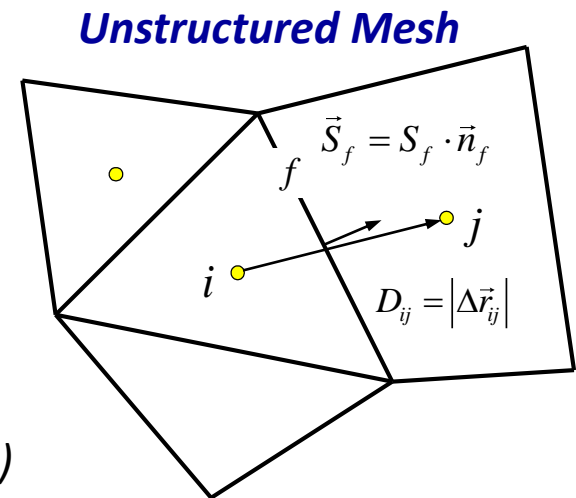
Gradient
$$\int_V \nabla \phi dV = \int_S \phi d\vec{S} \approx \sum_f \phi_f \vec{S}_f$$

Diffusion
$$\int_V \nabla^2 \phi dV = \int_S \nabla \phi \cdot d\vec{S} \approx \sum_f \nabla \phi_f \cdot \vec{S}_f$$

Convection
$$\int_V \nabla \cdot (\phi \vec{u}) dV = \int_S \phi \vec{u} \cdot d\vec{S} \approx \sum_f \phi_{up} \Psi_f$$

where $\Psi_f = \{ \xi \cdot \vec{u}_i + (1 - \xi) \cdot \vec{u}_j \} \cdot \vec{S}_f$ (Volume flux)

$$\phi_{up} = \begin{cases} \phi_i, & \Psi_f \geq 0 \\ \phi_j, & \Psi_f < 0 \end{cases}$$



Solution Schemes

CUPID provides 3 different solution schemes

- Energy Coupled Method (Semi-implicit)
- Energy Decoupled Method (Semi-implicit)
- Energy Decoupled Method (Fully-implicit)



Energy Coupled Method (Semi-implicit)

- » **Mass and Energy Equations** are used for establishing the **pressure equation**
- » Used in the **system analysis code** such as RELAP5
- » **Solution Procedure**

1. Momentum Eq.

2. Linearization of Scalar

3. Pressure Correction

4. Scalar Update

$$\vec{u}_{k,i}^* = \vec{\gamma}_{k,i} - \beta_{k,i} \nabla P_i^n \quad \vec{u}_{k,i}^{n+1} = \vec{u}_{k,i}^* - \beta_{k,i} \nabla \delta P_i$$

$$\sum_f \Psi_{k,f}^{n+1} = \sum_f \left[\Psi_{k,f}^* - \beta_{k,f} \frac{S_f}{|d\vec{r}_f|} (\delta P_j - \delta P_i) \right]$$

$$\delta \mathbf{x}_i = \mathbf{A}_i^{-1} \mathbf{s}_i + \sum_f \mathbf{A}_i^{-1} \sum_k \mathbf{c}_{k,f} \Psi_{k,f}^{n+1}$$

$$\delta \mathbf{x}_i = (\delta e_g, \delta e_l, \delta \alpha_g, \delta \alpha_l, \delta \alpha_d, \delta P)_i$$

$$\left(1 + \sum_f C_f \right) \delta P_i + \sum_f C_f \delta P_j = B_i$$

$$P_i^{n+1} = P_i^n + \delta P_i$$

$$\vec{u}_{k,i}^{n+1} = \vec{u}_{k,i}^* + \beta_{f,i} \nabla \delta P_i$$

$$\mathbf{x}_i^{n+1} = \mathbf{x}_i^n + \delta \mathbf{x}_i$$

Energy Decoupled Method (Semi-implicit)

- » **Mass eq.** is used for establishing the **pressure eq.**
- » Similar to that used in **the CFD code** but different in the **implicit calculation of the phase change term**

» Solution Procedure

1. Momentum Eq.



2. Combined Mass Eq.



3. Pressure Correction



4. Linearization & Update Scalar

$$\sum_f \Psi_{k,f}^{n+1} = \sum_f \left[\Psi_{k,f}^* - \beta_{k,f} \frac{S_f}{|d\vec{r}_f|} (\delta P_j - \delta P_i) \right]$$

$$\begin{aligned} \sum_k \left[\frac{\nabla \cdot (\alpha_k \rho_k \vec{u}_k)}{\rho_k} \right] &= \Gamma_v \left(\frac{1}{\rho_g} - \frac{1}{\rho_l} \right) - \sum_k \left(\frac{\alpha_k}{\rho_k} \frac{\partial \rho_k}{\partial t} \right) \\ \frac{1}{V_i} \sum_k \frac{(\alpha_k \rho_k)_f}{\rho_{k,i}} \Psi_{k,f}^{n+1} &= \Gamma_{v,i}^{n+1} \left(\frac{1}{\rho_{g,i}} - \frac{1}{\rho_{l,i}} \right) \\ &- \sum_k \left[\frac{\alpha_k}{\rho_k} \delta t \left(\frac{\partial \rho_k}{\partial P} \delta P + \frac{\partial \rho_k}{\partial e_k} \delta e_k + \frac{\partial \rho_k}{\partial X_n} \delta X_n \right) \right] \end{aligned}$$

Phase change term should
be treated implicitly

Values at previous
the time step

Energy Decoupled Method (Fully-implicit) (1/2)

» **Convection and Diffusion** terms are calculated *implicitly* in the “**Fully-implicit Scheme**”

	Semi-implicit	Fully-implicit
Energy Coupled	O	X
Energy Decoupled	O	O

» **Momentum Equation**

Implicit terms

Semi-implicit	Fully-implicit
$\alpha_g \rho_g \frac{\vec{u}_g^* - \vec{u}_g^n}{\delta t} + \nabla \cdot (\alpha_g \rho_g \vec{u}_g \vec{u}_g)^n - \vec{u}_g \nabla \cdot (\alpha_g \rho_g \vec{u}_g)^n$ $= -\alpha_g \nabla P_i^n + \nabla \cdot (\alpha_g \mu_g \nabla \vec{u}_g)^n + C_d (\vec{u}_l^* - \vec{u}_g^*) + SRC_g^n$ <p style="text-align: center;">↓ Interfacial friction</p>	<p>① Phase link step</p> $\alpha_g \rho_g \frac{\vec{u}_g^* - \vec{u}_g^n}{\delta t} = -\alpha_g \nabla P_i^n + C_d (\vec{u}_l^* - \vec{u}_g^*) + SRC_g^n$ <p>② Space link step</p> $\alpha_g \rho_g \frac{\vec{u}_g^{**} - \vec{u}_g^*}{\delta t} + \nabla \cdot (\alpha_g \rho_g \vec{u}_g^{**} \vec{u}_g^n) - \vec{u}_g^{**} \nabla \cdot (\alpha_g \rho_g \vec{u}_g^n)^n$ $= \nabla \cdot (\alpha_g \mu_g \nabla \vec{u}_g^{**})$ <p style="text-align: center;">Convection Diffusion</p>

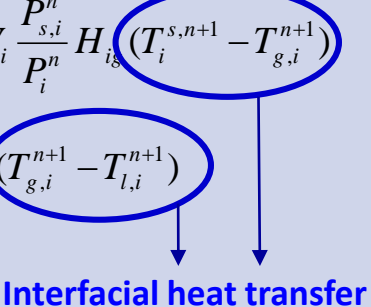
Energy Decoupled Method (Fully-implicit) (2/2)

Implicit
terms

» Energy Equation (ex. Vapor Energy)

Semi-implicit


$$\begin{aligned}
 & V_i \delta t^{-1} \alpha_{g,i}^n \rho_{g,i}^n (e_{g,i}^{n+1} - e_{g,i}^n) + \\
 & \sum_f \left[(\alpha_g \rho_g e_g)_f^n - e_{g,i}^n (\alpha_g \rho_g)_f^n \right] \Psi_{g,f}^{n+1} = \\
 & + V_i \delta t^{-1} \frac{\alpha_{g,i}^n P_i^n}{\rho_{g,i}^n} \delta \rho_{g,i} + \\
 & \frac{P_i^n}{\rho_{g,i}^n} \sum_f \left[(\alpha_g \rho_g)_f^n - \rho_{g,i}^n \alpha_{g,f}^n \right] \Psi_{g,f}^{n+1} \\
 & + \sum_f (\alpha_g \vec{q}_g)_f S_f + V_i \frac{P_{s,i}^n}{P_i^n} H_{ig} (T_i^{s,n+1} - T_{g,i}^{n+1}) \\
 & - V_i \left(\frac{P_i^n - P_{s,i}^n}{P_i^n} \right) H_{gf} (T_{g,i}^{n+1} - T_{l,i}^{n+1})
 \end{aligned}$$



Fully-implicit

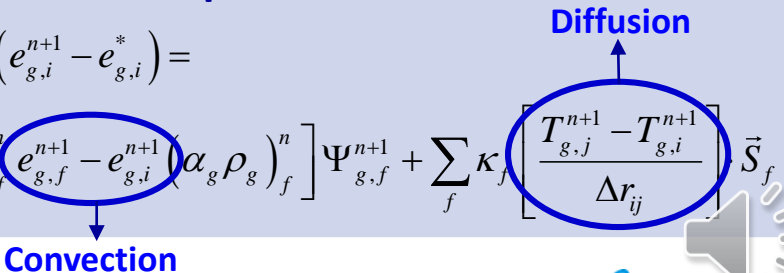
① Phase link step

$$\begin{aligned}
 & V_i \delta t^{-1} \alpha_{g,i}^n \rho_{g,i}^n (e_{g,i}^* - e_{g,i}^n) = \\
 & + V_i \delta t^{-1} \frac{\alpha_{g,i}^n P_i^n}{\rho_{g,i}^n} \delta \rho_{g,i} + \frac{P_i^n}{\rho_{g,i}^n} \sum_f \left[(\alpha_g \rho_g)_f^n - \rho_{g,i}^n \alpha_{g,f}^n \right] \Psi_{g,f}^{n+1} \\
 & + \sum_f (\alpha_g \vec{q}_g)_f S_f + V_i \frac{P_{s,i}^n}{P_i^n} H_{ig} (T_i^{s,*} - T_{g,i}^*) \\
 & - V_i \left(\frac{P_i^n - P_{s,i}^n}{P_i^n} \right) H_{gf} (T_{g,i}^* - T_{l,i}^*)
 \end{aligned}$$



② Space link step

$$\begin{aligned}
 & V_i \delta t^{-1} \alpha_{g,i}^n \rho_{g,i}^n (e_{g,i}^{n+1} - e_{g,i}^*) = \\
 & - \sum_f \left[(\alpha_g \rho_g)_f^n e_{g,f}^{n+1} - e_{g,i}^{n+1} (\alpha_g \rho_g)_f^n \right] \Psi_{g,f}^{n+1} + \sum_f \kappa_f \left[\frac{T_{g,j}^{n+1} - T_{g,i}^{n+1}}{\Delta r_{ij}} \right] \vec{S}_f
 \end{aligned}$$



Verification & Validation

4

- Verification of Different Solution Scheme
- Validation for the Reflood Test Problems

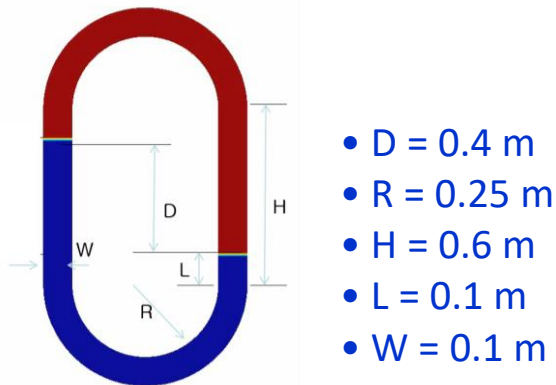


Verification of Different Solution Schemes

» **3 different schemes are compared** using the Verification and Validation matrix consisting of **90 test cases**.

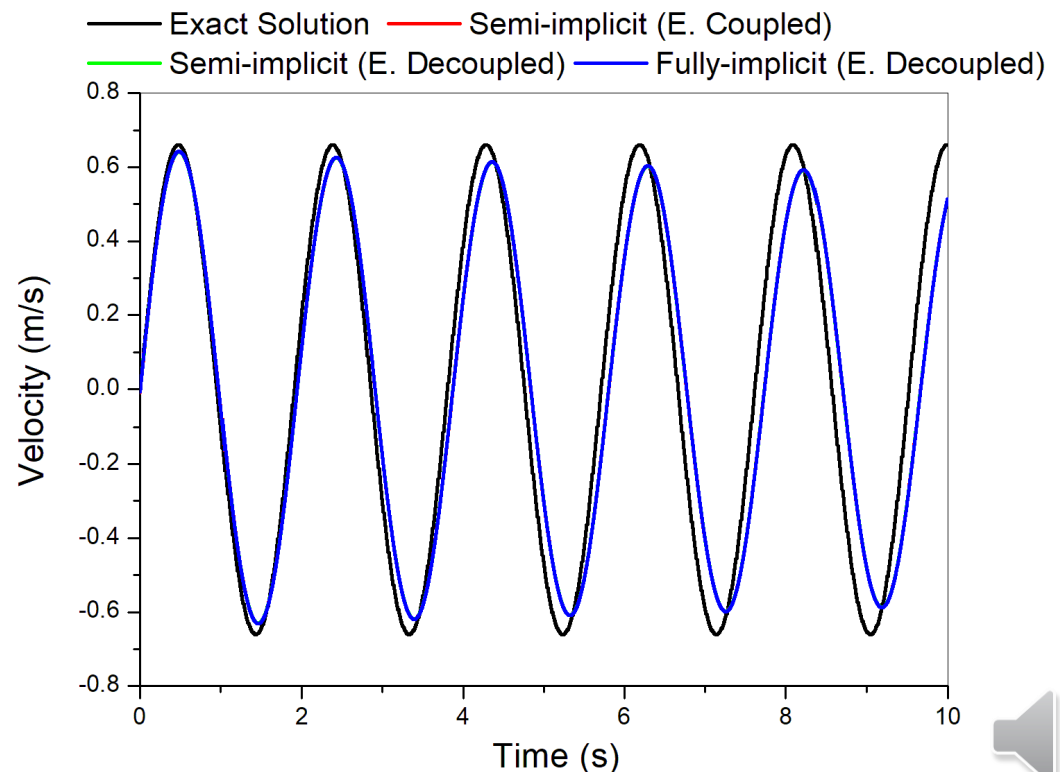
» Gravity-driven Flow Oscillations

➤ 3 solution schemes show the same result



Liquid velocity at the bottom of the channel

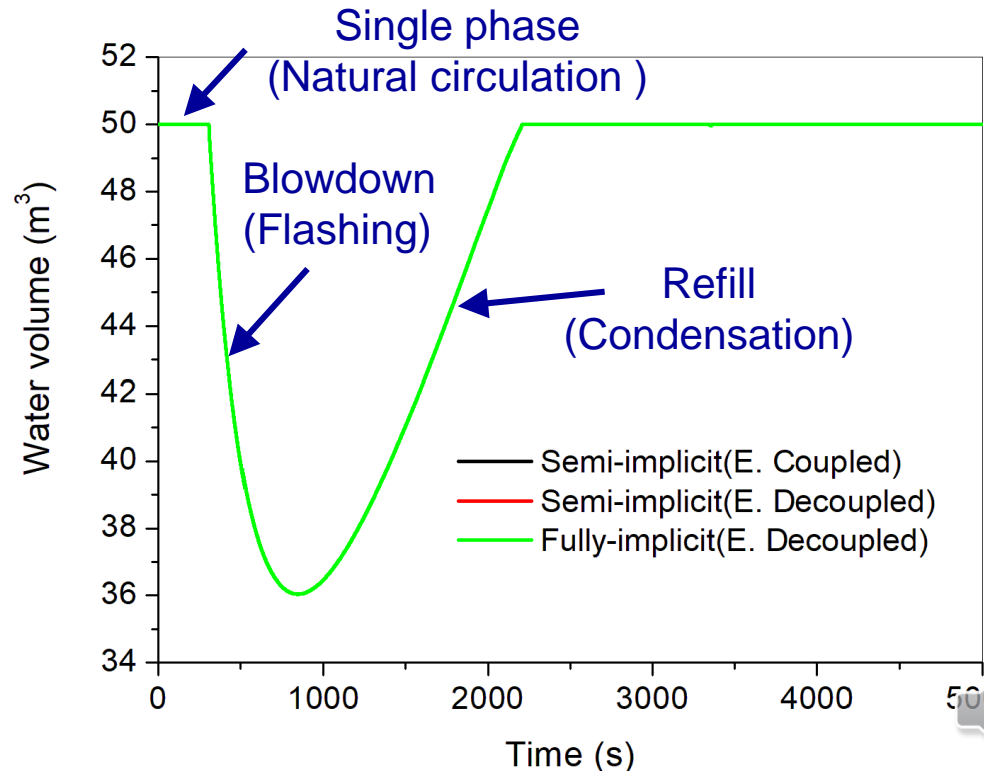
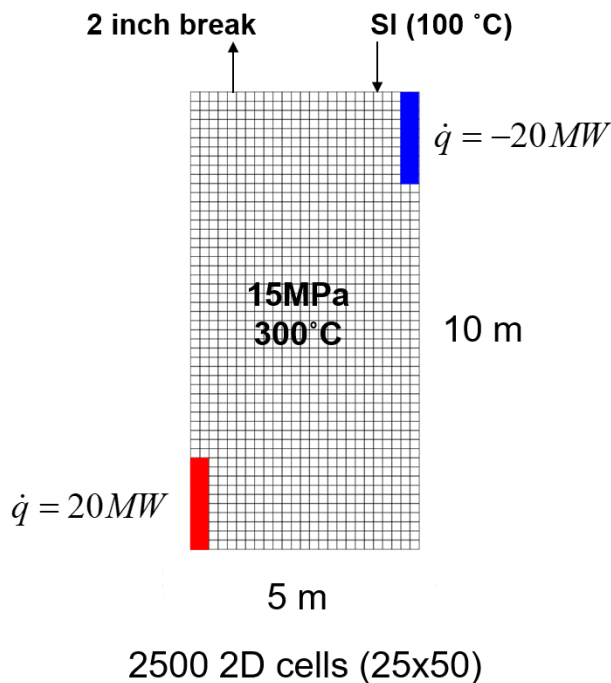
$$u(t) = H_0 \sqrt{\frac{2g}{L}} \sin\left(\sqrt{\frac{2g}{L}} t\right)$$



Verification of Different Solution Schemes

» 2-phase flow numerical test to simulate the *Blowdown and Refill* Phenomena

- To test *Numerical stability* when *a large phase change is involved*
- Fast Transient: *Single phase liquid* → *Blowdown* → *Refill*
- 3 solution schemes show the same result



Validation for the Reflood Test Problems (1/2)

» FLECHT-SEASET

- Full-Length Emergency Core Heat Transfer – Separate Effects and System Effects Test (EPRI/NRC, 1986)

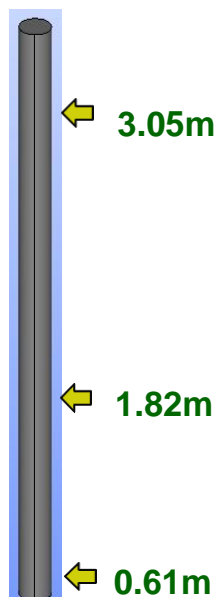
- 17x17 rod bundle test

» RBHT

- Rod Bundle Heat Transfer test (Pen State/NRC, 2012)

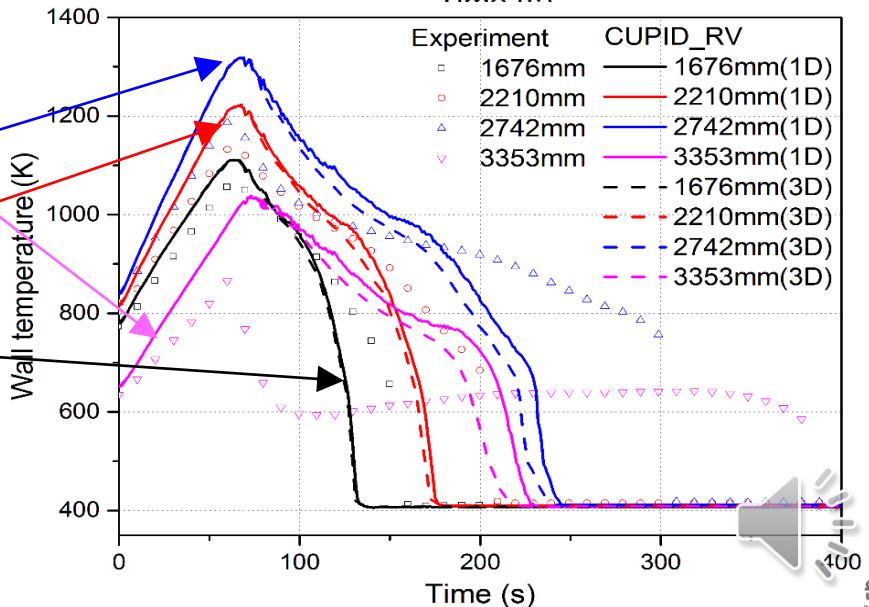
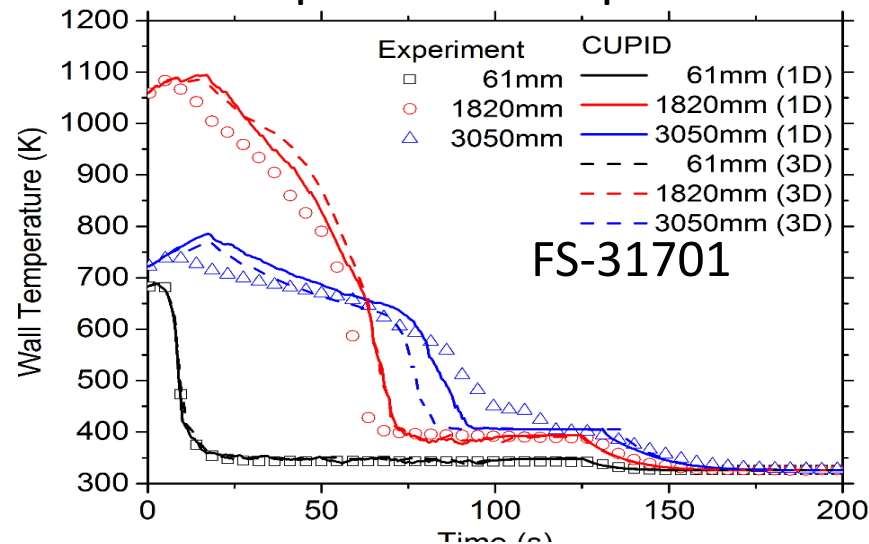
- 7x7 rod bundle in a square array

- » **2-phase flow Models and correlations** have been implemented in CUPID-RV for the analysis of **blowdown**, **refill**, and **reflood** phenomena following LBLOCA



Test Channel

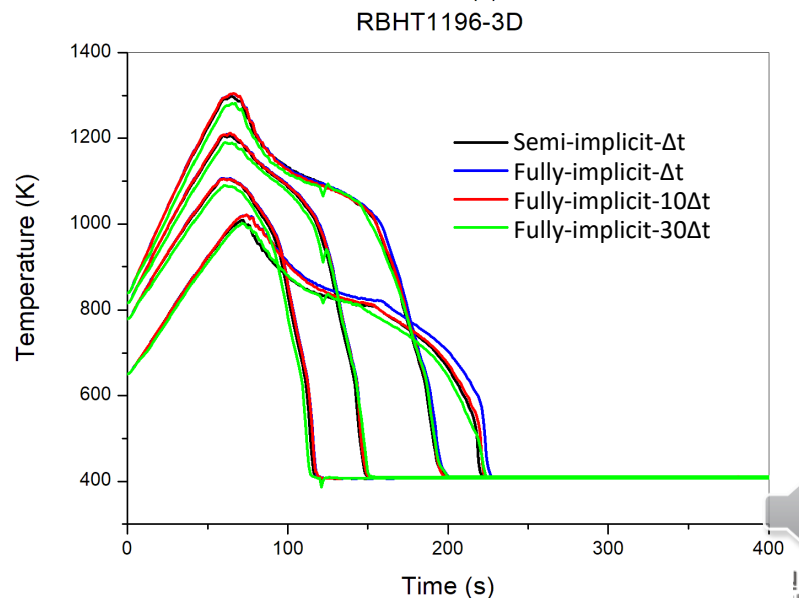
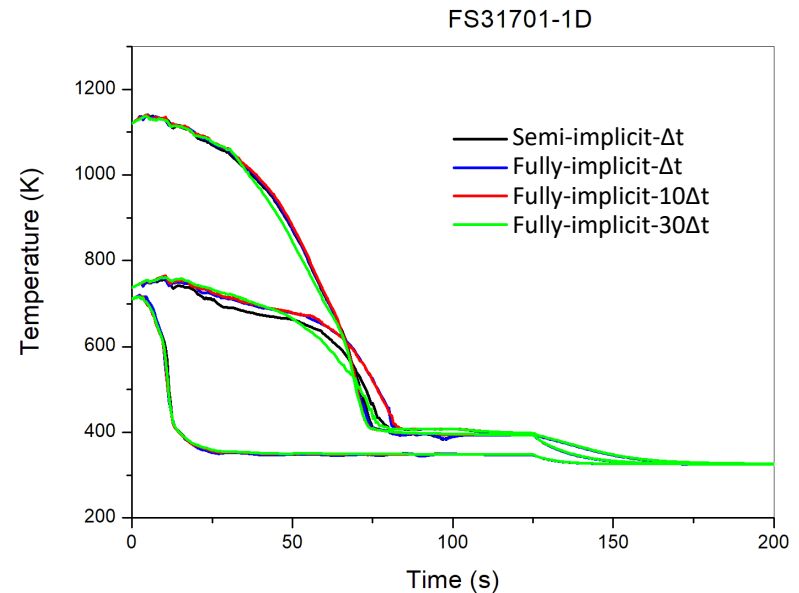
Comparison of Wall Temperatures



Validation for the Reflood Test Problems (2/2)

FS31701-1D	Computation time (s)
Semi-implicit (Δt)	69
Fully-implicit (Δt)	100
Fully-implicit ($10\Delta t$)	8
Fully-implicit ($30\Delta t$)	3

RBHT1196-3D	Computation time (s)
Semi-implicit (Δt)	1792
Fully-implicit (Δt)	2225
Fully-implicit ($10\Delta t$)	278
Fully-implicit ($30\Delta t$)	108



Summary

5



Summary

» Discretization Method of CUPID

- FVM for the modeling of complicated 3D geometries

» 3 Solution Methods are available in CUPID

➤ Energy Coupled Semi-implicit Scheme

- Used in the system analysis code and provides a reference solution

➤ Energy Decoupled Semi-implicit Scheme

- Improved numerical stability due to the nearly symmetric pressure matrix

➤ Energy Decoupled Fully-implicit Scheme

- Allows a large CFL number for a fast 2-phase flow calculation

» The fully-implicit scheme provides a ***fast and robust simulation*** of the ***transient 2-phase flow with a large phase change*** that is important for the analysis of LWR thermal hydraulics

THANK YOU

hyyoon@kaeri.re.kr

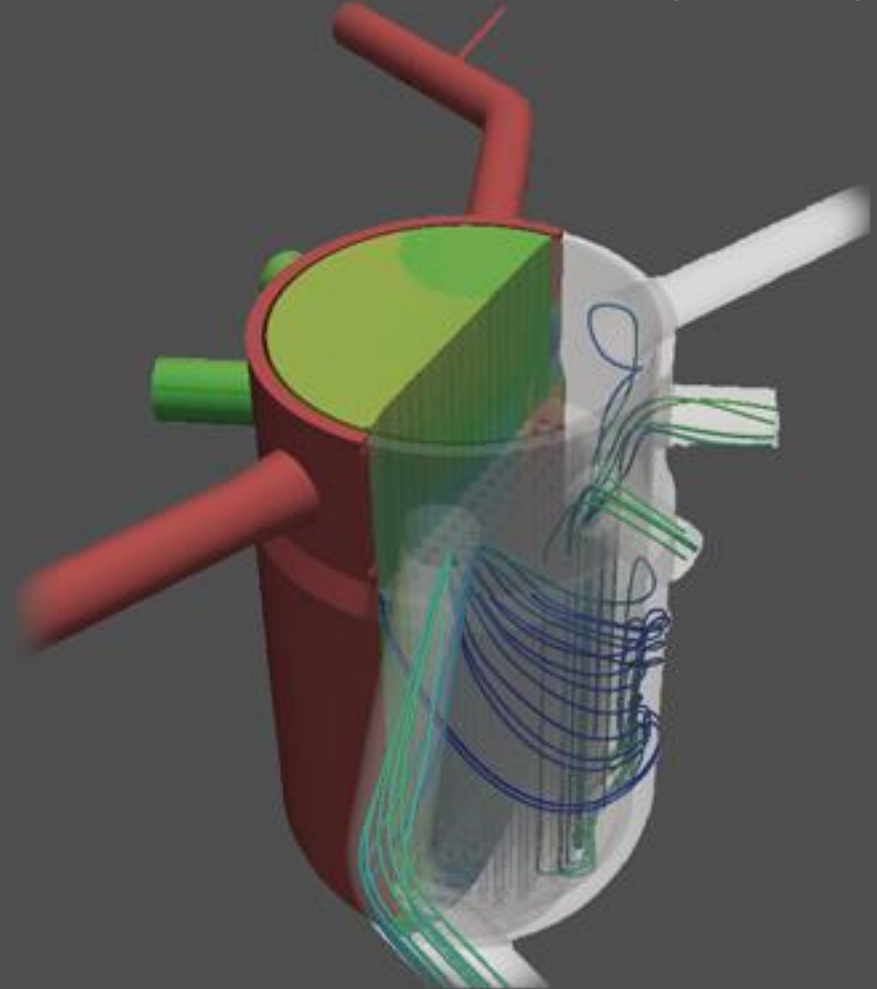




CUPID Workshop

Highly Scalable Iterative Solver
(Geometric Multi-Grid Method for
Unstructured Mesh)

Seongju Do
March 04, 2022



CUPID Workshop

CONTENTS

- ▶ 01 WHY 'Multi-Grid'?
- ▶ 02 WHAT is 'GMG'?
- ▶ 03 GMG Algorithm
- ▶ 04 Speedup Test

WHY 'Multi-Grid'?

1



WHY 'Multi-Grid'?

» One of the most time-consuming part in CUPID is the “**Poisson equation**” solving module.

- Total cost of solving pressure matrix is **40-90%**.
- The Conjugate Gradient (CG) solver is
 - Widely used in commercial CFD software
 - **Not scalable** w.r.t the number of cells N

$$CG : t_{CPU} \propto N^{1.5}$$

$$PBICG : t_{CPU} \propto N^{1.4}$$

- Development of Multi-Grid(MG) solver which is **scalable** w.r.t the number of cells

$$MG : t_{CPU} \propto N^{1.0}$$

What does the exponent mean?

#Cells	CPU time of CG	CPU time of MG
10,000	1 min	1 min
1,000,000	$100^{1.5}$ min \approx 17 hours	100^1 min \approx 1.7 hours
100,000,000	$10,000^{1.5}$ min \approx 694 days	$10,000^1$ min \approx 7 days

Pre-process

Time iteration

Model
Calculation

Intermediate
Velocity

Pressure
equation

Pressure
correction

Write output

Finalize

<CUPID work flow>

WHAT is 'GMG'?

2

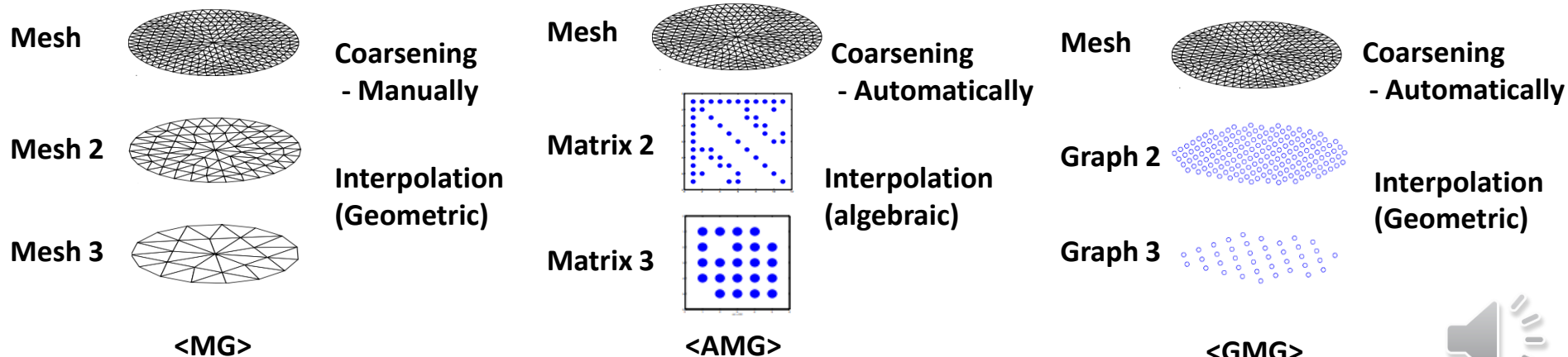


WHAT is GMG?

» Comparison MG / AMG / GMG

[1] Cao Lu et al. "A Hybrid Geometric + Algebraic Multigrid Method with Semi-Iterative smoother" NUMERICAL LINEAR ALGEBRA WITH APPLICATIONS, 2013

	Classic MG	AMG	GMG
Memory requirement	low	high	low
Operator complexity	less costly	more costly	less costly
Irregular domains	not robust	robust	Moderate
user friendliness	less friendly	more friendly	Moderate



GMG Algorithm

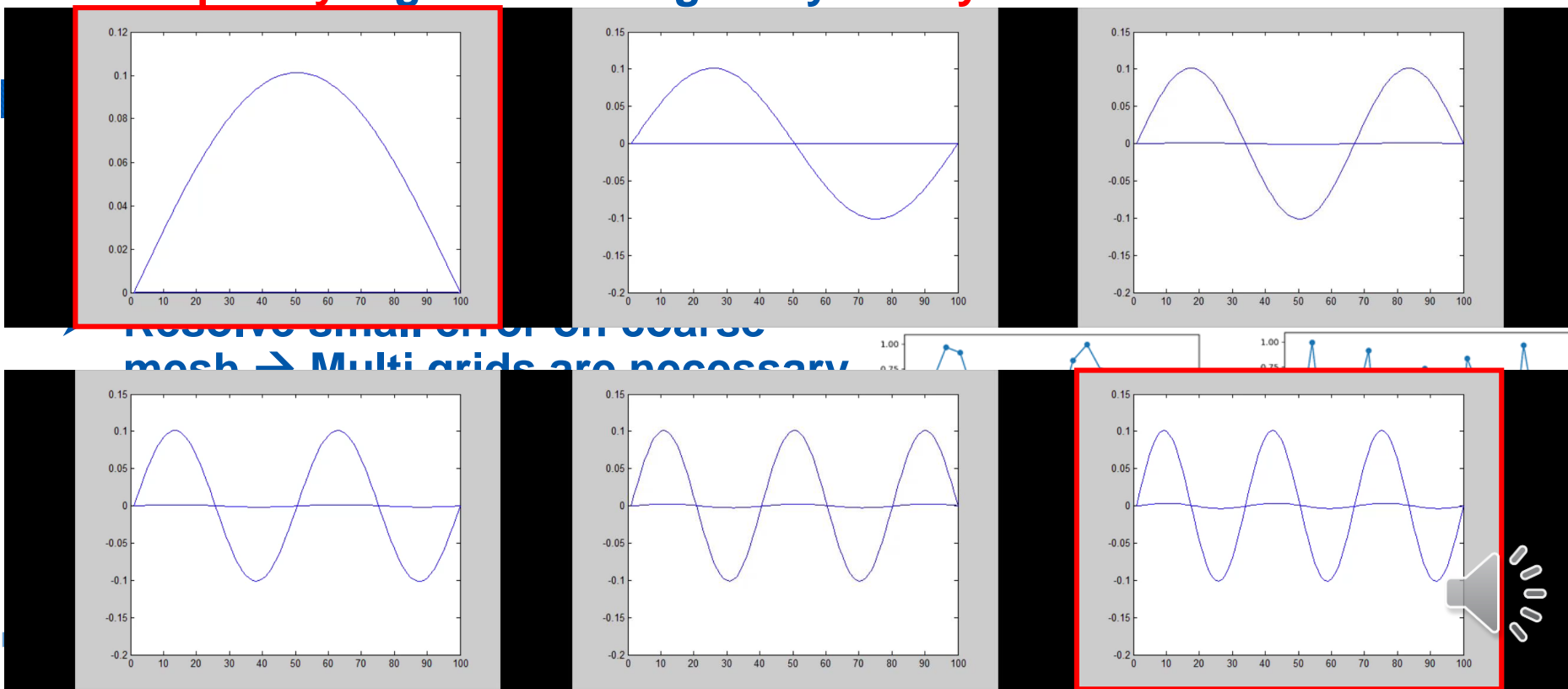
3



GMG algorithm

» Jacobi/Gauss-Seidel solver

- One of the simplest iterative linear solver
- Computational complexity for convergence is $O(N^2)$
 - Impossible to use in practical areas
- **High-frequency** parts of the error converge **quickly**, while the **low-frequency** regions converge very **slowly**.



GMG algorithm

» Elements of MG solver

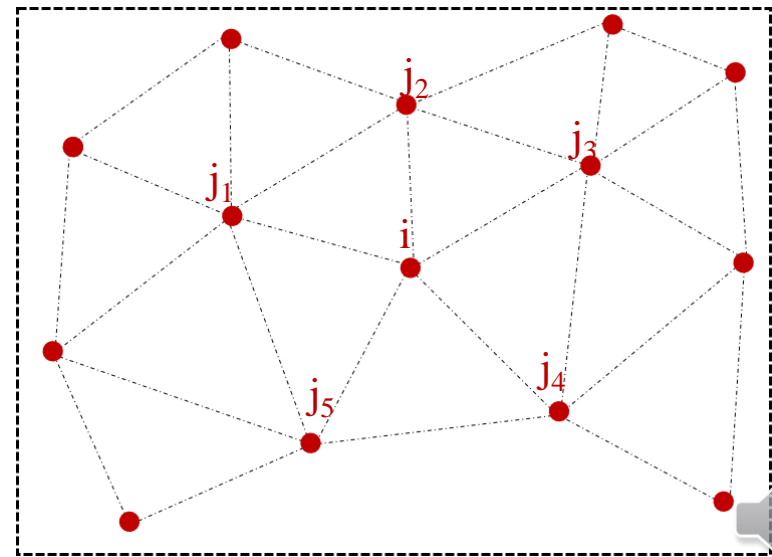
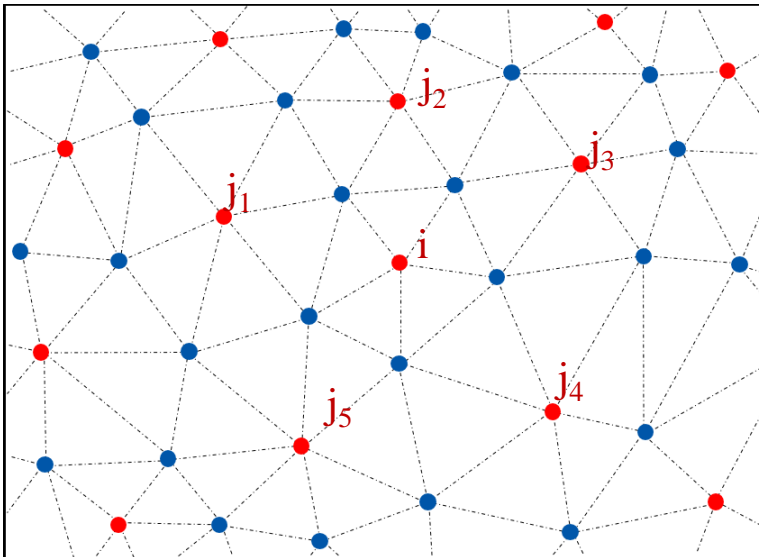
- **Coarse mesh generator**
 - Semi-coarsening method
- **Data transfer between coarse and fine meshes.**
 - Interpolator (coarse \rightarrow fine)
 - Restrictor (fine \rightarrow coarse)
- **Smoother**
- **V-cycle iteration**

GMG algorithm

[2] Herve Guillard, Node-nested multi-grid with Delaunay coarsening, (1993)

» Coarse mesh generator

- Only the finest mesh is required as an input data
 - Automatic mesh generation on coarse levels
- Node-coarsening by MIS(Maximum Independent Set [2])
 - Initially, mark all the nodes in finer mesh 'green'
 - And then, for each node in a finer mesh:
 - ✓ If the node is green add this node to the list of red nodes and mark its neighbor as the blue nodes.
 - ✓ Otherwise, go to the next node.

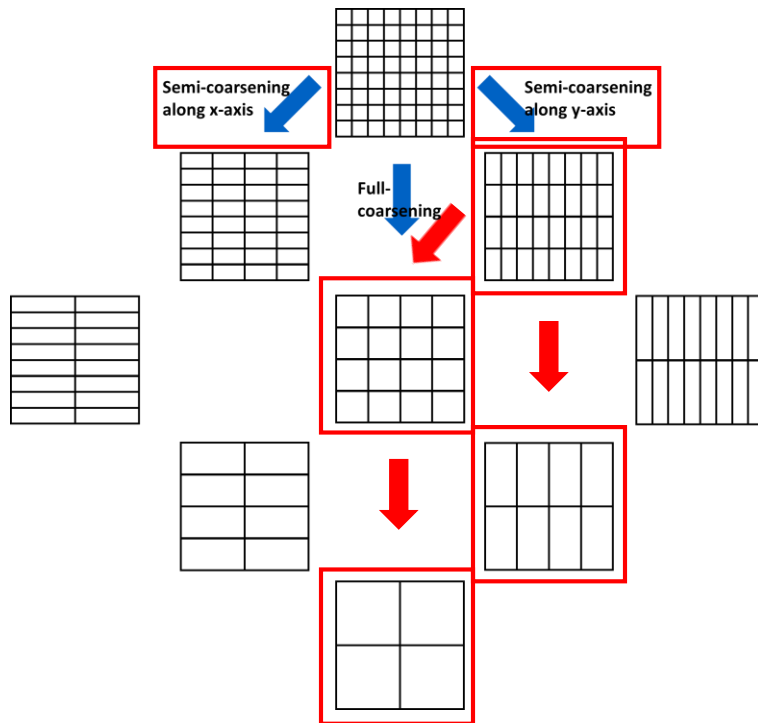


GMG algorithm

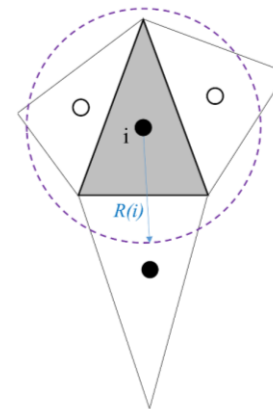
» Semi-Coarsening technique [3]

- In case of high aspect ratio mesh, the convergence speed of MG solver could be slower.
- Semi-coarsening algorithm in structured mesh is extended to unstructured mesh.

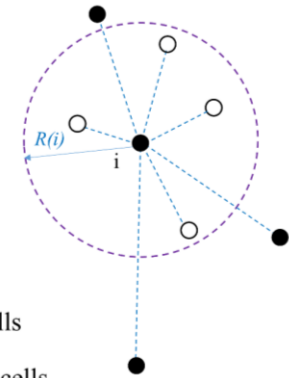
[3] E. MORANO, Coarsening Strategies For Unstructured Multigrid Technique with Application to Anisotropic Problem, *SIAM J.SCI.COMPUT.* Vol.20, No2, pp.393-415 (1998)



<Unstructured mesh>



Coarsening on the finest level



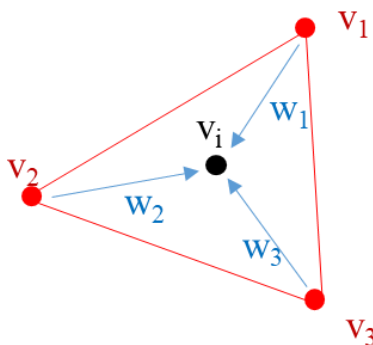
Coarsening on other coarse levels

GMG algorithm

» Data transfer between coarse and fine meshes

- Interpolator (coarse \rightarrow fine)

✓ Inverse distance

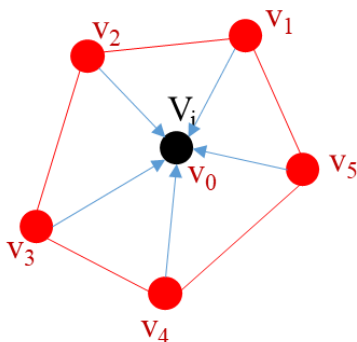


$$v_i = \frac{w_1 v_1 + w_2 v_2 + w_3 v_3}{w_1 + w_2 + w_3}$$

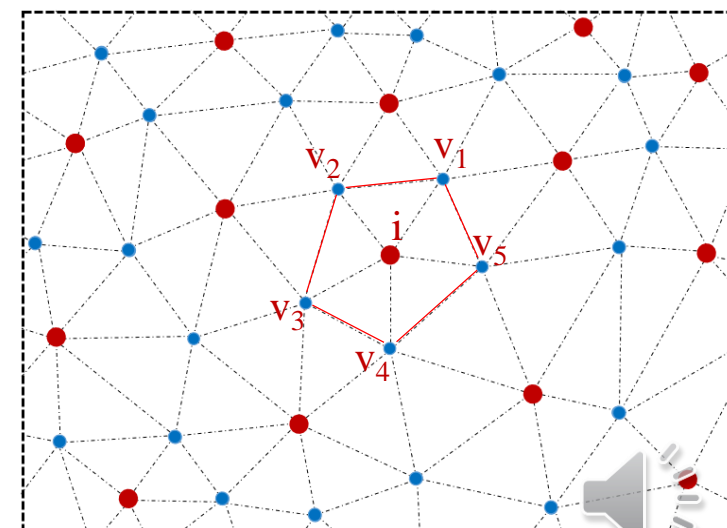
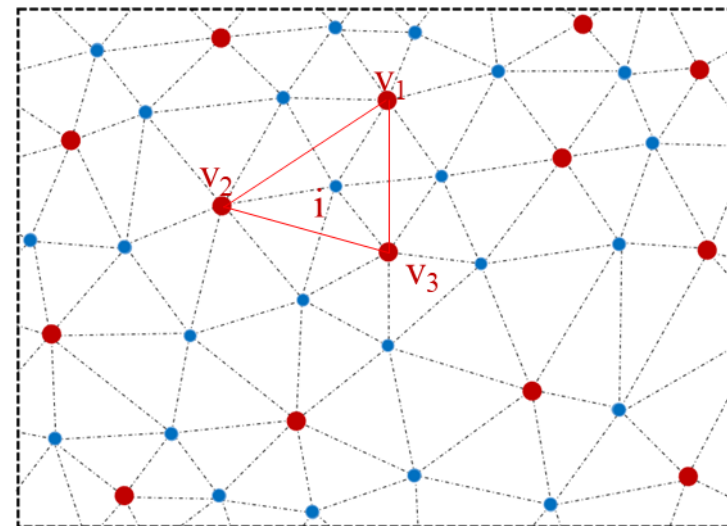
$$w_k = \frac{1}{d(v_i, v_k)}$$

- Restrictor (fine \rightarrow coarse)

✓ Injection



$$V_i = v_0$$



GMG algorithm

» Smoother

- Jacobi
- Gauss-Seidel
- Weighted Jacobi
- Weighted Gauss-Seidel (SOR)

» In CUPID, **2-3 times SOR sweeps** are performed on each meshes.

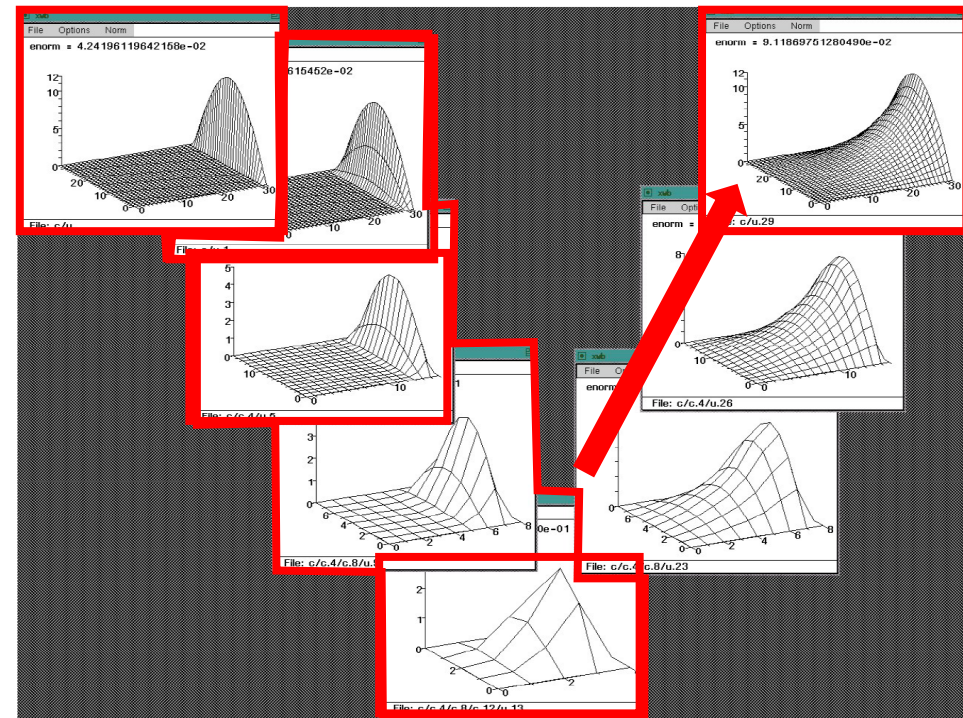
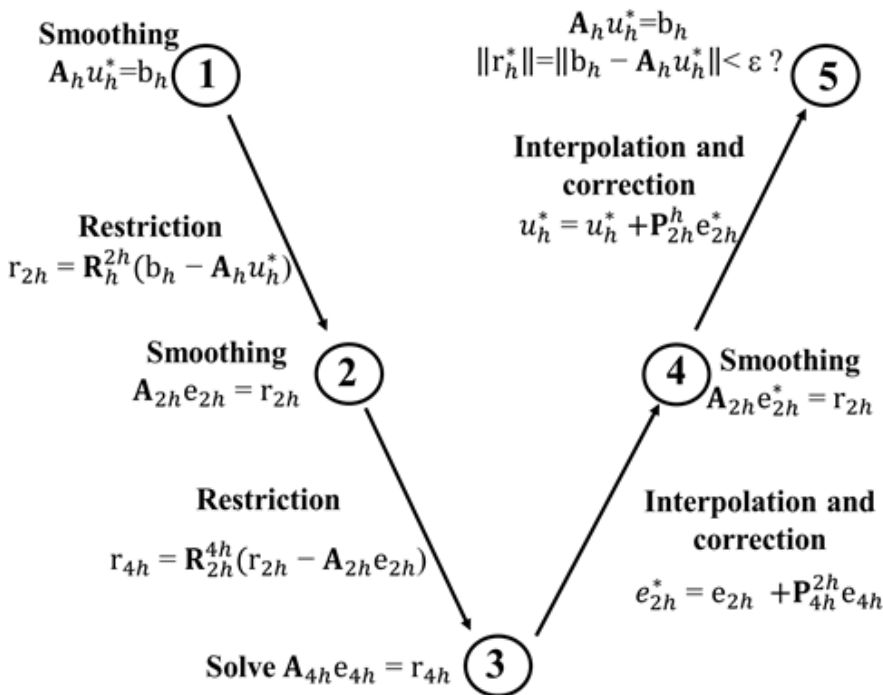
GMG algorithm

» V-cycle iteration [3]

- Smoothing residual vectors for each level
- Correct solution by adding smoothed residual vector

[3] William L. Briggs et al. "A multigrid tutorial" SIAM, 2000

[4] <http://www.mgnet.org/mgnet/tutorials/xwb/smooth.html>



V-cycle workbench [4]

Speedup Test

4

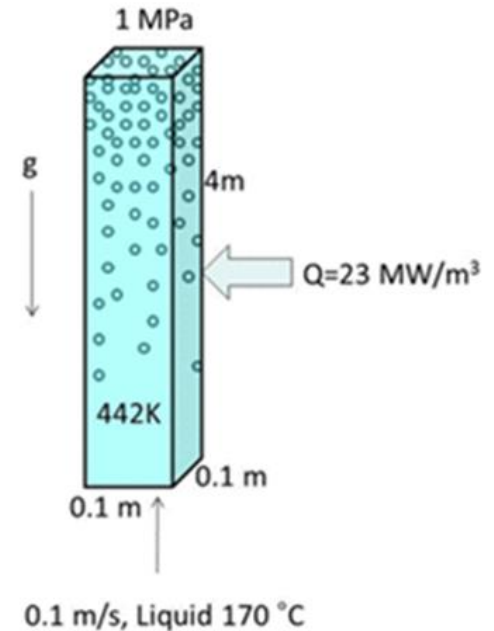
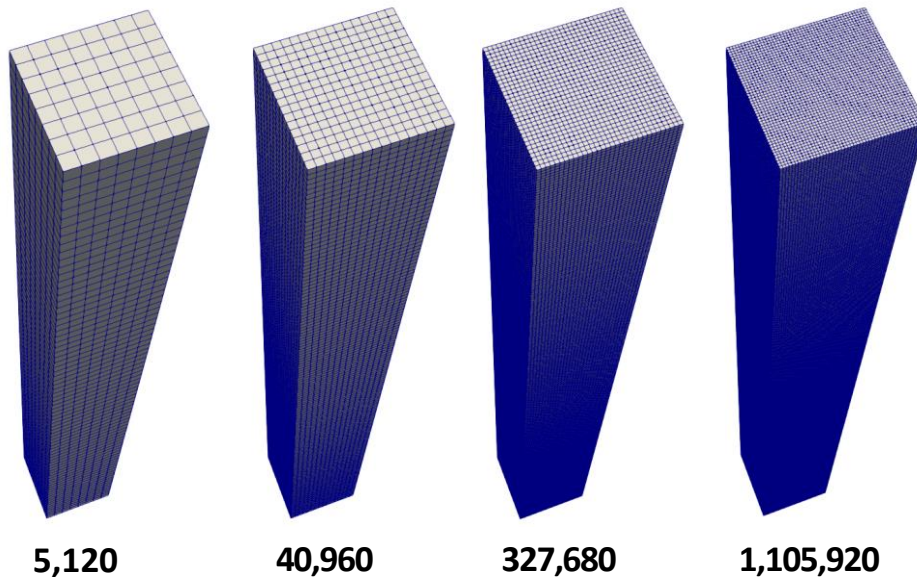
- 3D boiling flow
(two-phase/structured)
- 3D Reactor Vessel problem
(single-phase/unstructured)
- 3D Channel flow
(single-phase/unstructured/
~100 million cells)



Speedup Test – 3D boiling (1/2)

» 3D boiling test

- Two-phase simulation
- 4 kinds of structured meshes are used to evaluate the performance of GMG solver

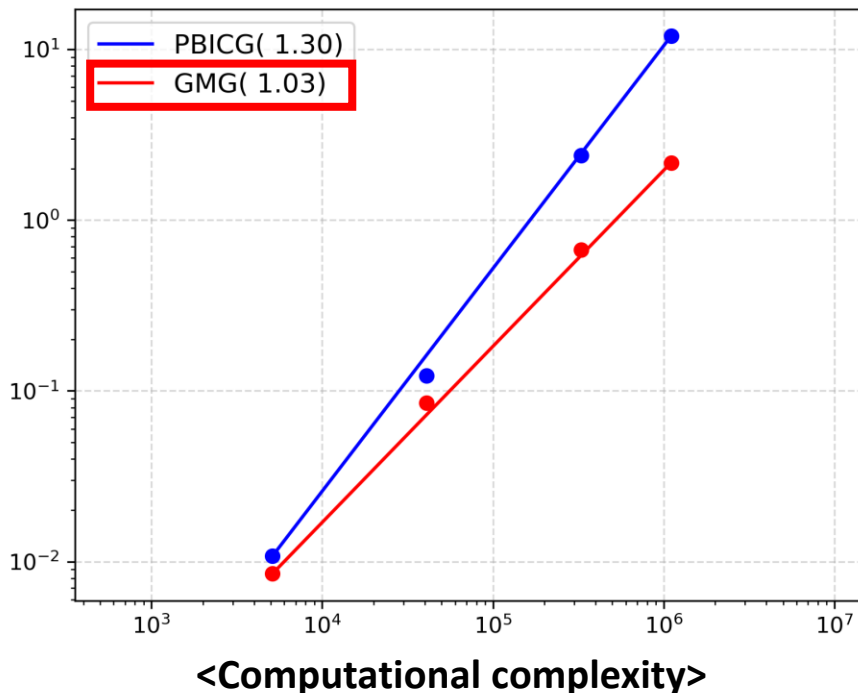


<Test setup>

Speedup Test – 3D boiling (2/2)

» 3D boiling test

➤ Result of automatic mesh coarsening



➤ Comparison of PBICG / GMG

- The number of iteration in GMG is *constant* regardless of the number of cells.
- The larger the problem size, the greater the benefit of GMG.

Case	Num. cells	PBICG iteration	GMG iteration	Speed up [times]
Mesh 1	5,120	37	10	0.88
Mesh 2	40,960	63	10	1.44
Mesh 3	327,680	124	10	3.91
Mesh 4	1,105,920	174	10	5.40

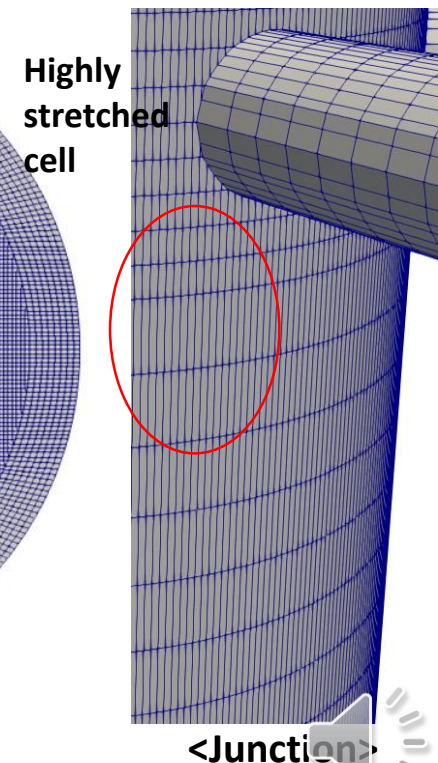
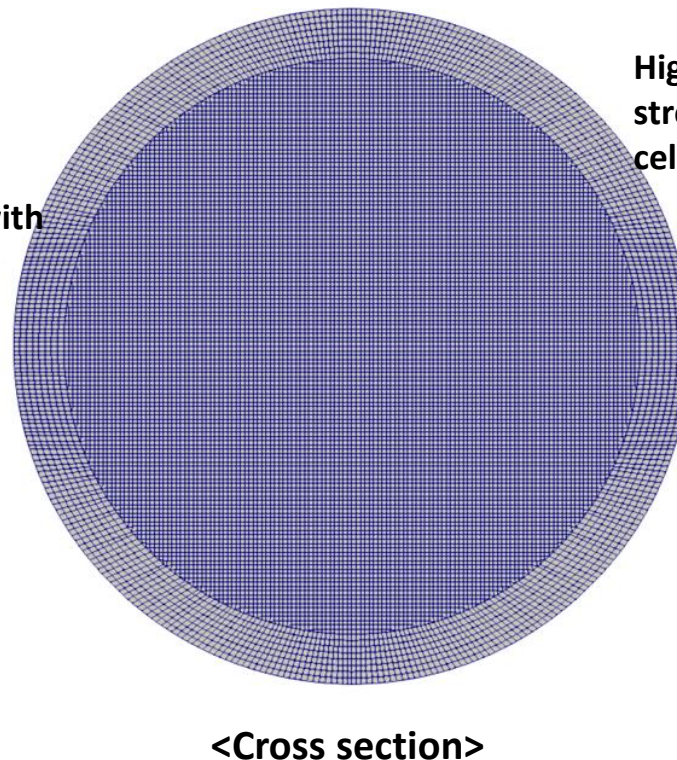
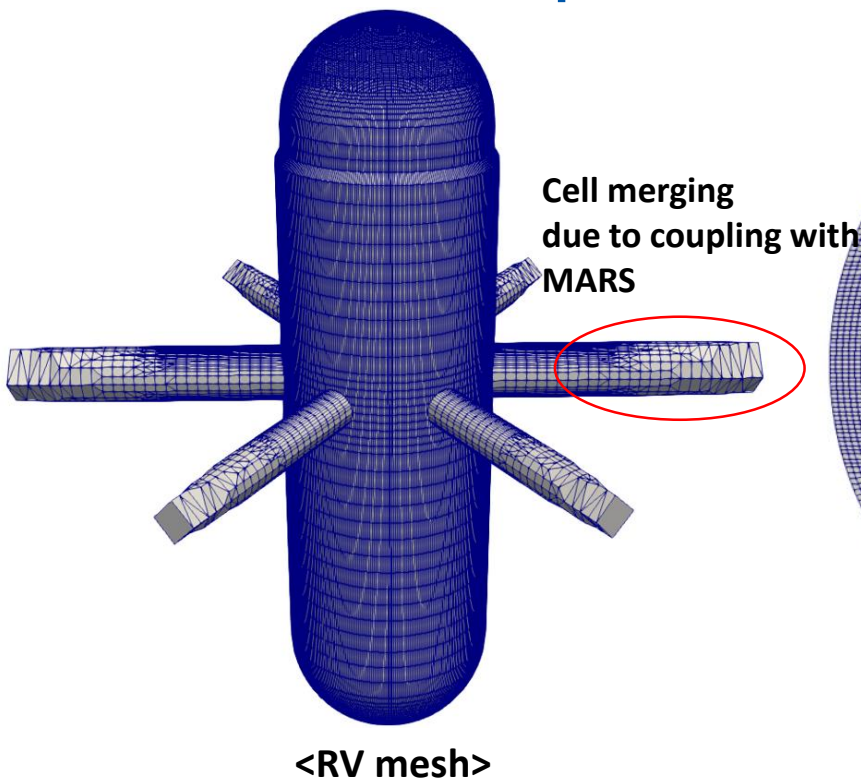
Increasing!

Constant !

Speedup Test – RV problem (1/2)

» RV test

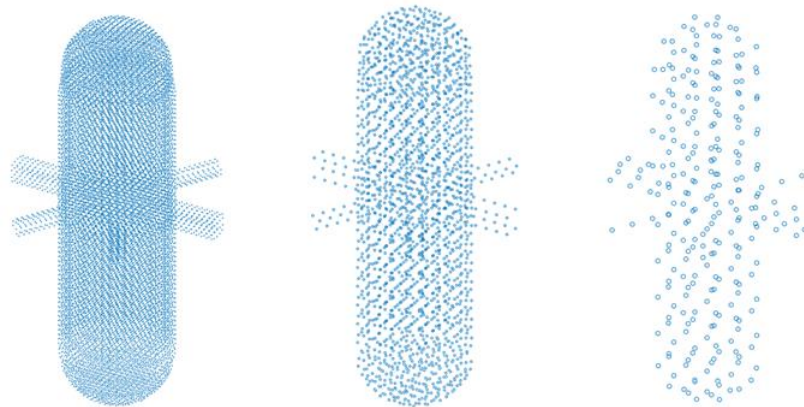
- Polygonal cells / High aspect ratio mesh
- 4 kinds of unstructured meshes are used to evaluate the performance of GMG solver



Speedup Test – RV problem (2/2)

» RV test

➤ Result of automatic mesh coarsening



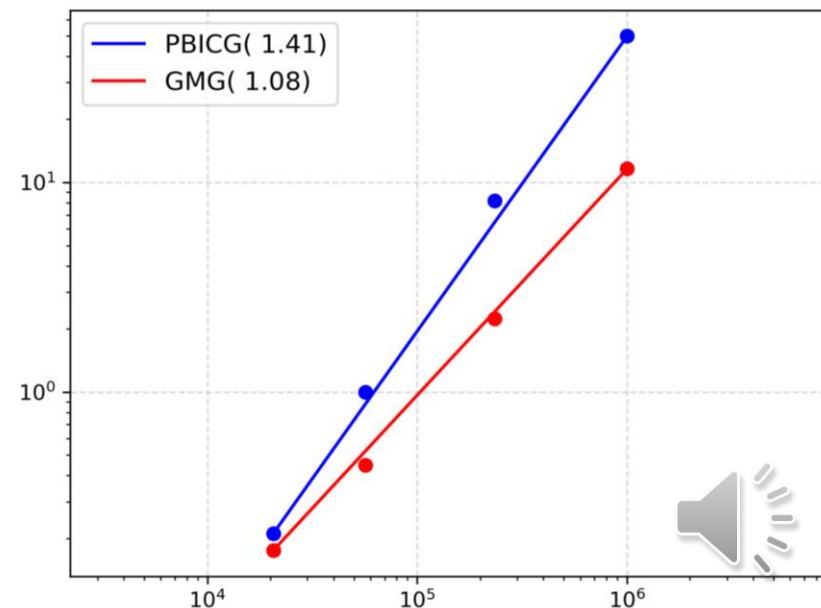
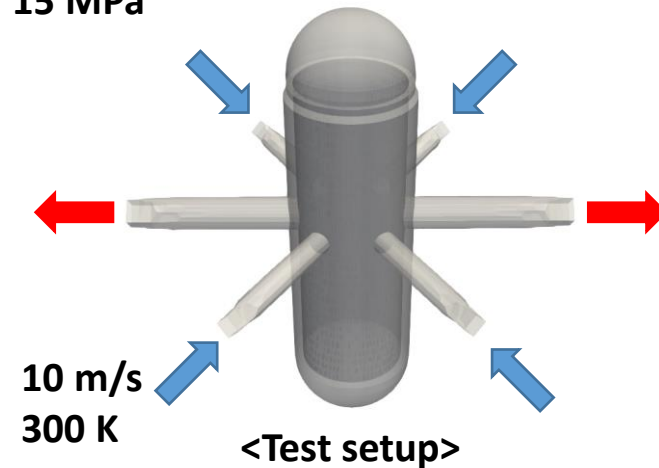
<Nodes after coarsening>

➤ Comparison of PBICG / GMG

Case	Num. cells	PBICG iteration	GMG iteration	Speed up [times]
Mesh 1	20,619	121	28	1.273
Mesh 2	56,654	171	22	2.246
Mesh 3	234,122	263	26	3.617
Mesh 4	1,003,086	317	28	4.245

Almost constant

15 MPa



Speedup Test – Channel flow (1/2)

» Single phase channel Flow

- Well-known problem in the DNS community

➤ Computational setup

- Domain

$$4\pi\delta \times 2\delta \times \frac{4\pi\delta}{3} \quad (\delta = 0.01m)$$

- 6 kinds of unstructured meshes

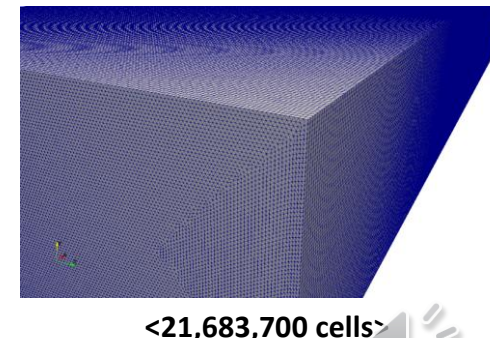
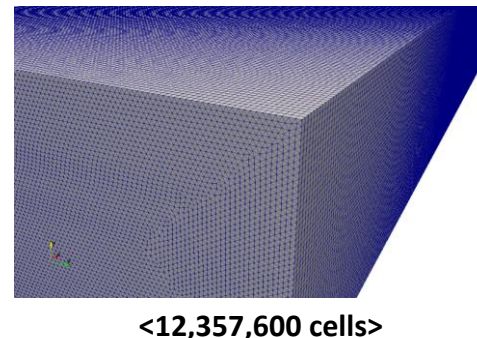
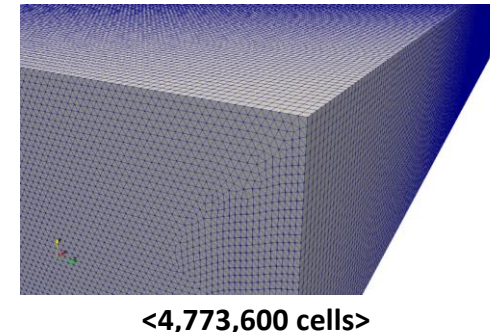
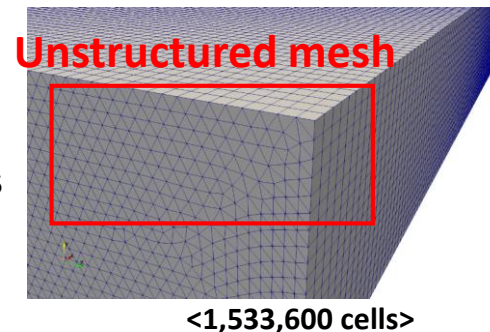
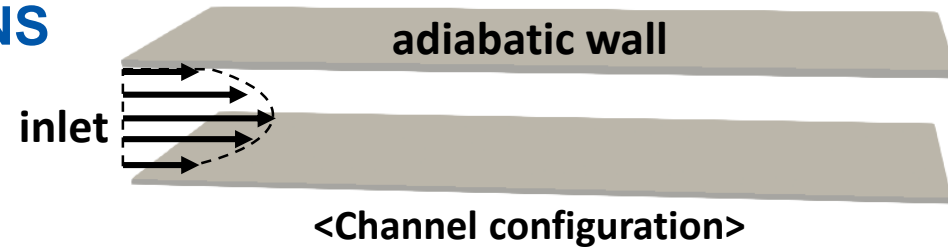
191,800(mesh1)	1,533,600(mesh2)
4,773,600(mesh3)	12,357,600 (mesh4)
21,683,700(mesh5)	107,968,000(mesh6)

- Low Reynolds number

$$\text{Re} = \frac{U_h \delta}{\nu} = 283.4$$

- Inlet condition

- ✓ parabolic velocity profile from DNS data



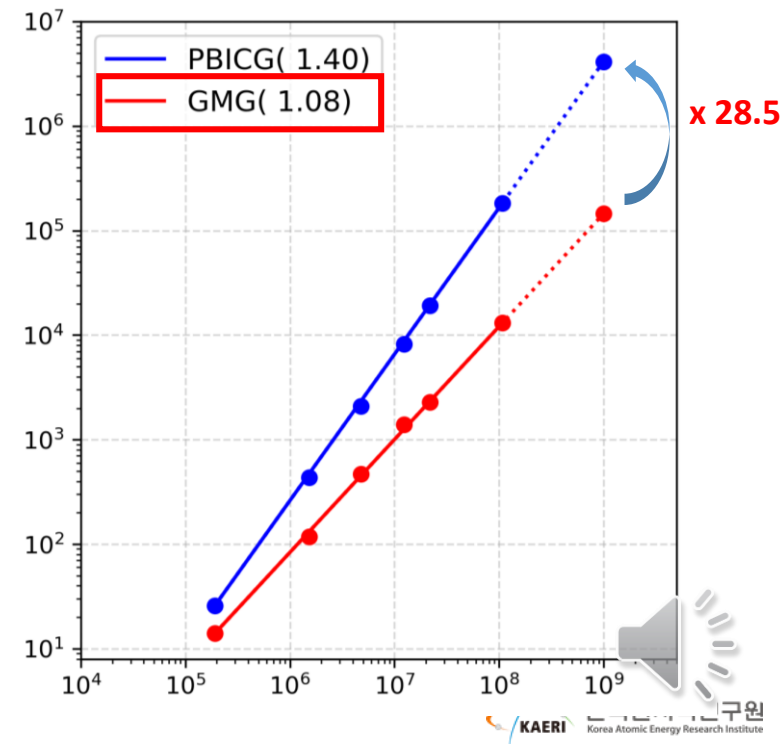
<Computational meshes>

Speedup Test – Channel flow (2/2)

➤ Comparison of PBICG / GMG

- The overall trend is similar to the previous problems.
- The complexity exponent of GMG is **1.08**, which is slightly larger than the theoretical value 1.
- In the case of **1 billion** cells, GMG is predicted to improve matrix solving performance by about **28.5** times.

Case	Num. cells	PBICG iteration	GMG iteration	Speed up [times]
Mesh 1	191,800	152	21	1.84
Mesh 2	1,533,600	216	27	3.66
Mesh 3	4,773,600	463	27	4.57
Mesh 4	12,357,600	640	27	5.85
Mesh 5	21,683,700	892	28	8.44
Mesh 6	107,968,000	1472	29	13.63



Speedup Test – Total computational time

» Calculation load

1st part



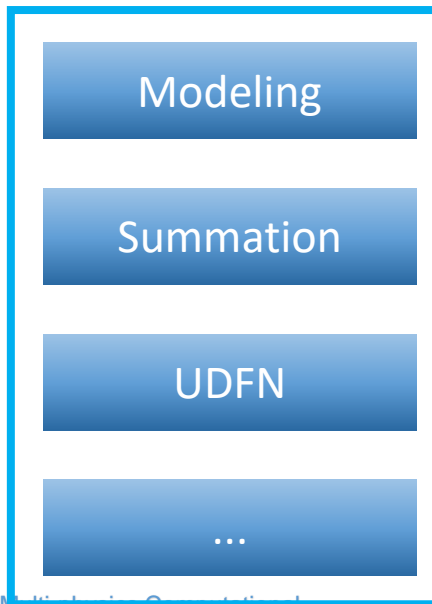
Computational cost:
 $O(n^{1.4})$ for PBICG

Do **Until converge** ← depends on n
 Do cell loop
 (PBICG algorithm)
 End Do
 End Do

➤ How much can GMG solver contribute to reduction of whole CPU time?

➤ Computational time of 'Pressure solving' is dominant as 'n' increases.

2nd part



Computational cost: $O(n)$

Do cell loop
 (Do something.)
 End Do

 Do face loop
 (Do something.)
 End Do

Total calculation

Pressure solve

Num. cells	$\frac{t_{PBICG}}{t_{total}}$	Speed up (pressure)	Speed up (total)
191,800	0.566	∞	2.30
1,533,600	0.739	3.66	2.160
4,773,600	0.816	4.57	2.758
12,357,600	0.840	5.85	3.293
21,683,700	0.902	8.44	4.881
107,968,000	0.946	13.63	8.069
1,000,000,000	0.987	28.52	21.005

1 day → 1 hour

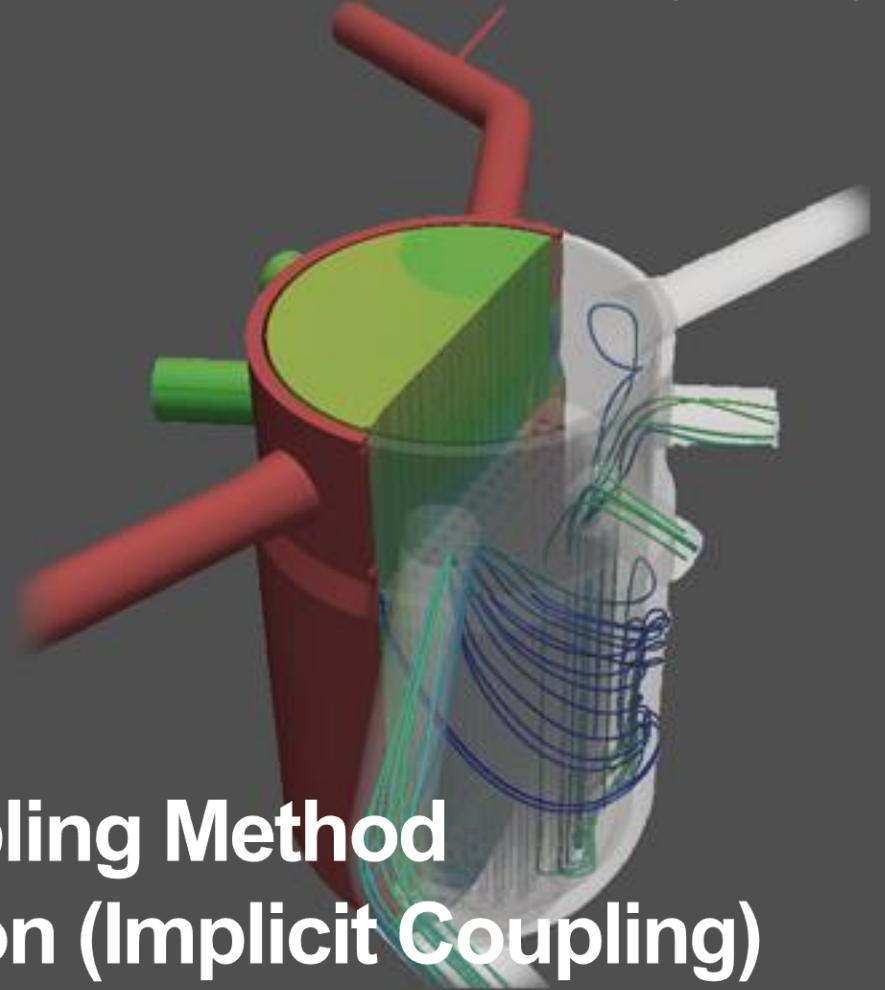
Summary

- » GMG solver can **stably** and **efficiently** solve the **single/multi-phase** problem on **unstructured** meshes.
- » The performance gain of GMG solver becomes **more larger** as the number of mesh increases.
- » GMG solver can be used in calculations on unstructured meshes **without additional user's effort**

THANK YOU

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CUPID Workshop

Unique Multi-Scale Coupling Method for a Transient Calculation (Implicit Coupling)

Ik Kyu Park
March 04, 2022

CUPID Workshop

CONTENTS

- ▶ 01 Multi-Scale Method for PWRs
- ▶ 02 Multi-Scale Coupling Method of CUPID
- ▶ 03 Nuclear Reactor Application
- ▶ 04 Summary

Multi-Scale Method for PWRs

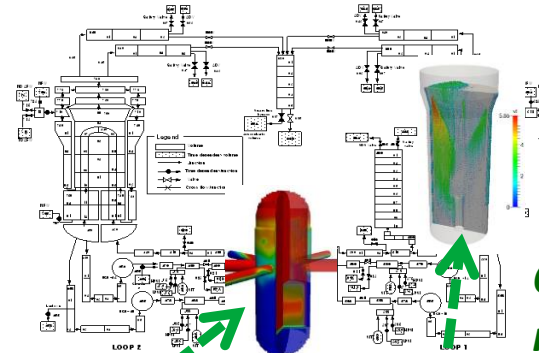
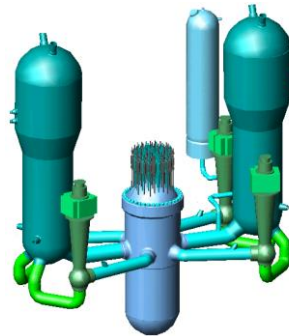
1

- Overview of Multi-Scale Approach
- Multi-Scale Coupling Strategy of CUPID



Multi-Scale Approach in Nuclear T/H

System-scale



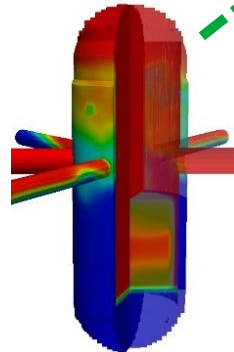
$\sim 10^0 m$

**Combined
multi-scale
calculation**

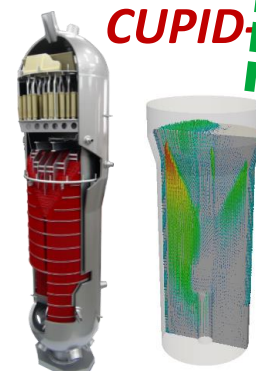
**Component-scale
(CFD-Porous)
(subchannel-scale)**



CUPID-RV



CUPID-SG

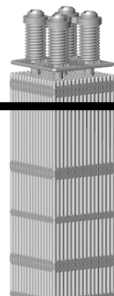


$\sim 10^{-3} m$

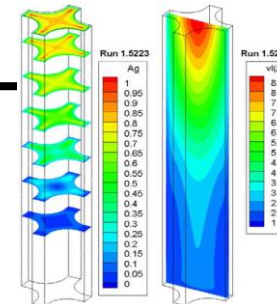
CFD-RANS

CFD-LES

CFD-DNS



CUPID-CFD



$\sim 10^{-4} m$

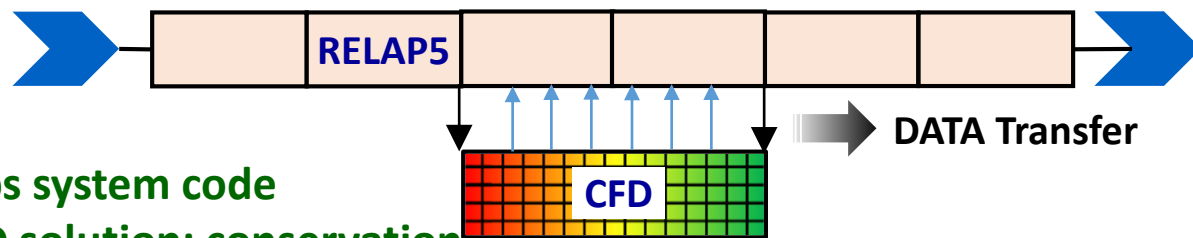
$\sim 10^{-5} m$

$\sim 10^{-6} m$

Overview of Multi-Scale Methods

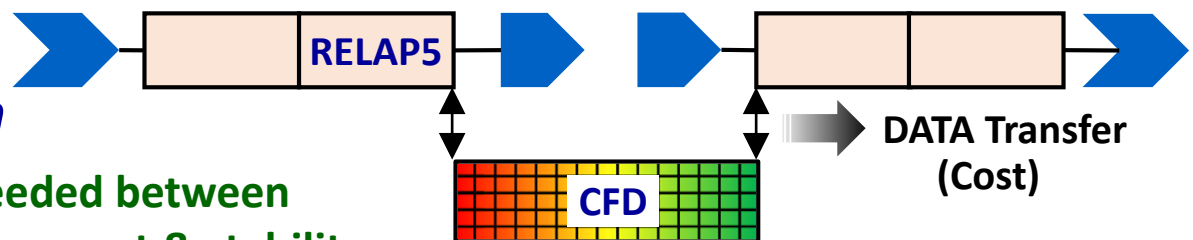
Domain Overlapping

CFD code overlaps system code
solution with CFD solution: conservation



Domain Decomposition

Data Transfer is needed between
two separate solvers: cost & stability



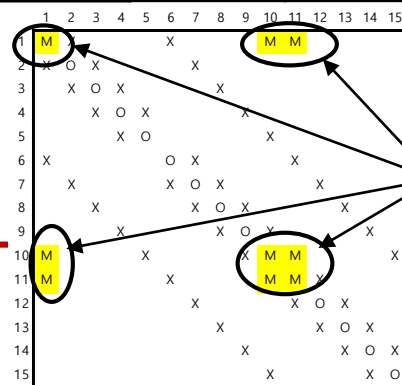
Ex)
RELAP5/
CFX,
FLEUNT,
STAR-CCM+

Single Domain

Single pressure solver matrix
: **No need for the Data Transfer**
→ Versatile application to transient problems



System analysis code
developed by KAERI



Contribution
of MARS
to CUPID pressure
matrix coefficients

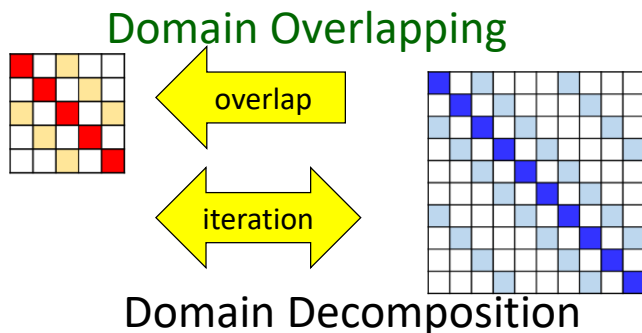
<Combined Pressure
Matrix of CUPID>

* I.K.Park et al., Annals of Nuclear Energy, 2013.

Multi-Scale Coupling Strategy of CUPID

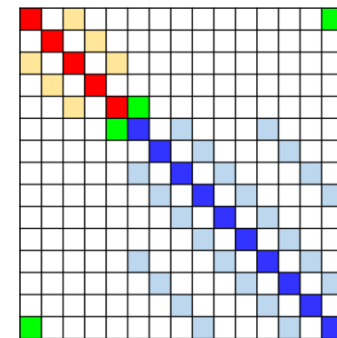
» Comparison Multi-Scale Coupling Methods

Method	Characteristics	Limitation	Applications
Domain Overlapping	Transfer B.C. Overlapping solutions	Mapping Conservation Fast transient	CATHARE2/TrioCFD SFR Natural Convection
Domain Decomposition	Iterate two solvers transferring B.C.	Fast transient	ATHLET/OpenFOAM ROCOM PKL3 Test 1.1 Flow Mixing
Single Domain (Implicit coupling)	Build a single solver matrix combining two domains	Two source codes should be accessible.	MARS/CUPID APR1400 MSLB Accidents



Combined Single Domain
with a Single solver

-manipulate pressure
matrix coefficients



Multi-Scale Coupling Method

2

- Implicit Multi-Scale Coupling Method
- Verification of the Implicit Coupling Method

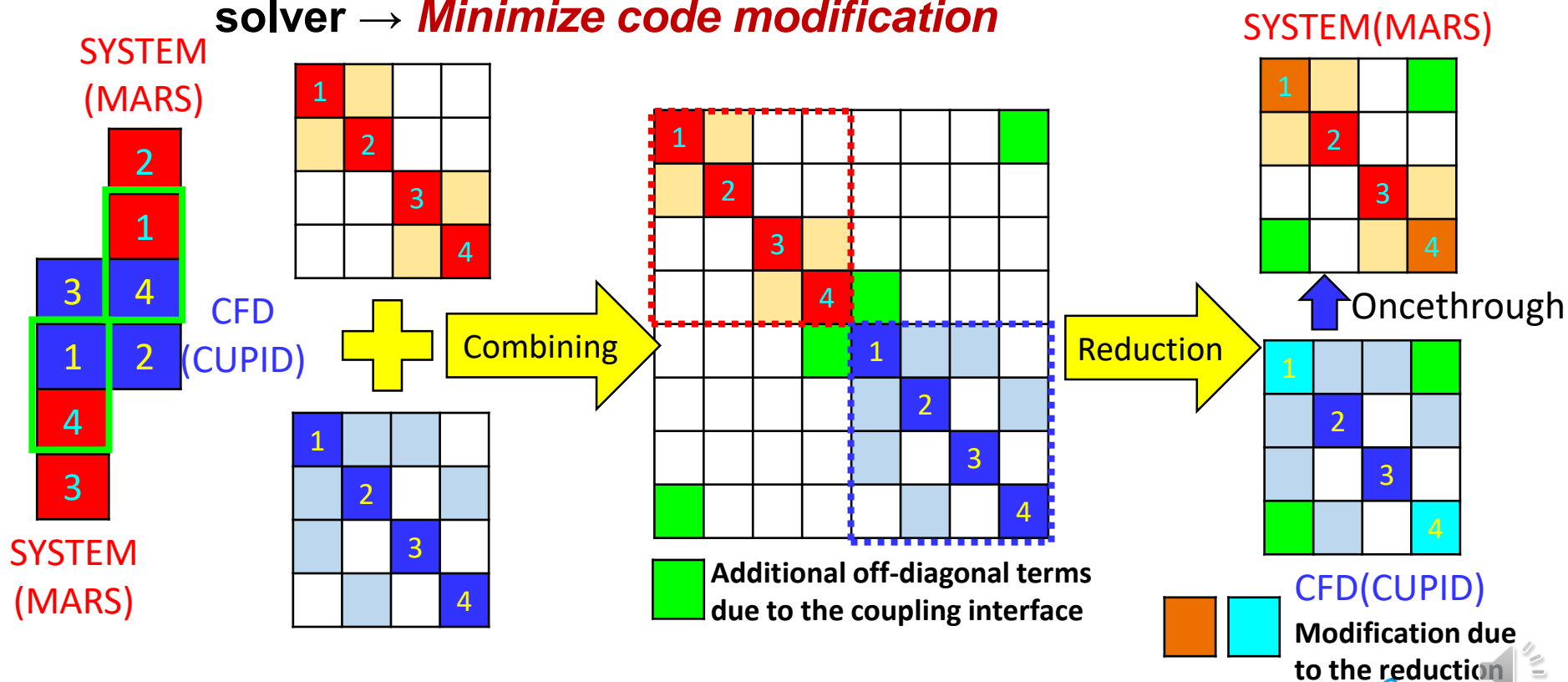


Implicit Multi-Scale Coupling Method (1/3)

» Strategy of the Coupling Method

➤ Solve a *single matrix* for the combined single domain

- The pressure matrices of two codes are *combined*
- *Matrix reduction* is needed to fit the matrix into each code solver → *Minimize code modification*



Implicit Multi-Scale Coupling Method (2/3)

» Contribution of Coupling Face to Pressure Solver

➤ Pressure correction eq. from mass & energy eqs.

- Relation btw volume flow & pressure correction from momentum eq.

➤ Neighbor cell effects appears on off-diagonal terms

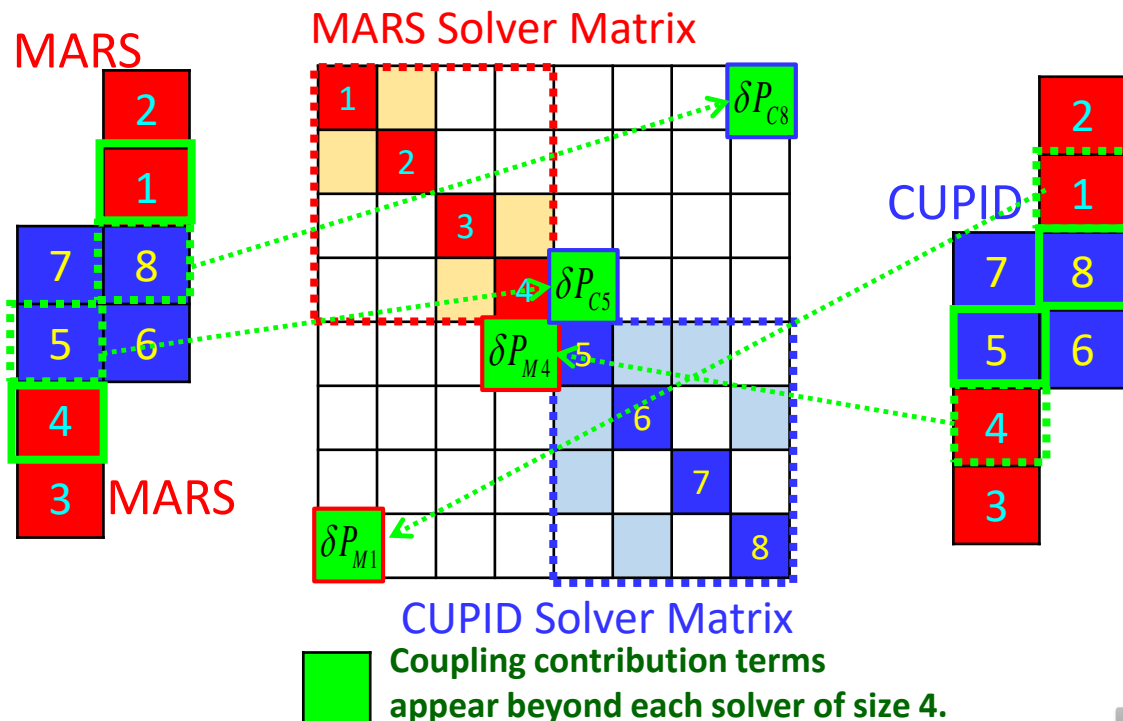
- Need to eliminate off-diagonal terms contributed by the partner code

$$\delta P_i = b_i + \sum_{f=1, NB} S_f V_f^{n+1}$$

$$S_f V_f^{n+1} = \alpha_f + \beta_f (\delta P_j - \delta P_i)$$

$$\delta P_i = b'_i + \sum_{f=1, NB} \left(\beta_f (\delta P_j - \delta P_i) \right)$$

j=Neighbor cell

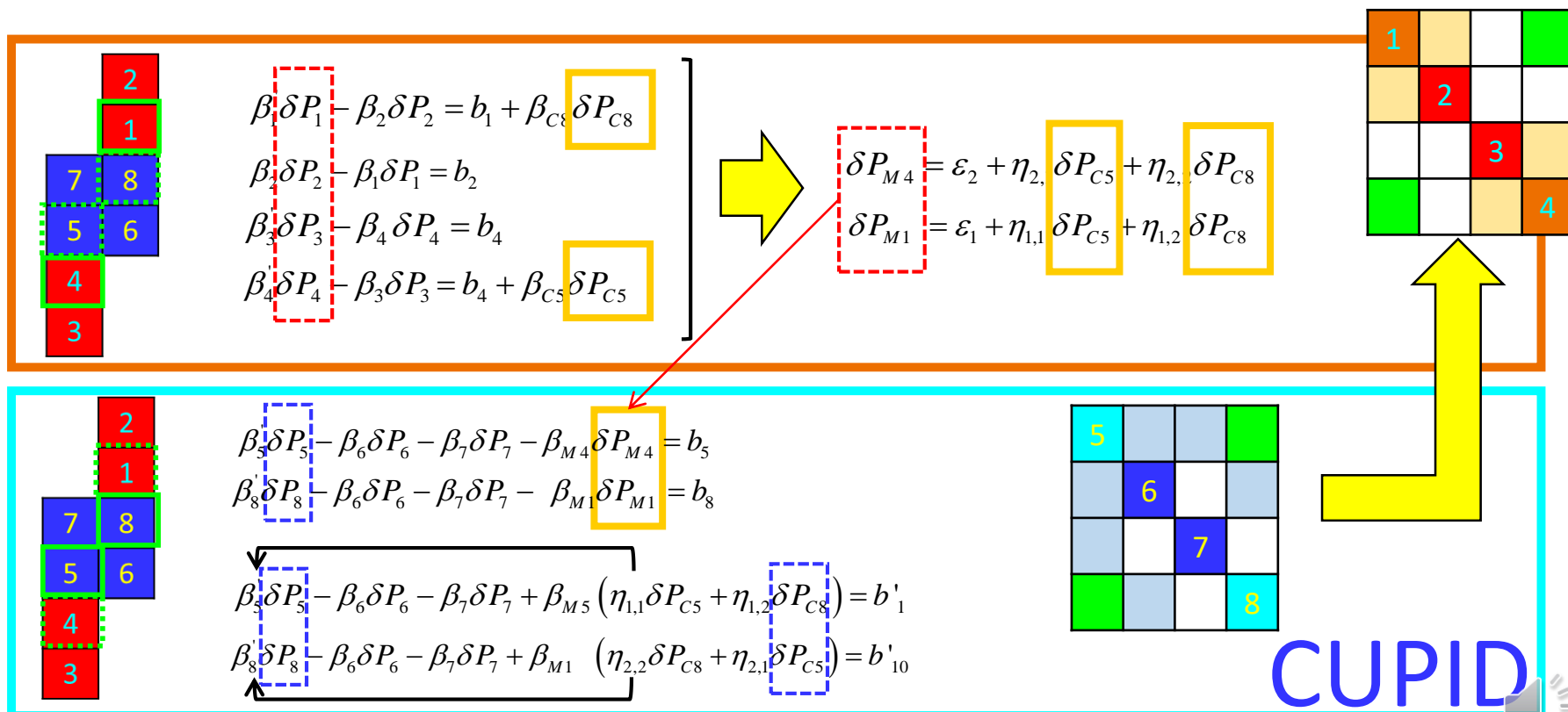


Implicit Multi-Scale Coupling Method (3/3)

» Reduction to fit the matrix into each code solver

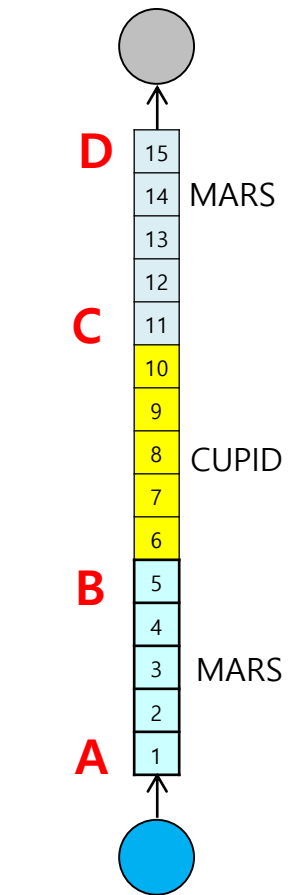
- Relation of pressure corrections btw coupled cells in MARS
- Eliminate MARS contribution in CUPID pressure correction eqs.
- Solve pressure matrix from CUPID to MARS

MARS

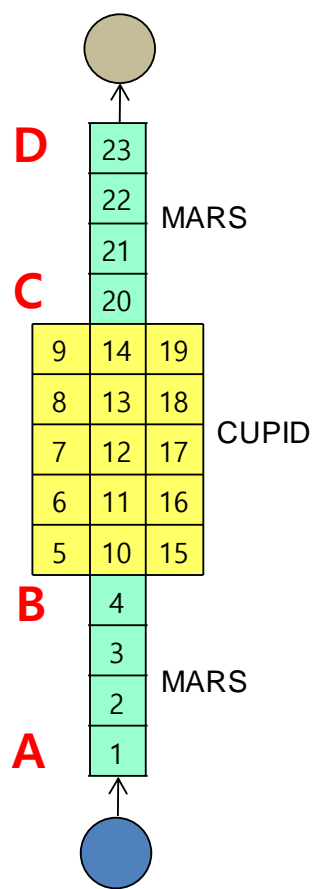


Verification of Implicit Flow Coupling (1/3)

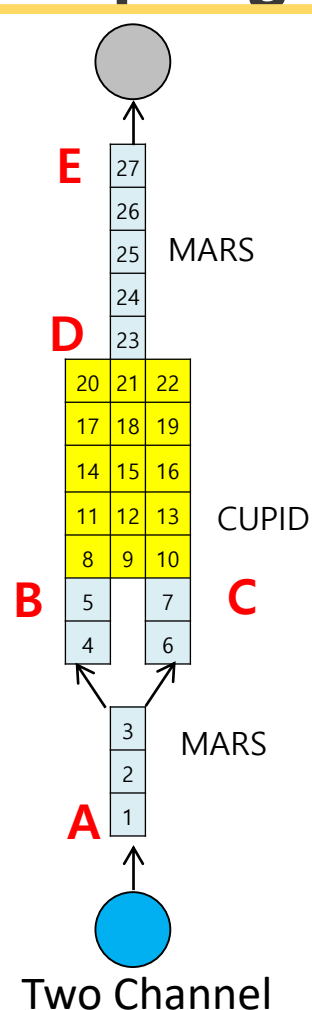
» Various Types of Coupling Examples



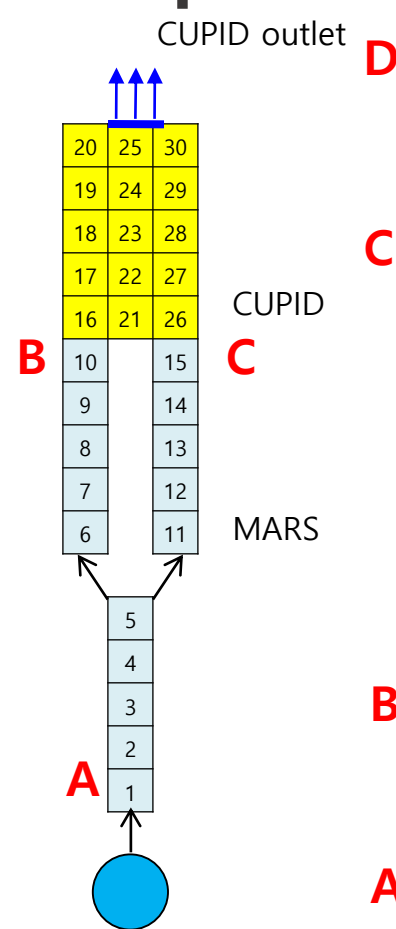
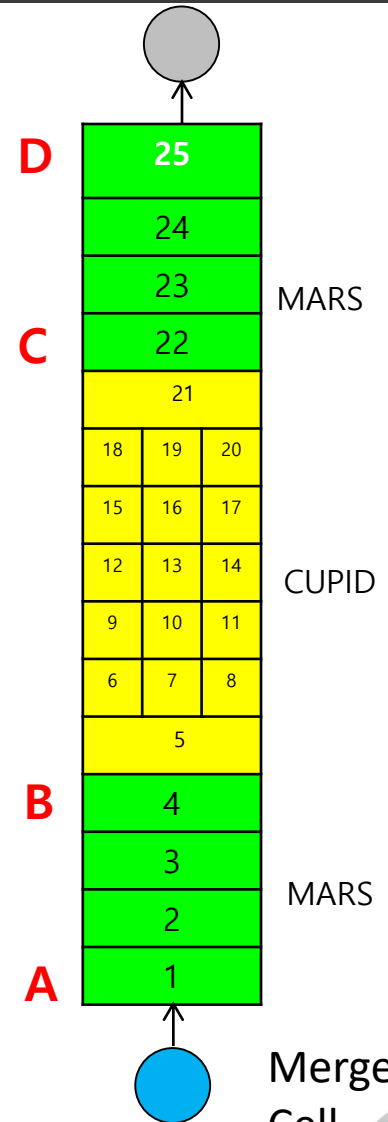
Single channel



Diffused channel

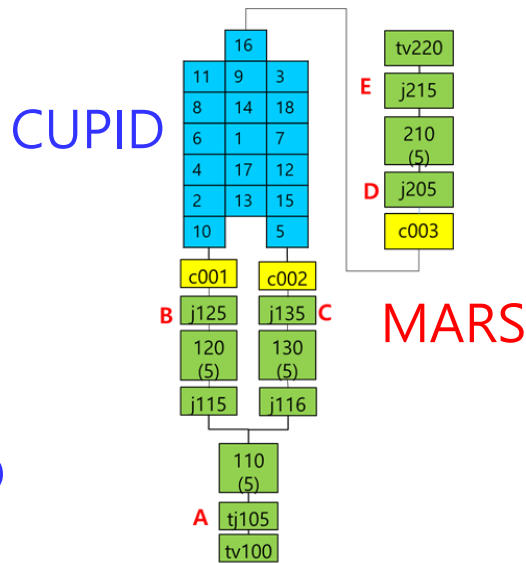
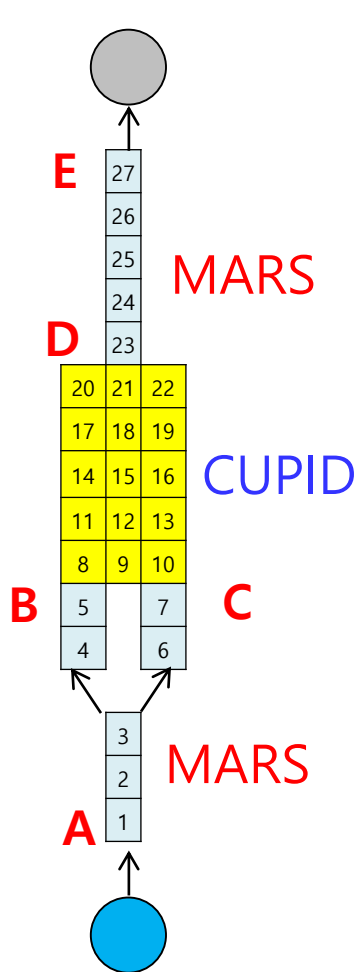


Two Channel

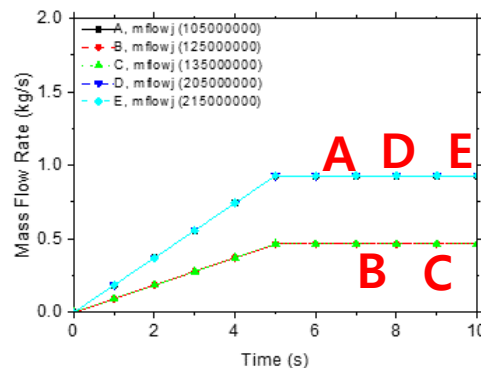
Two Channel
with P.B.Merged
Cell

Verification of Implicit Flow Coupling (2/3)

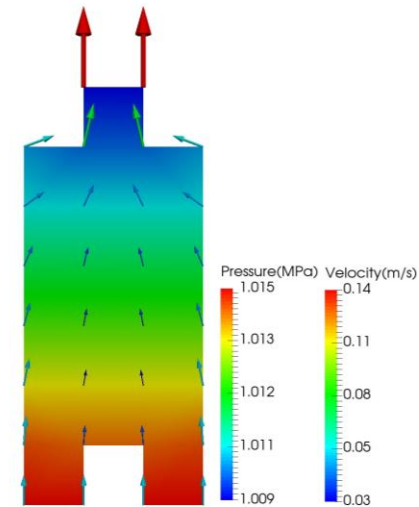
» Two-Channel Coupling Example



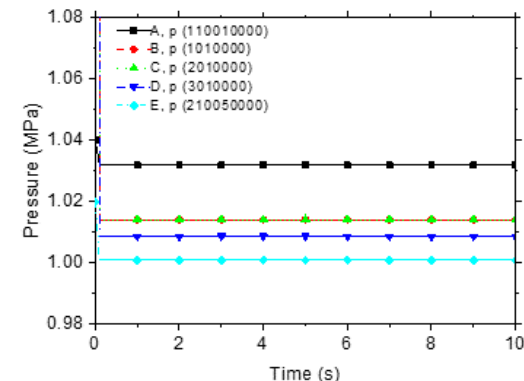
Calculation Mesh



Mass flow rate at A,B,C,D,E



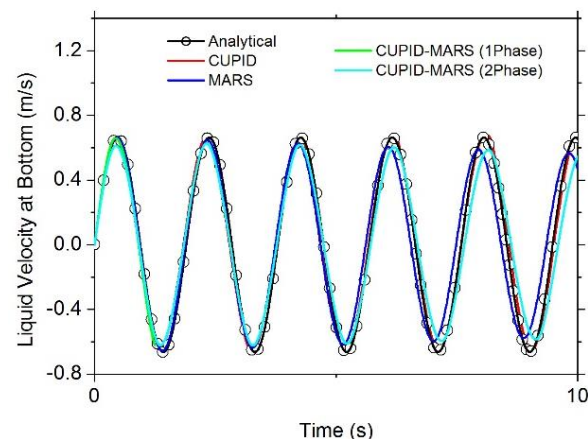
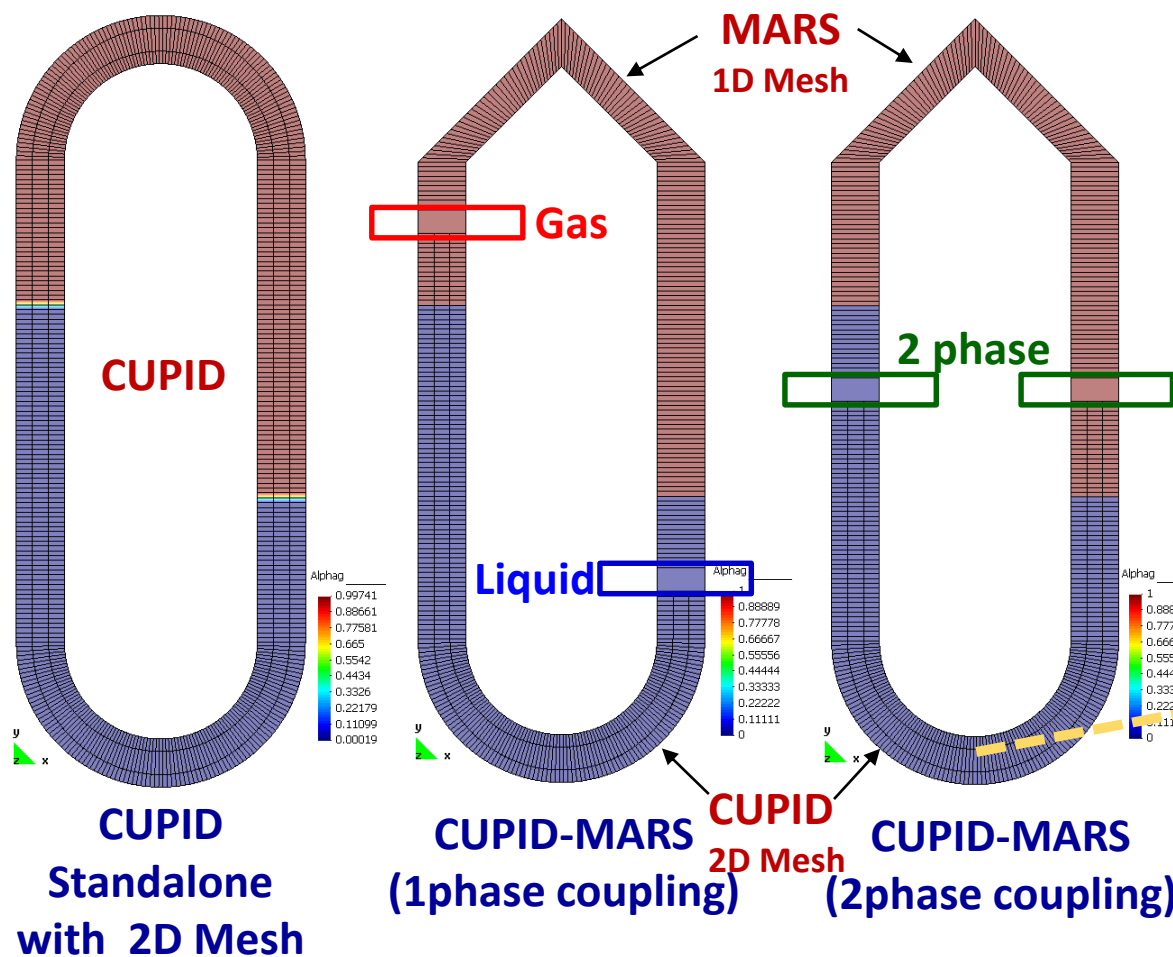
Pressure contour & Velocity vector



Pressure at A,B,C,D,E

Verification of Implicit Flow Coupling (3/3)

» Liquid Column Oscillations in O-tube



<Comparison of Liquid Velocities at the Tube Bottom>

Analytical Solution of Liquid Velocity

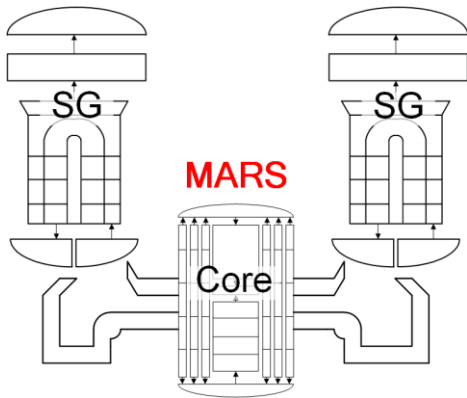
Nuclear Reactor Application

3

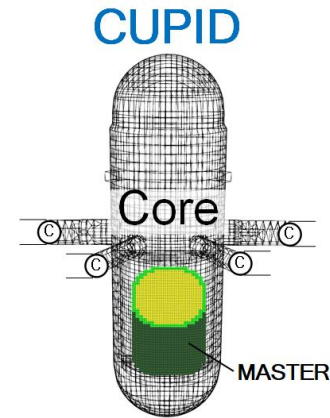
- Calculation Procedure for the Coupled Code
- Coupled Analysis of PWR MSLB



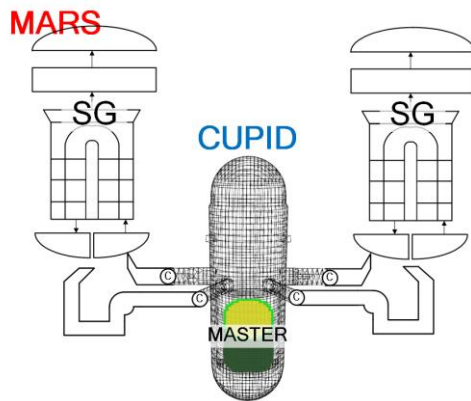
Calculation Procedure for the Coupled Code



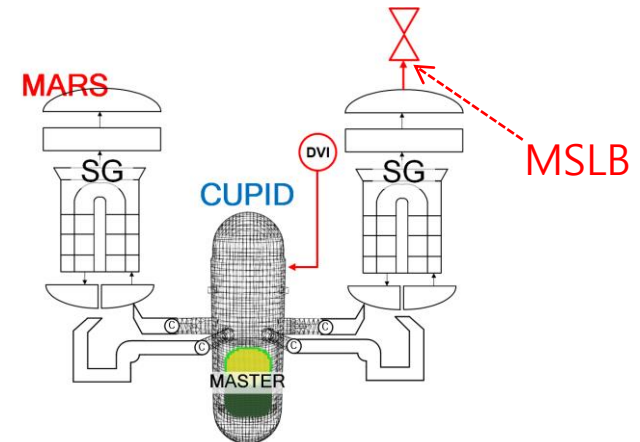
① 1D Reactor System *Steady*



② 3D RPV *Steady*



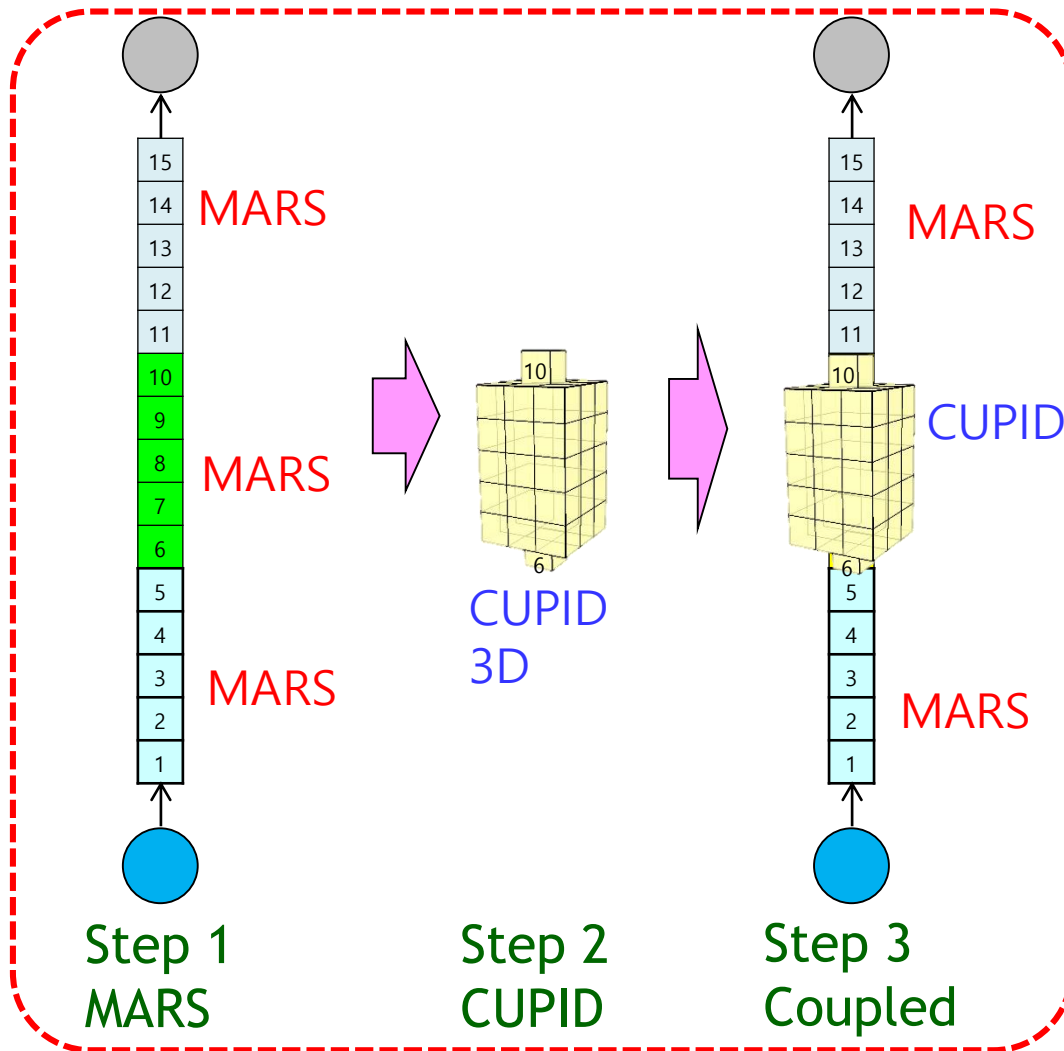
③ 1D/3D Coupled *Steady*



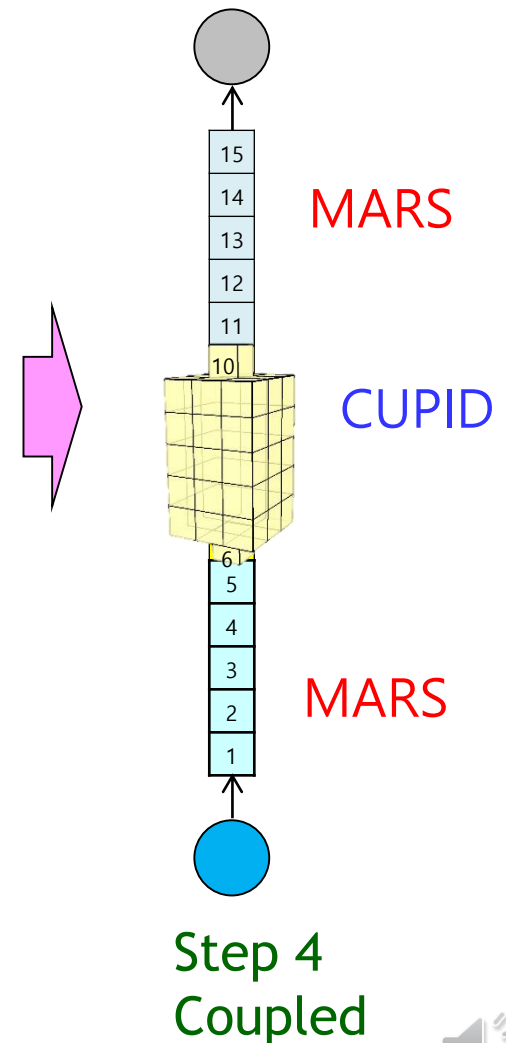
④ 1D/3D Coupled *Transient*

Verification of the Calculation Procedure (1/2)

Steady State



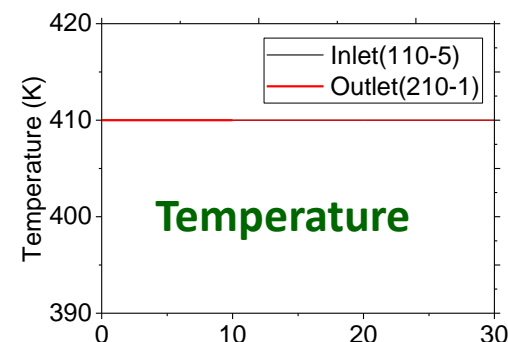
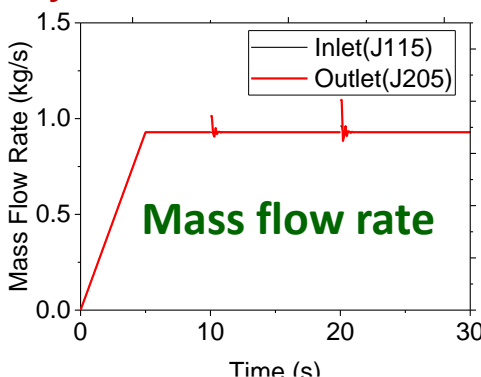
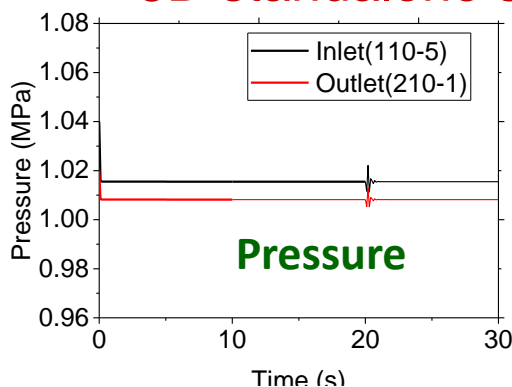
Transient



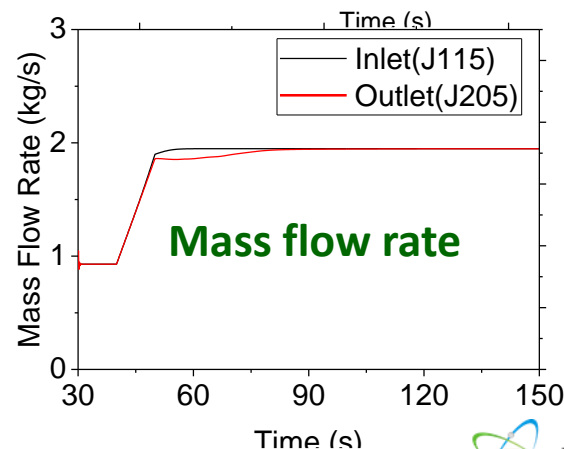
Verification of the Calculation Procedure (2/2)

» Calculation Results

- **Steady state calculations (Step 1,2,3: 10s,20s,30s) provide consistent pressure, mass flow rates, and temperatures.**
 - Coupled steady state can be achieved quickly by combining 1D and 3D standalone steady state.

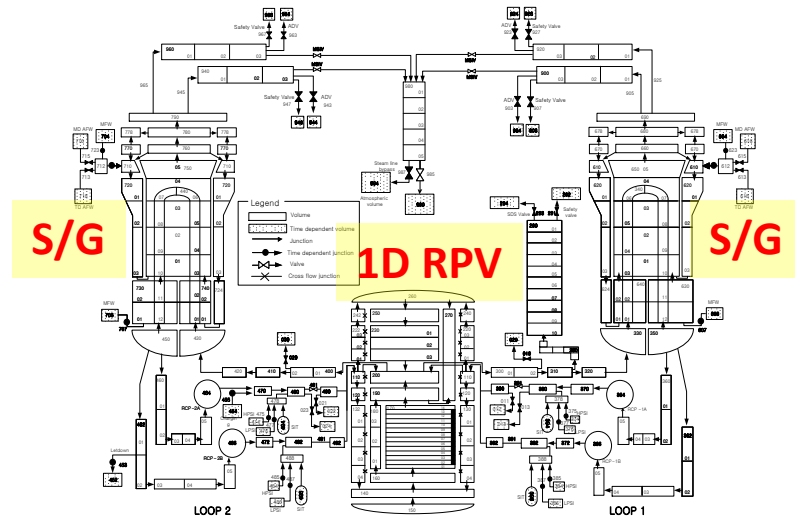


- **Transient calculation(Step 4) can be done using the coupled steady state.**
 - Nuclear safety analysis can be conducted with this suggested procedure.

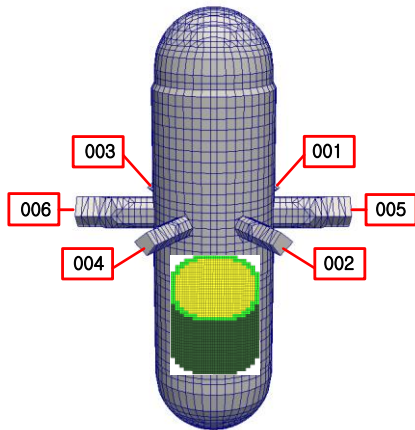


Coupled Analysis of PWR MSLB (1/2)

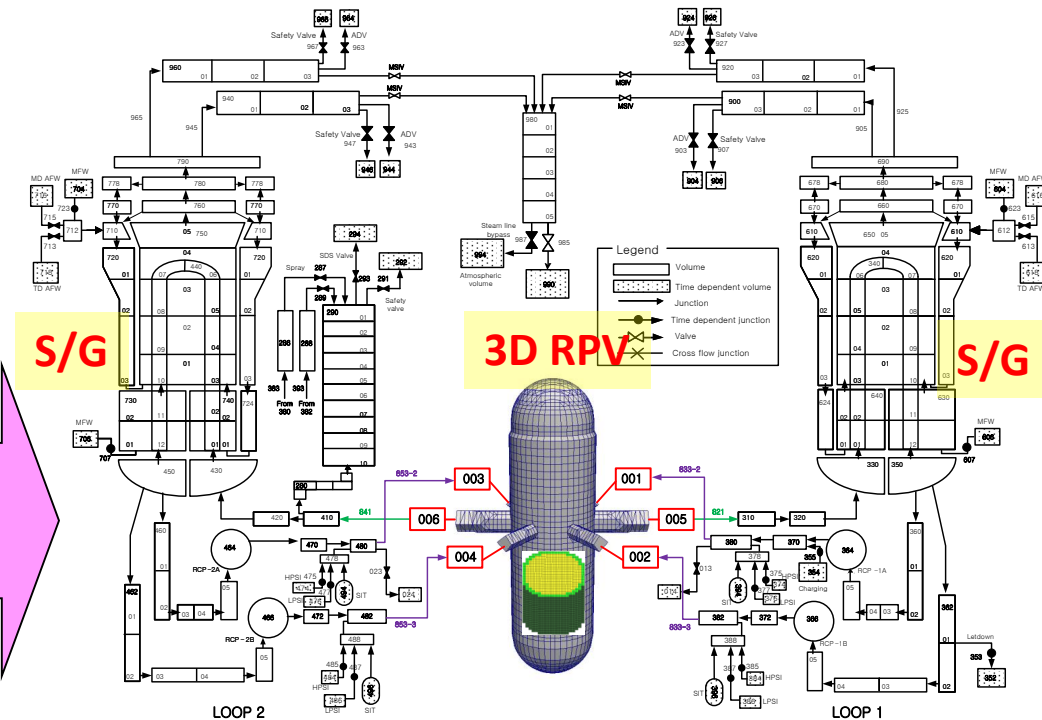
» Coupling of 1D and 3D meshes for the OPR1000 MSLB Accident Analysis



Step 1: 1D Mesh for Reactor System



Step 2: 3D Mesh for 3D RPV



Step 3,4: Multi-scale Mesh for a 1D/3D Coupled Reactor System

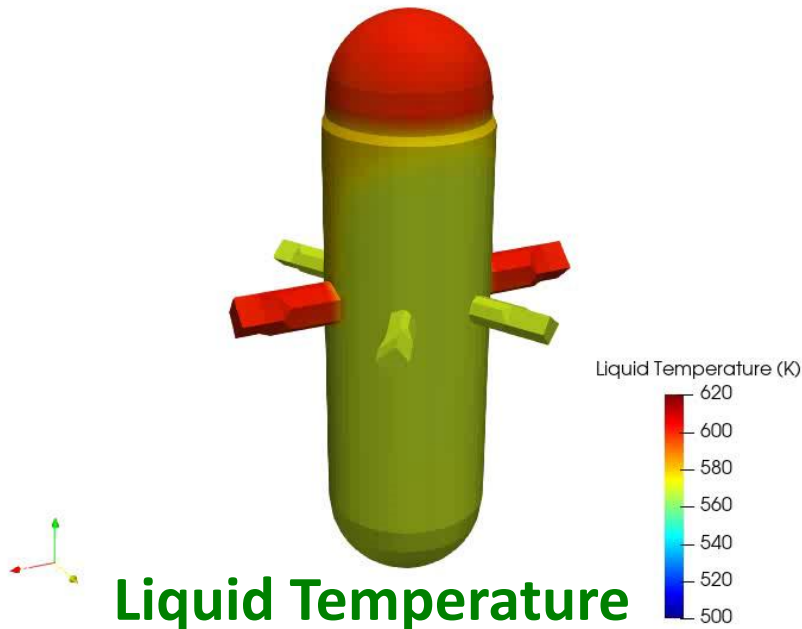
Coupled Analysis of PWR MSLB (2/2)

» Verification of Coupled Safety Analysis Method

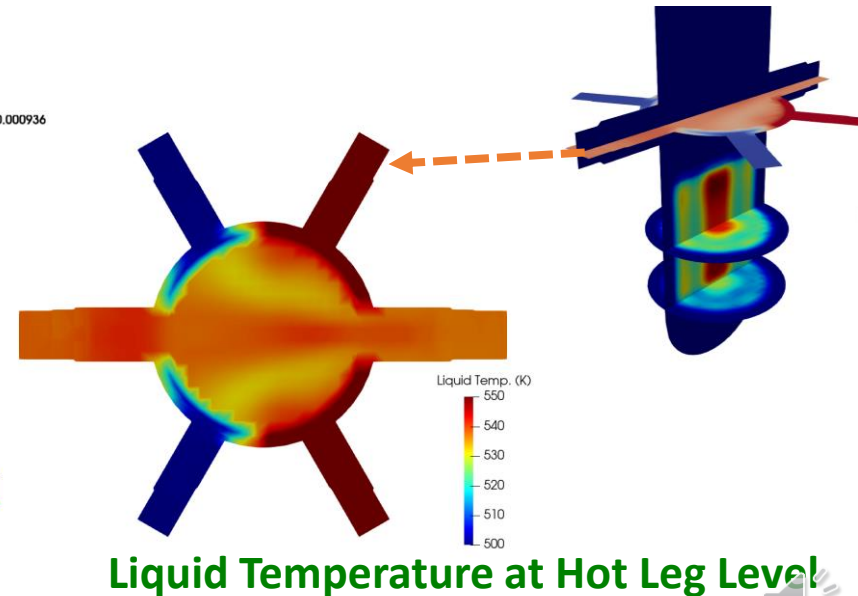
➤ Set up PWR MSLB calculation set in assembly-scale

- Confirm **the proper simulation of MSLB** including SLB major feature like asymmetric coolant temperature.
- **Computation times** is 3600s for 21055 cells, 8 cores, 100s transient.
- CUPID/MARS is **efficient and practical** enough for safety analysis.

Time: 0.000000



Time: 100.000936



Summary

4



Summary

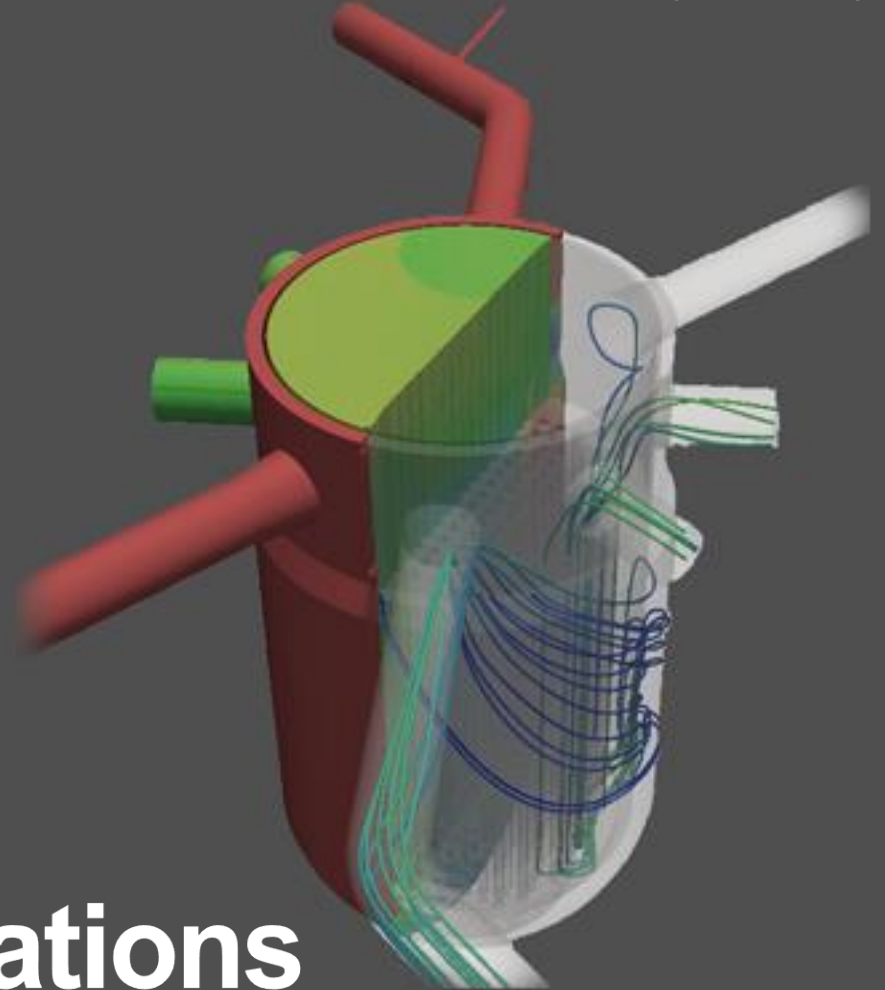
- » **Reactor system analysis code, MARS, is coupled with, 3D reactor vessel T/H code, CUPID-RV, implicitly in a single domain**
 - **No needs to transfer data and to iterate each solver**
 - **Fast and robust calculation of a transient**
- » **The coupled CUPID/MARS code was verified using the various types of mesh coupling**
 - **Arbitrary types of coupling interfaces are allowed**
- » **CUPID/MARS was successfully applied to the PWR MSLB accident analysis with a practical computation time**
 - **Calculation time of CUPID/MARS was 3600 s at the assembly-scale (21055 cells, 8 cores, 100s transient)**



THANK YOU

gosu@kaeri.re.kr





CUPID Workshop

CFD Scale Applications

Yun-Je Cho
March 04, 2022

CUPID Workshop

CONTENTS

- ▶ 01 INTERNATIONAL CFD BENCHMARK
- ▶ 02 OECD/NEA IBE-4 (GEMIX)
- ▶ 03 IAEA CRP (ROCOM)
- ▶ 04 OECD/NEA (HYMERES-2)
- ▶ 05 DEBORA Benchmark
- ▶ 06 SUMMARY

International CFD Benchmark

1

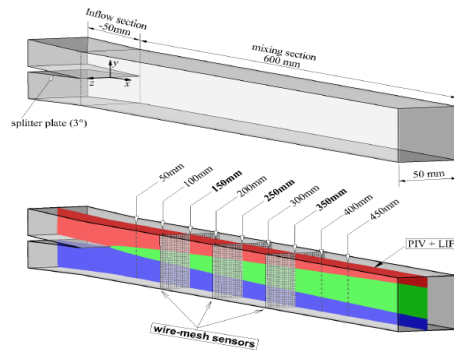
- CFD Applications using CUPID
- International Benchmark



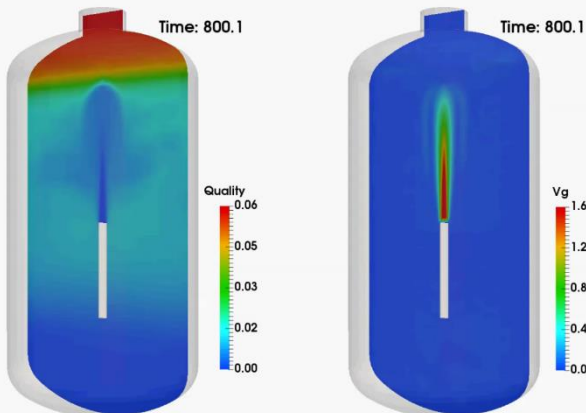
Introduction

» CFD-Scale Applications using CUPID

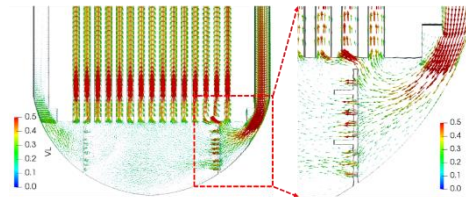
CFD Scale: Downcomer, Lower Plenum, Etc.



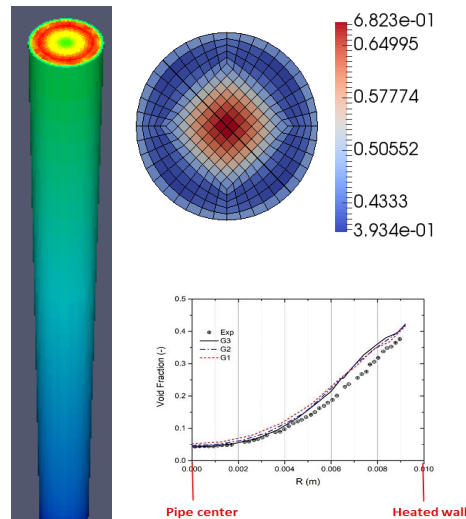
<OECD/NEA IBE: GEMIX>



< OECD/NEA HYMERES-2>



<IAEA CRP: ROCOM_12>



<DEBORa Benchmark>

OECD/NEA IBE-4 (GEMIX)

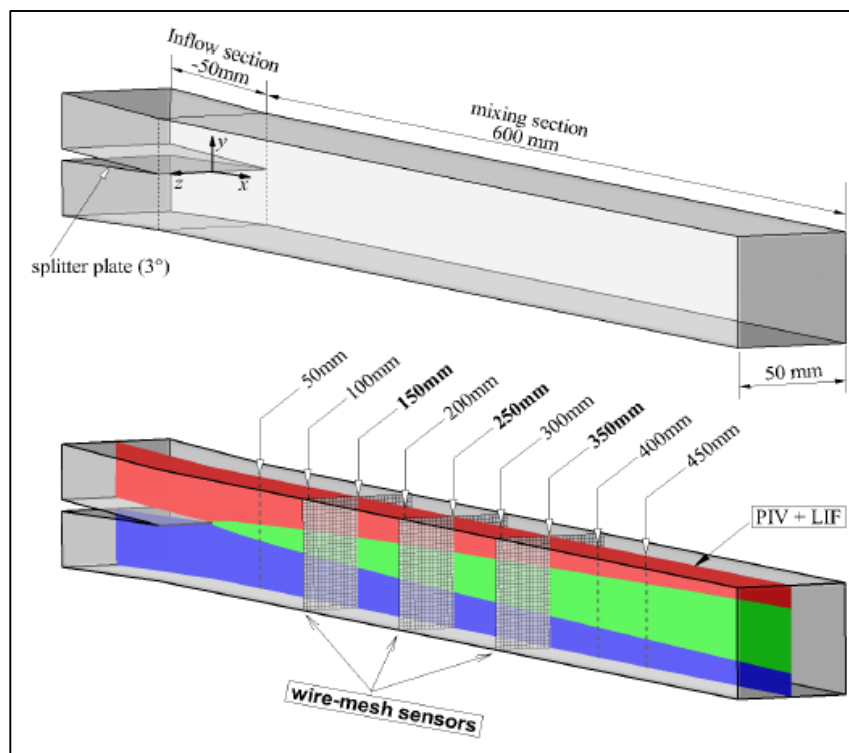
2

- IBE-4 GEMIX
- Calculation Results
- Synthesis Report



OECD/NEA Benchmark (1/3)

» IBE-4: GEMIX (2016)



Inlet velocity	0.6 m/s	1.0 m/s
Global Re	30000	50000
$\Delta\rho=0\%$, $\Delta T=0K$	N339	N337
$\Delta\rho=1\%$, $\Delta T=5K$	N320	N318
	Open	Blind

13 submissions

CFD-CODE

ANSYS (CFX)	3
ANSYS (FLUENT)	2
STAR-CCM	2
Code_Saturne	2
CUPID	1
TrioCFD	1
P2REMICS	1
OpenFOAM	1

TURBULENCE MODEL

k-eps	7	CUPID
k-omega	4	
LES	2	
RSM	1	

Number of grid

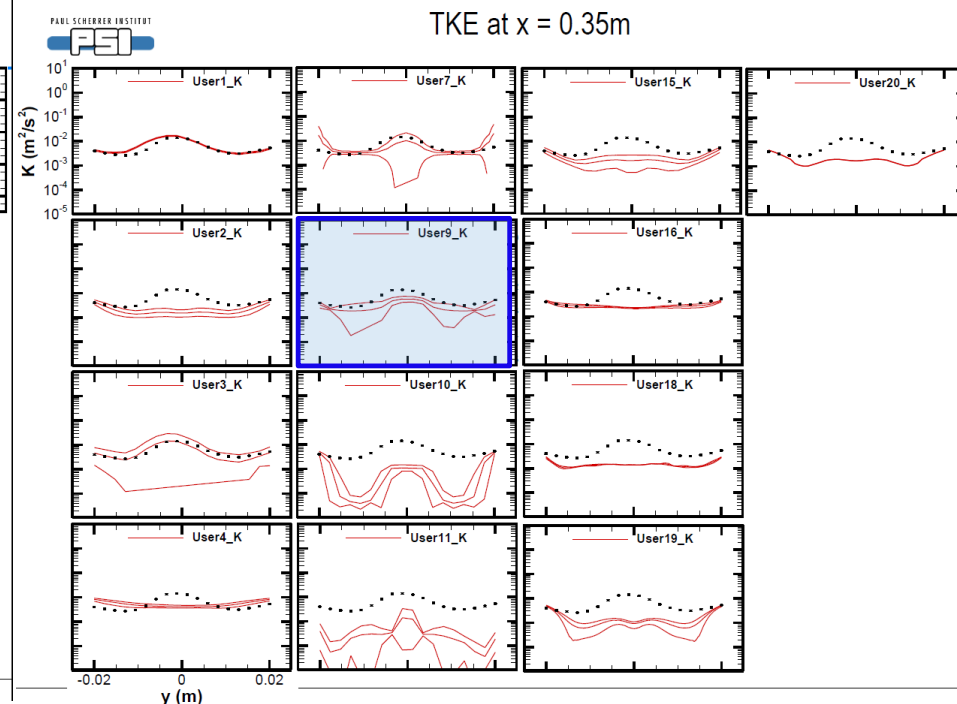
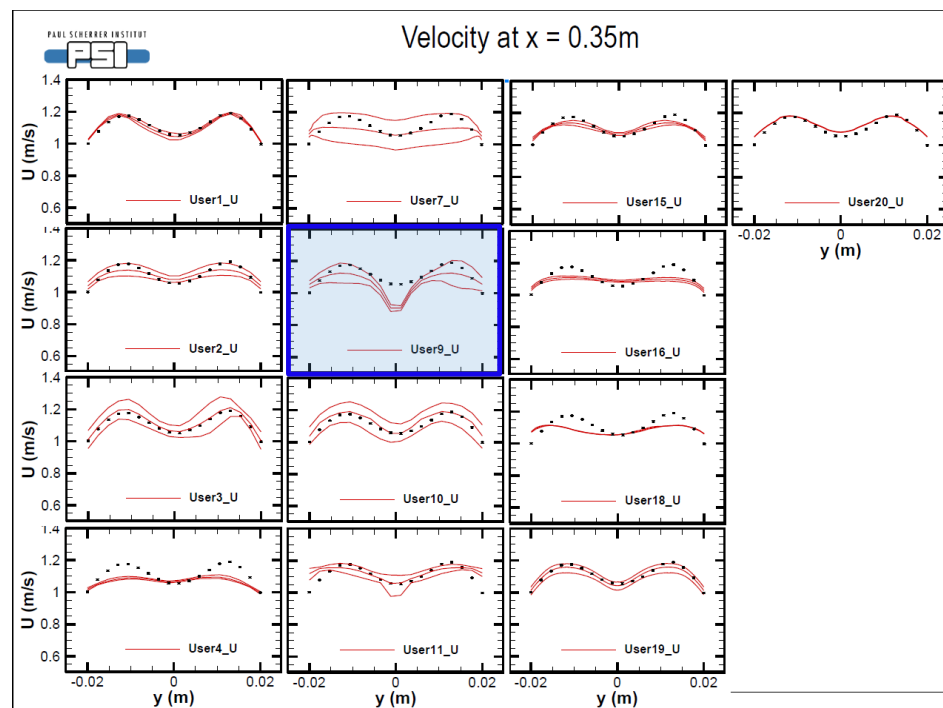
59850 (2D)	← minimum
CUPID	
156260	
300000	
20644596	← maximum
3696000	
5753458	
3596992	
675168	
712704	
62418 (2D)	
1637784	
652320	
813276	

OECD/NEA Benchmark (2/3)

» Calculation Results

➤ Velocity

➤ Turbulent kinetic energy



OECD/NEA Benchmark (3/3)

» Final Result

➤ Thickness of mixing layer

user	FoM	Ranking
1	0.031418	2
2	0.186935	7
3	0.02999	1
4	0.476981	13
CUPID 7	0.156025	6
9	0.09458	5
10	0.069638	4
11	0.274574	11
15	0.203641	8
16	0.215331	10
18	0.294725	12
19	0.033593	3
20	0.213123	9

➤ Turbulent kinetic energy

user	FoM	Ranking
1	3.867411	2
2	6.002381	6
3	3.463244	1
4	6.352827	7
CUPID 7	4.662649	4
9	4.86622	5
10	11.21324	12
11	12.31548	13
15	6.523958	8
16	4.401786	3
18	10.81458	11
19	7.109226	9
20	9.406994	10

IAEA CRP (ROCOM)

3

- IAEA CRP
- ROCOM Test
- Computational Setup
- Computational Mesh
- Calculation Results



» Coordinate Research Project (CRP)

➤ Title: Application of Computational Fluid Dynamics Codes for Nuclear Power Plant Design

- Purpose: to address the application of CFD computer codes to optimize the design of water cooled nuclear power plants
- Period: February 2013 ~ October 2019
- **16 participants** : Canada/CNL, China/Jiao Tong University, France/CEA Grenoble, France/AREVA, France/EDF, Germany/HZDR, India/BARC, Italy/University of Pisa, Republic of **Korea/KAERI**, Russian Federation/GIDROPRESS, Russian Federation/VNIIAES, Switzerland/Goldsmith Transactions, USA/MIT, USA/Texas A&M University, Algeria/CNRB, and USA/Westinghouse
- Four **Benchmark problems**: Boron Dilution, PTS, two rod bundle tests

Description of ROCOM (1/2)

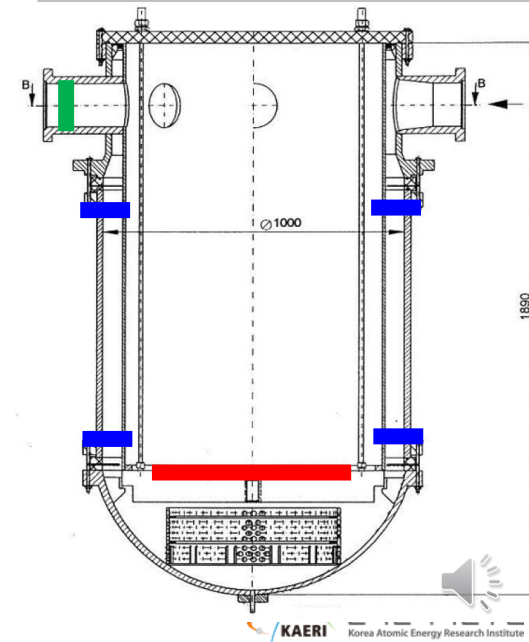
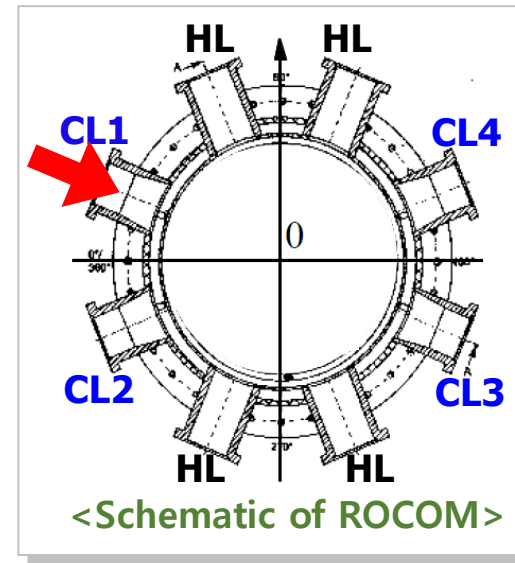
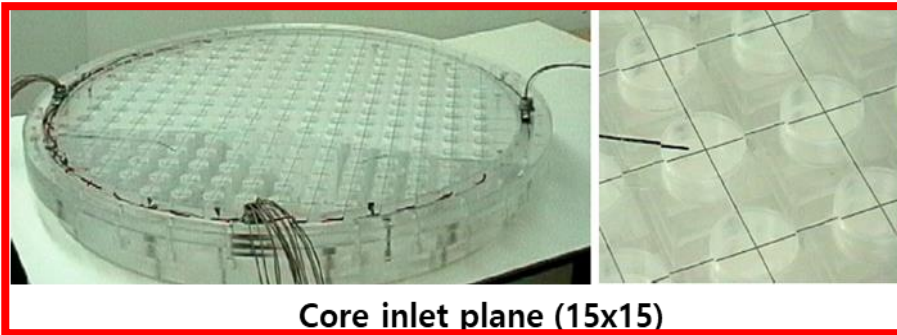
» ROCOM_12 Test (HZDR)

➤ Slug Mixing Experiments

- Prototype: German KONVOI reactor
- To simulate 'Boron dilution transients'
- Injection of water from one cold leg

Ramp length	Volumetric flow rate	Slug volume (salted water)
14 s	185.0 m ³ /h	8.0 m ³

- Wire mesh sensor: conductivity change



Model and Numerical Setup

» Turbulence Models

- Standard k- ε model & Low Reynolds number model
- RNG k- ε model & Realizable k- ε model
- SST k- ω model

» Boron Transport Equation

$$\frac{\partial}{\partial t}[(1 - \alpha_g)\rho_l C_B] + \nabla \cdot (\alpha_l \rho_l C_B \vec{u}_l) + \nabla \cdot (\alpha_d \rho_l C_B \vec{u}_d) = 0$$

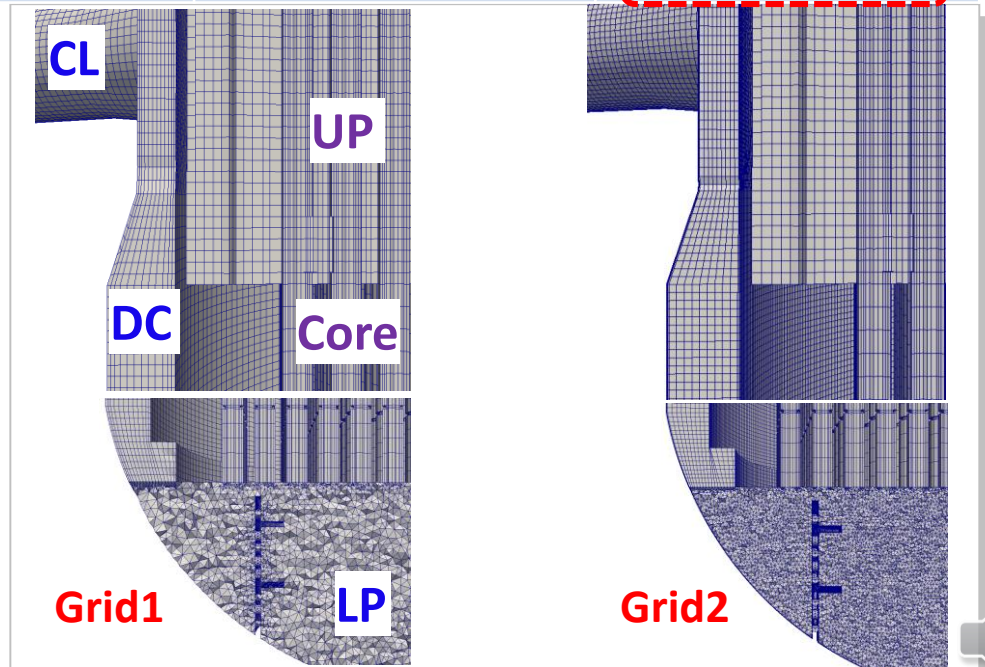
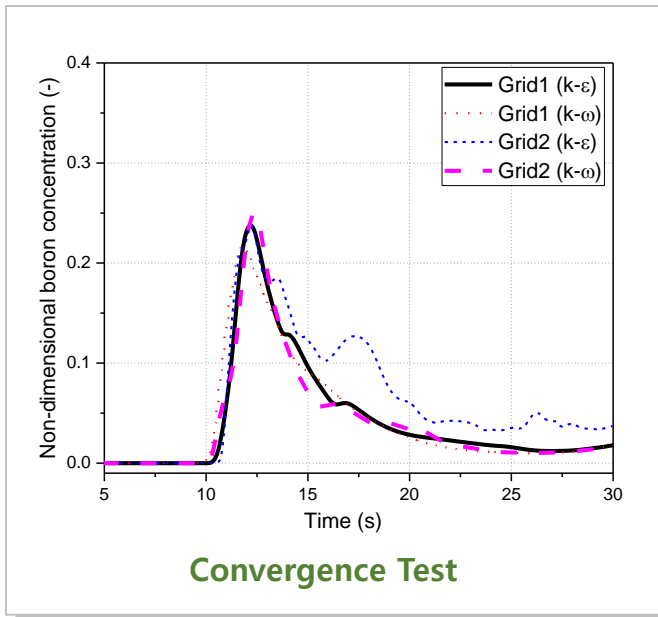
» Baseline Calculation Case

Baseline case	Setup
Mesh	Reference grid
Turbulent model	Standard k- ε model
Convection scheme	2 nd order upwind
Solution Scheme	Implicit SMAC scheme

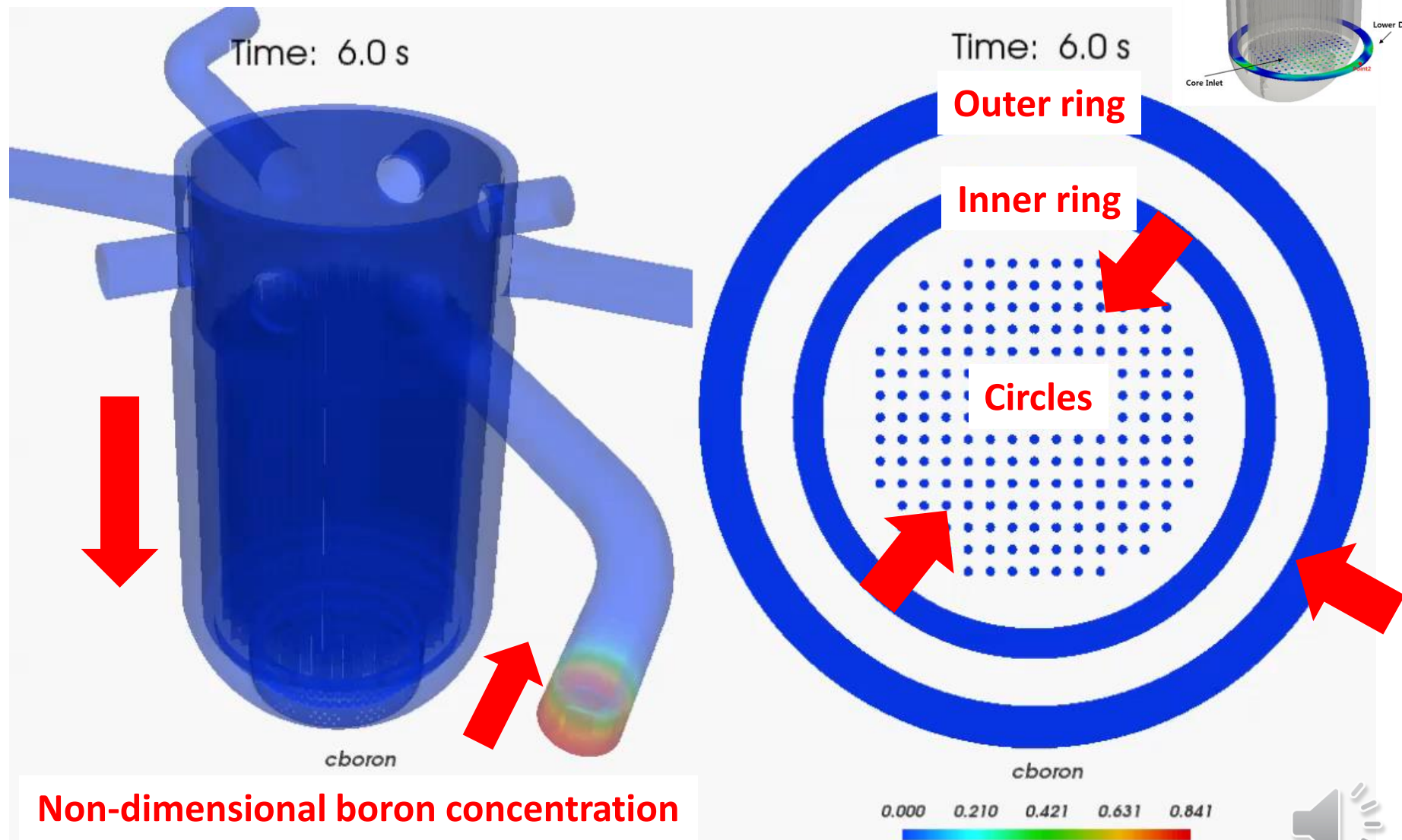
Mesh Sensitivity Test

» Additional Grids for Sensitivity Test

Grid	Core+UP	CL+DC+LP	Y^+
Coarse	2.2M	1.15M	$Y^+ > 300$
Grid1		2.45M	$30 < Y^+ < 300$
Grid2		10.21M	$Y^+ < 5$

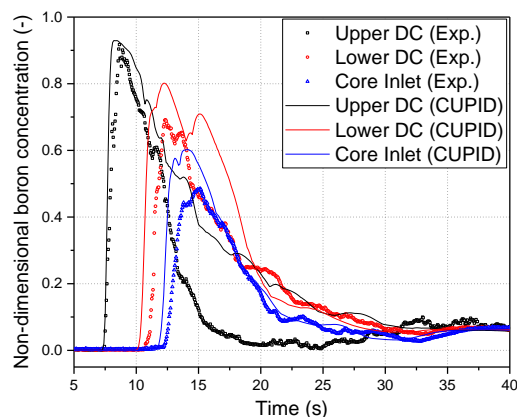
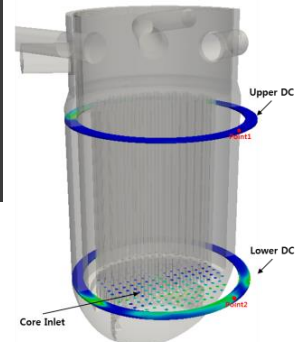


Overall Mixing Behavior

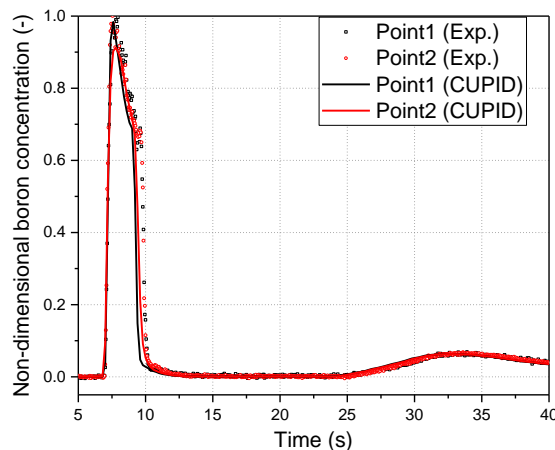


Quantitative Comparisons

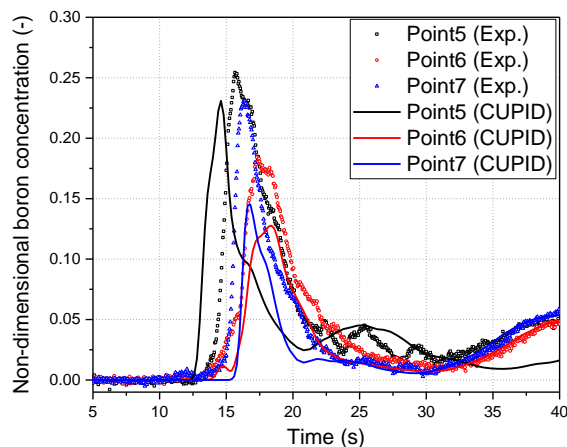
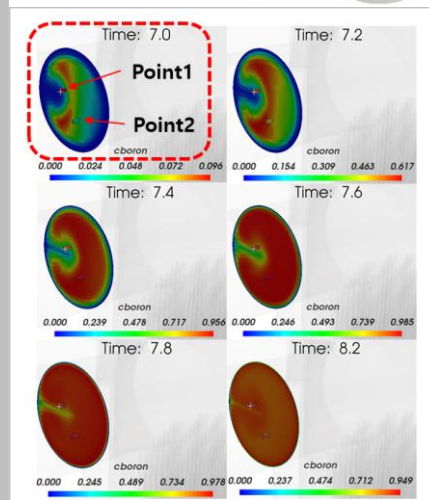
» Averaged & Local concentration



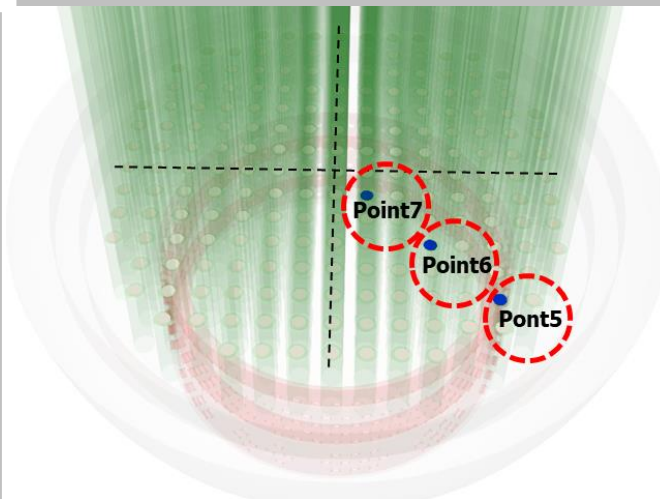
Maximum concentration at upper DC, Lower DC, Core inlet



Local concentration at cold leg



Local concentration at core inlet



Synthesis Report (1/2)

» IAEA CRP: Boron dilution benchmark

- Competition with **CFX**, **Star-CCM+**, and **OpenFOAM**
- Use of different models and meshes
- Prediction of hydraulic resistance of perforated drum and turbulence mixing in downcomer

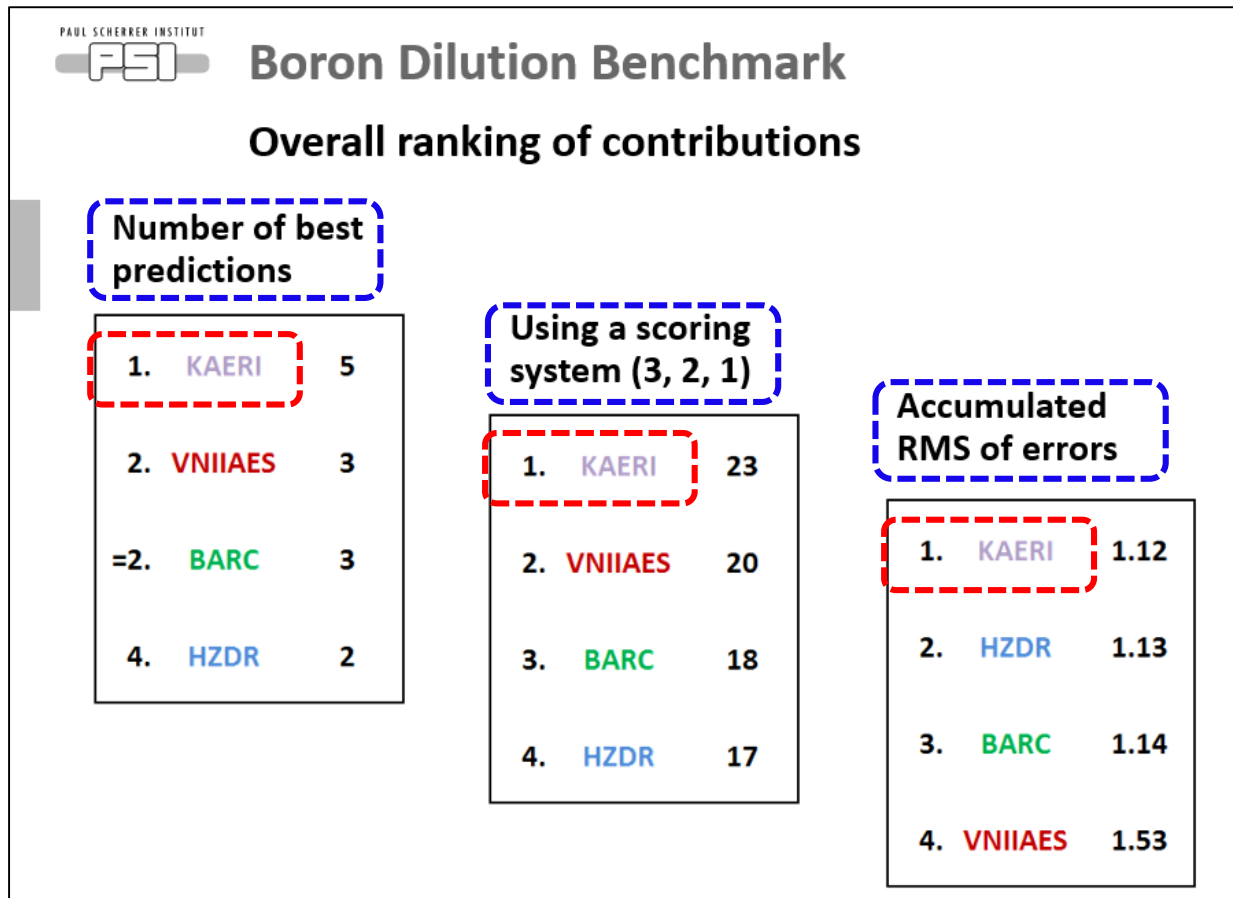
Participant	Code	Turbulence model	Mesh
HZDR	CFX 18	SST	6.5 M mixed cells
VNIIAES	Star-CCM+	Realizable k-ε with two layer wall model	Unknown number of mixed cells
BARC	OpenFOAM	One equation LES with delta cube root	8 M or 19 M of mixed cells
KAERI	CUPID 2.0	k-ε with Chen's low-Re number model	4.6 M mixed cells

Synthesis Report (N. Boyan, PSI)

Synthesis Report (2/2)

» IAEA CRP: Boron dilution benchmark

- The first place in three of ranking system



Synthesis Report (N. Boyan, PSI)

OECD/NEA HYMERES-2

4

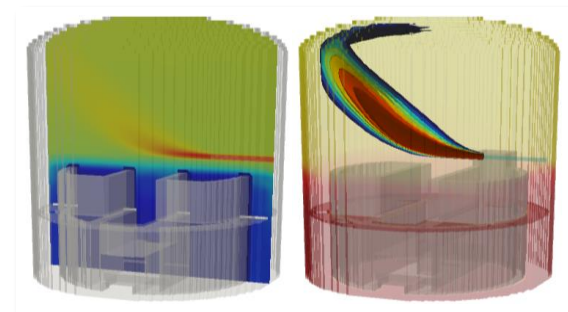
- HYMERES-2 Project
- PANDA Test
- Computational Setup
- Calculation Results



Overview of HYMERES-2

» HYMERES-2

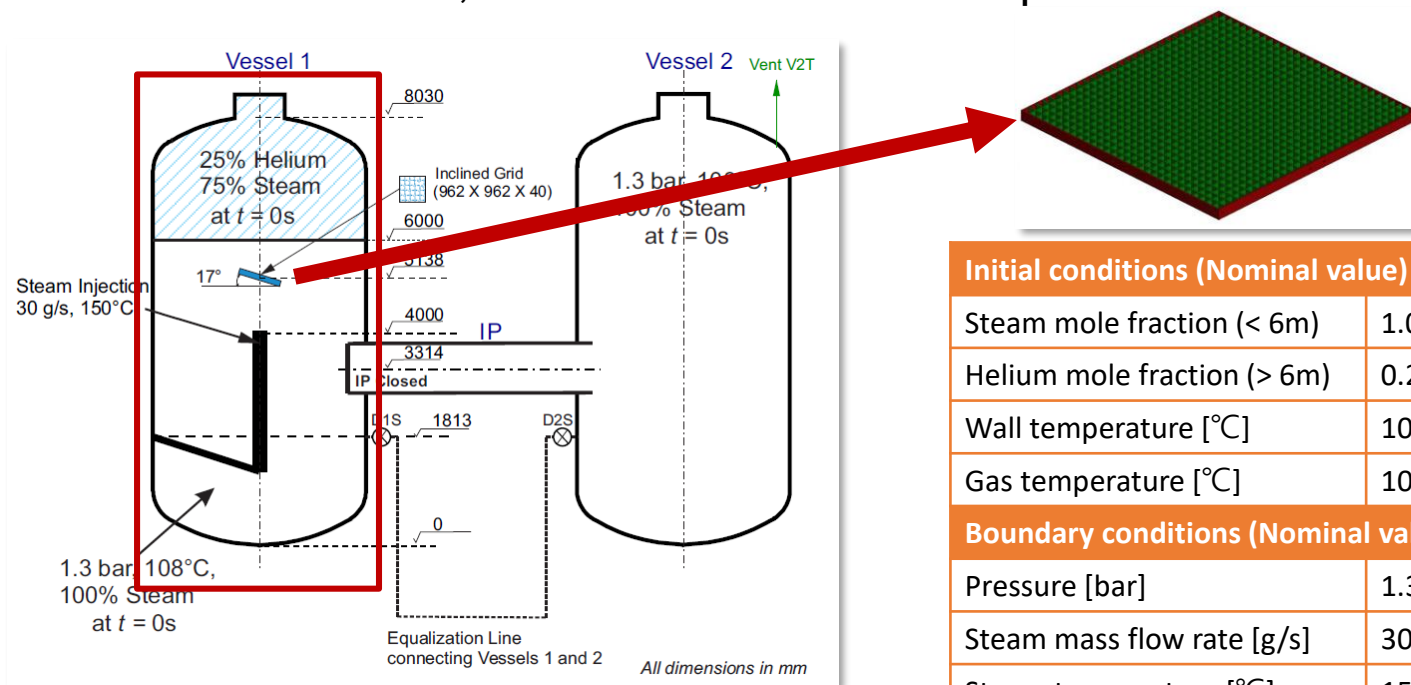
- **HYMERES-2 : 2017.01 – 2021.06 (HYMERES : 2013 - 2016)**
- **Main objective**
 - To improve the understanding of the **containment** phenomenology during postulated severe accident with **release and distribution of hydrogen**
- **Main topics of HYMERES-2**
 - **Erosion of helium layer by steam jet/plume interacting with various obstruction geometries**
 - Thermal radiation effects
 - Suppression pressure pool and BWR systems
 - Performance of safety components
- **Experimental Data**
 - PANDA tests (PSI, Switzerland)
 - Open cases, **1 blind benchmark case**



Description of PANDA Test

» Blind Benchmark (H2P1_10)

- Given initial and boundary conditions **without test results**
- Erosion of **helium stratification** by vertically injected **steam jet**
- **Flow obstruction (grid-shape)** blocked the steam jet.
 - Inclined grid : 0.962m x 0.962m x 0.04m,
 - Installed at 5.138m, inclined 17° to horizontal plane



<Test configuration and nominal conditions>

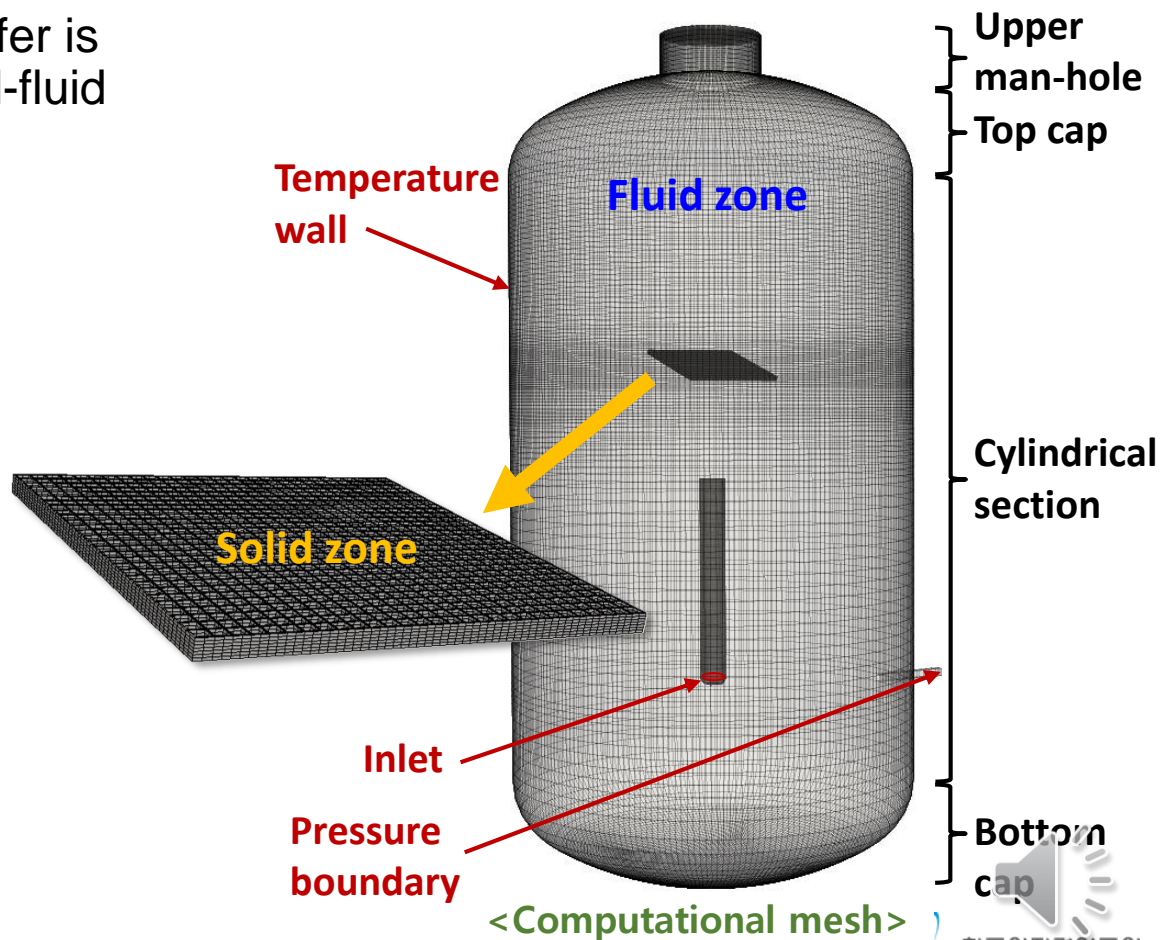
Computational Mesh

» Configuration

- 3-D geometry of the vessel
- Flow obstruction : solid zone
 - Conjugated heat transfer is considered at the solid-fluid interface.

» Computational mesh

- Hexahedron mesh
- 2.4M cells
 - Fluid zone : 2,290,376
 - Solid zone : 94,192



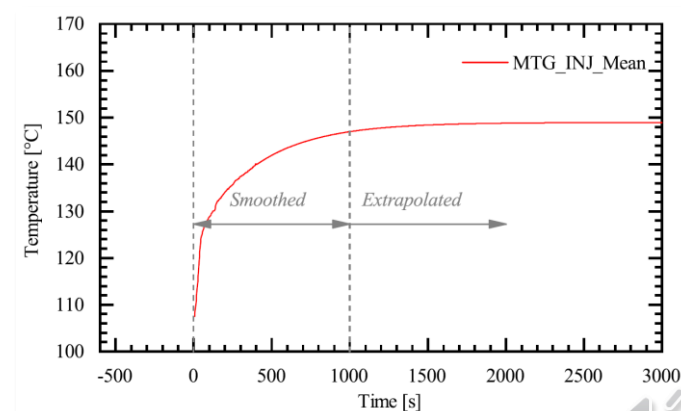
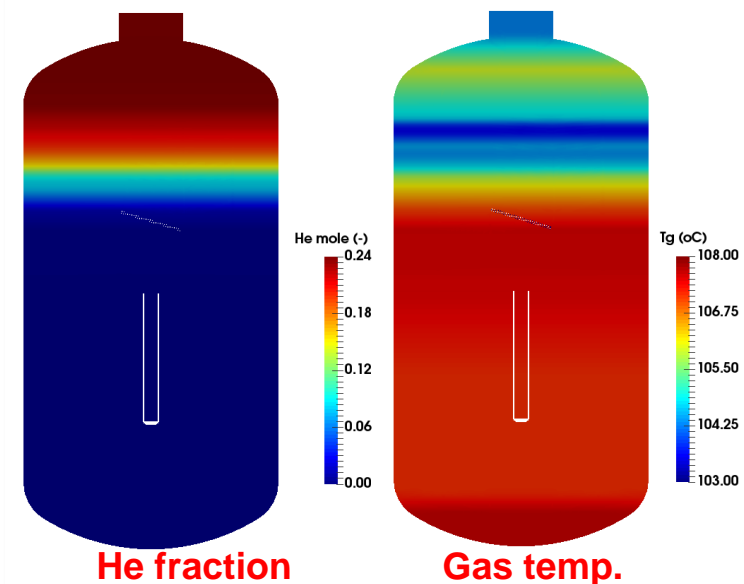
Initial & Boundary Conditions

» Initial Condition

- Helium concentration : Experimental data along the height at central axis
- Gas temperature: Experimental data along the height at central axis

» Boundary Conditions

- Inlet boundary
 - Experimental data suggested as calculation requirements
 - Temperature of injected steam is increased 108°C to 150°C during 1000s
- Wall boundary
 - Followed calculation requirements
 - Lid : constant at 101°C
 - Cylindrical wall : decreasing as $\sim 0.12\text{K}/100\text{s}$



<Steam injection temperature>

Physical Models

» Turbulence Model

- **Standard k - ε model** with standard wall function
- **Turbulence buoyancy effect is considered by adding buoyancy production term to source term of k and ε equation.**

$$G_k = -\vec{g} \frac{\mu_t}{\rho Pr_t} \nabla \rho : \text{buoyancy term for } k$$

$$G_\varepsilon = \frac{\varepsilon}{k} C_{\varepsilon 1} C_{\varepsilon 3} G_k : \text{buoyancy term for } \varepsilon$$

» Radiative Heat Transfer

- **P-1 model is applied.**

- Transport equation of incident radiation (G)

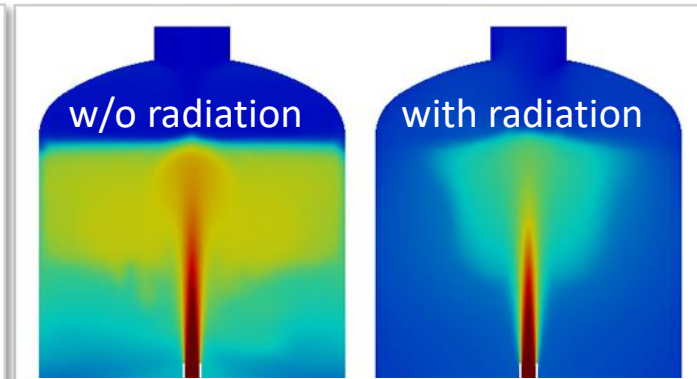
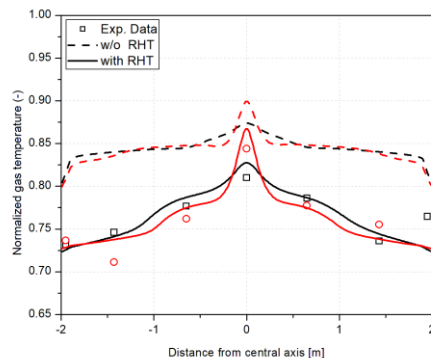
$$\nabla \cdot \left(\frac{1}{3(\kappa + \sigma_s) - A_1 \sigma_s} \nabla G \right) - \kappa G + 4\kappa \sigma T^4 = 0$$

- Radiative heat flux

$$\vec{q}_{rad} = -\frac{1}{3(\kappa + \sigma_s) - A_1 \sigma_s} \nabla G$$

$$\vec{q}_{rad, wall} = \frac{\varepsilon_w}{2(2 - \varepsilon_w)} (4\sigma T_w^4 - G_w)$$

$$S_{rad} = -\nabla \cdot \vec{q}_{rad} \quad \leftarrow \text{added to source term of gas-phase energy conservation equation}$$

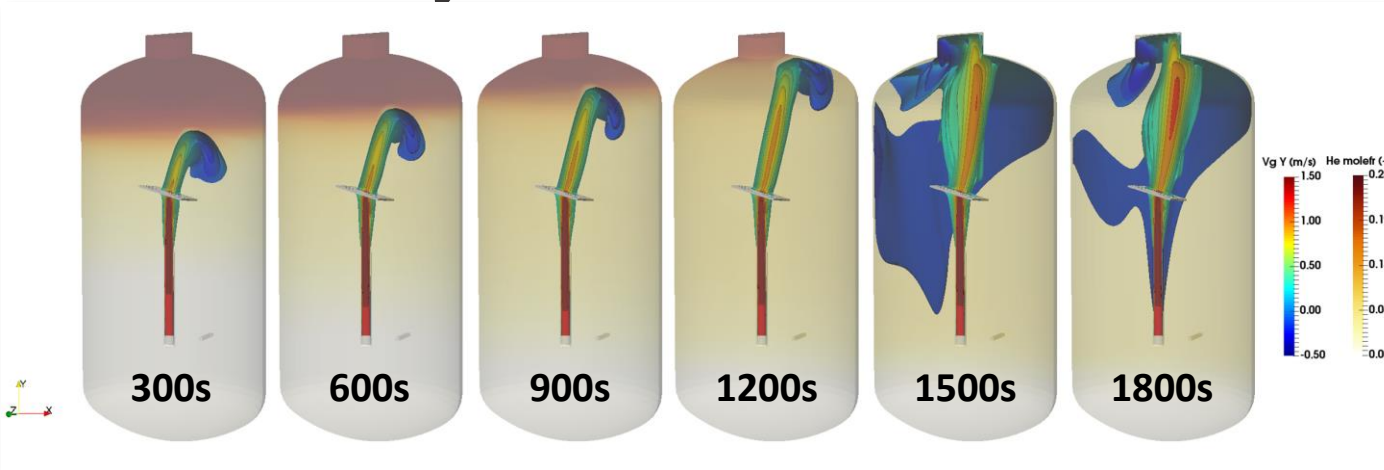


<Comparison of results with and without RHT model>

- * Left : Gas temperature profiles
- * Right : Distribution of gas temperature

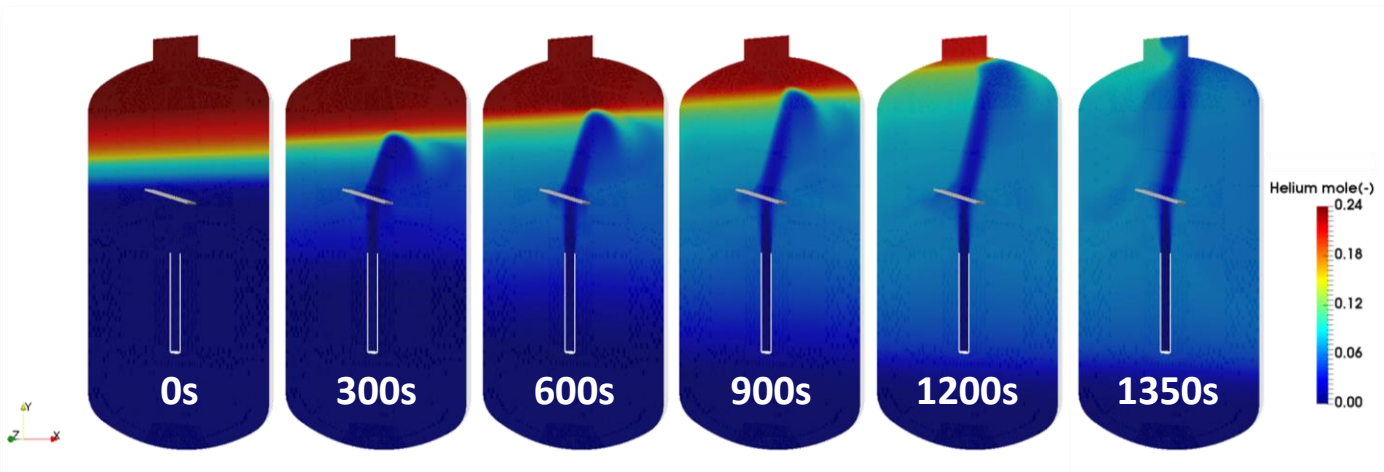
Overall Behavior

» Gas velocity



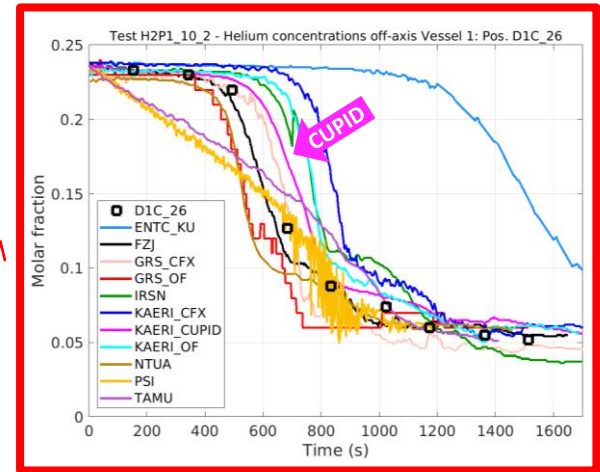
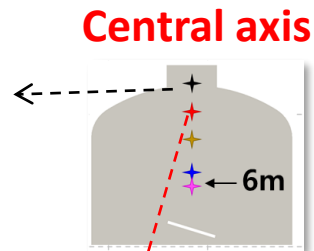
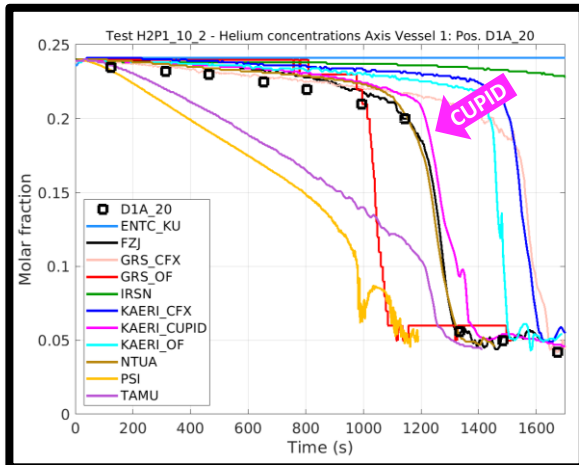
- The jet is inclined to the right in the figure due to the flow obstruction.
- As the jet rises, the stratified helium is gradually eroded.
- After the jet reached the top wall of the vessel, helium was distributed almost uniformly inside the vessel.

» Helium concentration

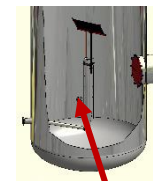
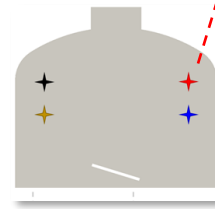


Helium Concentration

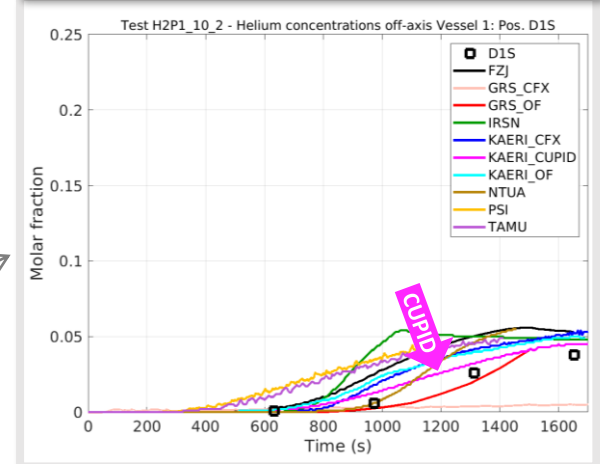
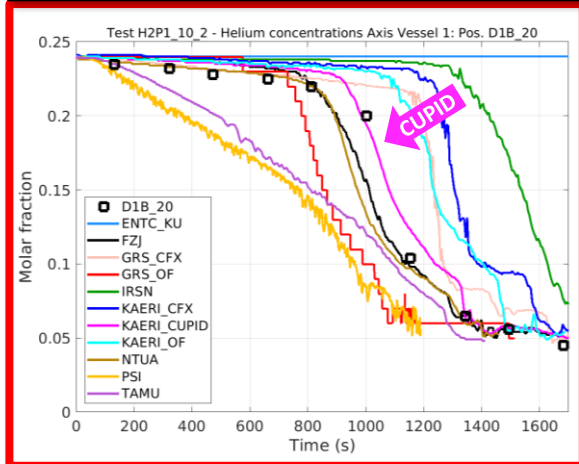
» Evolution of helium concentration over time



Off axis



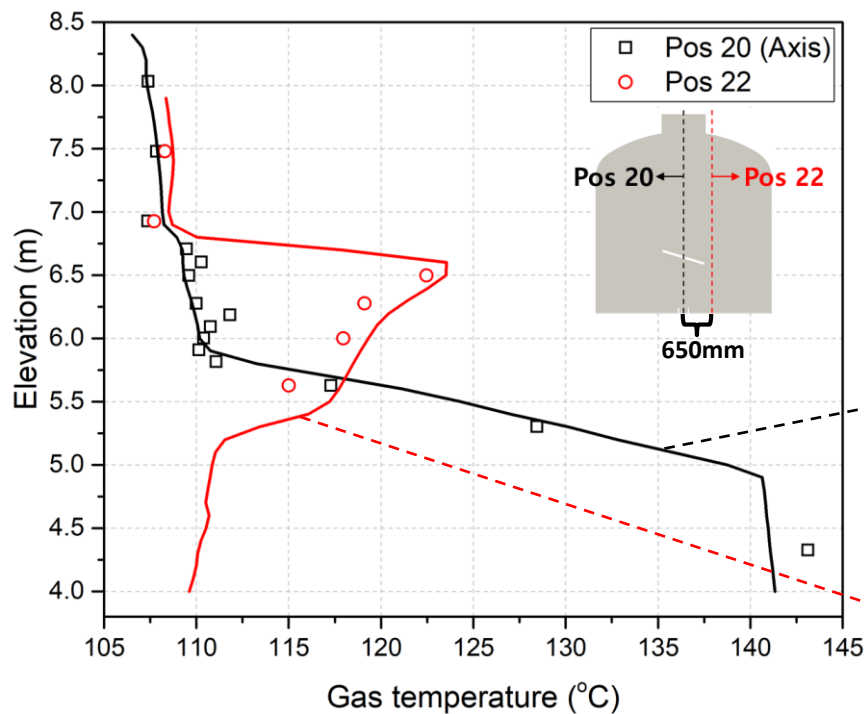
Equalisation line



- CUPID predicted fairly well the experimental data in which the helium stratification was completely eroded at 1300 s.
- Overall calculation results of CUPID were excellent among the other results.

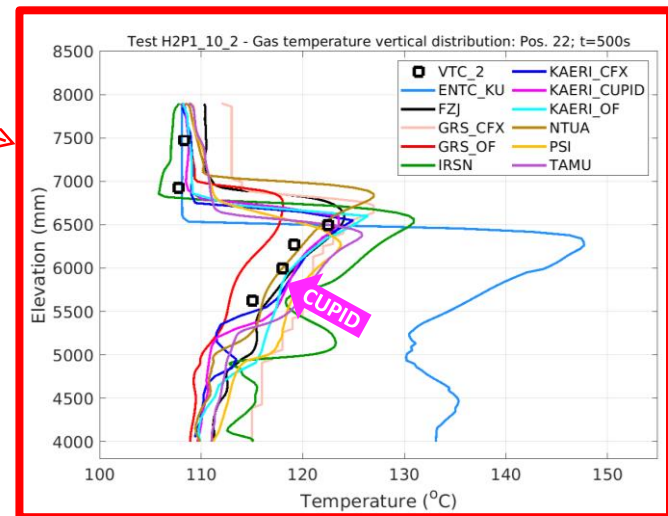
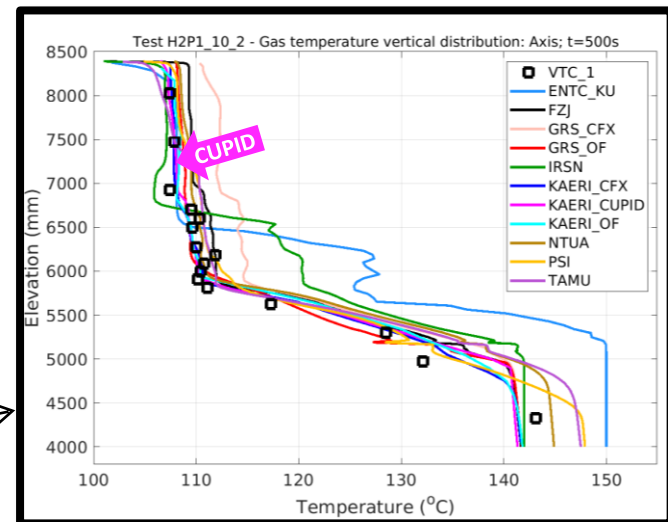
Gas Temperature

» Distribution of gas temperature at specific time



Vertical temperature profiles (500s)

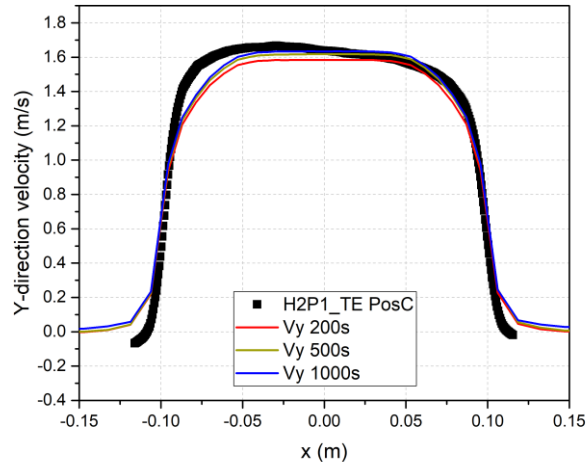
- The distribution of gas temperature in vertical direction agreed well with the experimental data.



Velocity Profile

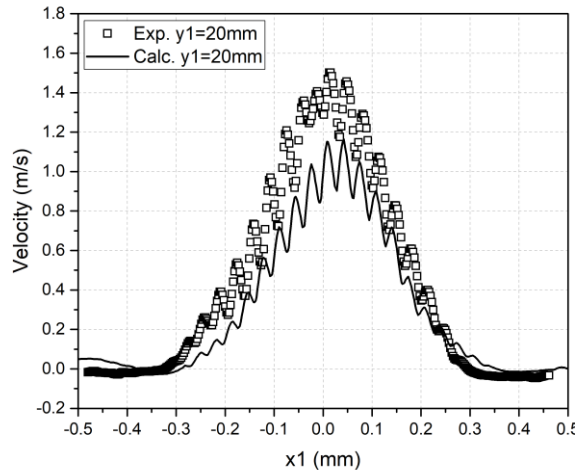
» Distribution of Y-direction velocity at specific time

At Injection Pipe Exit

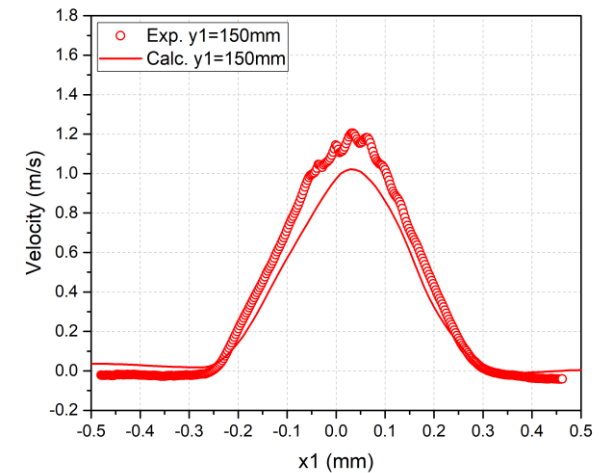


<Time at 200s, 500s, 1000s>

At PIV Area



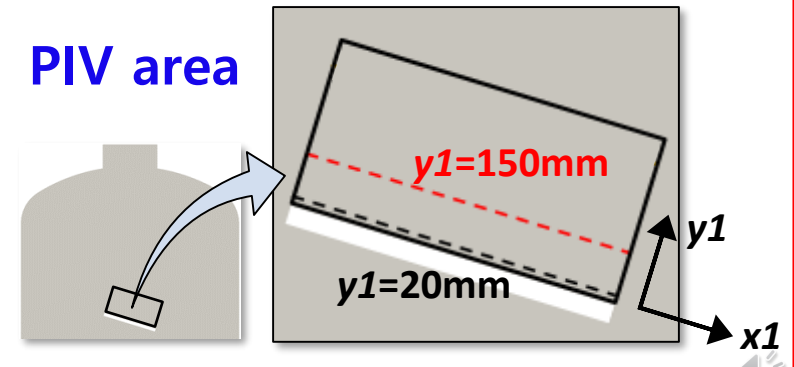
<Time at 846s, $y1=20\text{mm}$ >



<Time at 846s, $y1=150\text{mm}$ >

- Y-direction velocity at exit of injection pipe was calculated symmetrically and good agreement with experimental data.
- The velocity profile at $y1=20\text{mm}$, well reproduced the jagged shape.

PIV area



DEBORA BENCHMARK (CEA)

5

- Organization and Objectives
- Description of DEBORA Experiment
- Physical Models
- Calculation Results



Organization and Objectives

» DEBORA Benchmark

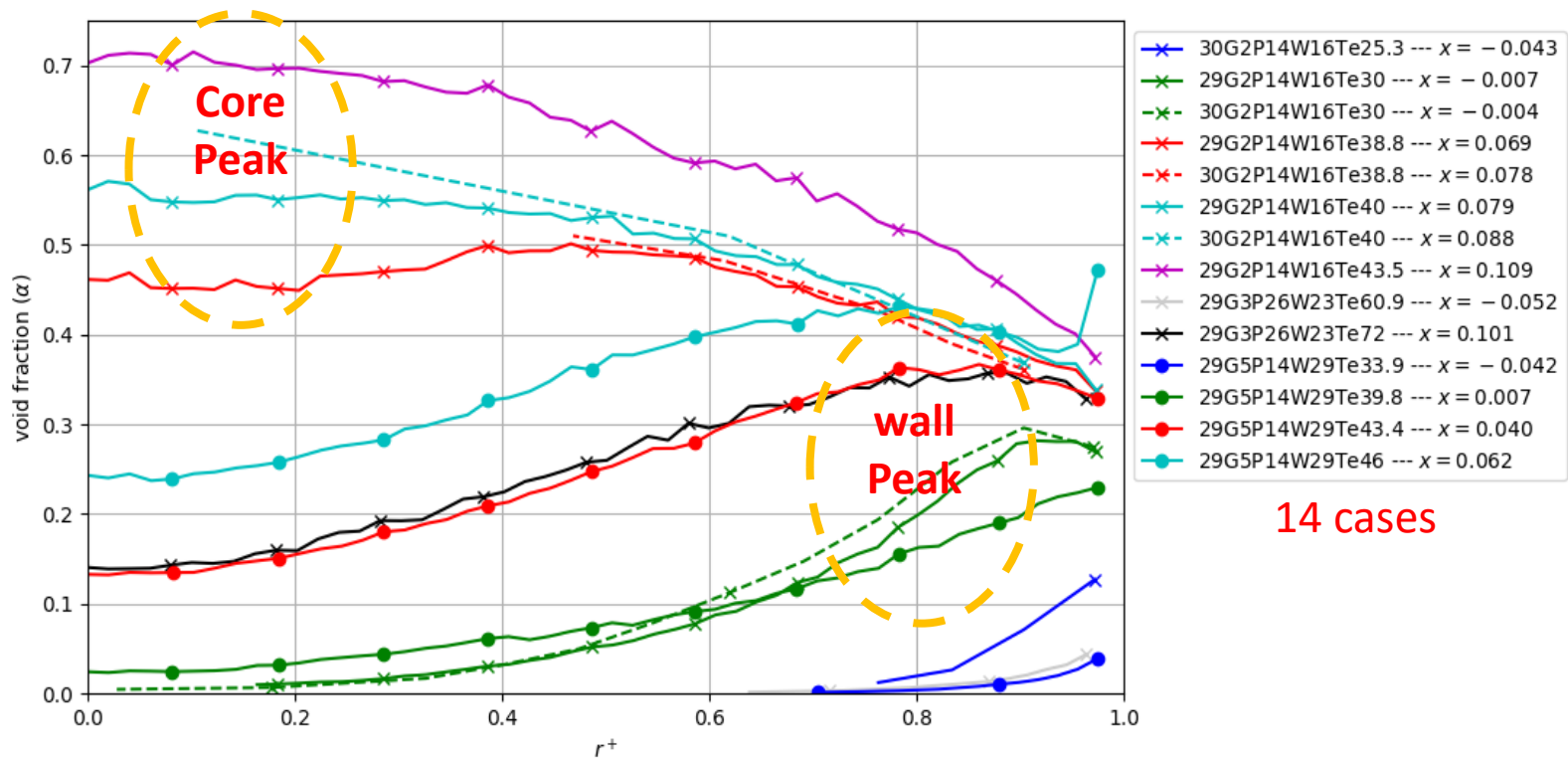
- Organized by **CEA (France)** and hosted by the **Neptune project**
- **24 institutes from 15 countries** confirm their participating
- **Main goals**
 - Lead the way towards a **unified method** for testing and validating CMFD closures under **high pressure** conditions in simple geometry
 - Addressing some aspects of **challenges** in boiling flows CMFD modeling
- **Two phases**
 - **Phase 1: open tests (October 2021- March 2022)**
14 selected cases with already **published data**, and opening of some supplementary data
 - **Phase 2: blind tests (June 2022- November 2022)**
4 additional cases in blind conditions

Organization and Objectives

» Phase 1

➤ Challenges

- A wide range of void fraction (up to 70%)
- Different positions of the **peak values**
- **Single set of closure model** for the whole database

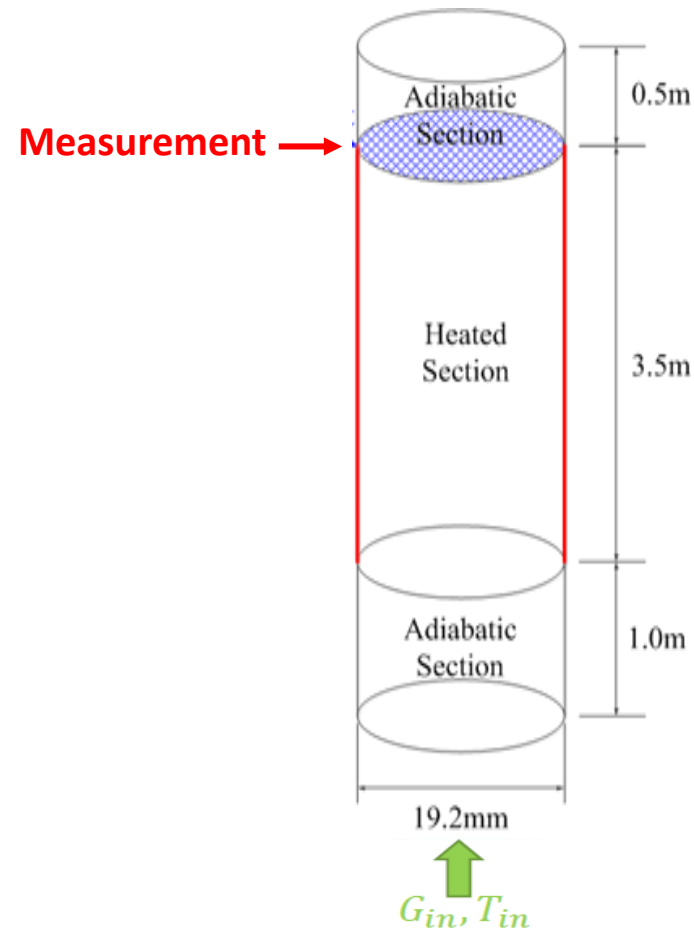


Description of DEBORA Experiment

» **Subcooled flow boiling** under **high-pressure** conditions

Main Characteristics

Test Section	pressurized pipe
Working fluid	R-12
Pressure range	1,46 to 3.0 MPa (R-12) 9.0 to 17.0 MPa (water/steam)
Measurement	Radial profiles of boiling parameters at <u>one elevation</u>
Country	France (CEA)
Year	<u>2001</u>



Numerical and Physical Models (1)

» Wall Heat Flux Partitioning

- The rate of **vapor generation** at the wall is computed by the Wall Heat Flux Partitioning model (WHFP)

WHFP “RPI boiling model”

$$\dot{q}_w'' = \dot{q}_c'' + \dot{q}_q'' + \dot{q}_e''$$

Single-phase
Convection

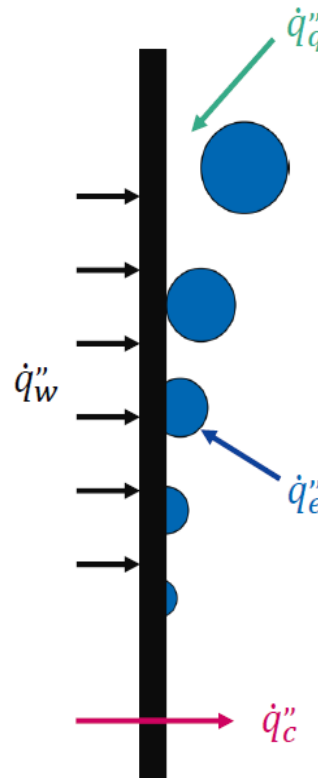
Quenching

Evaporation

$$\dot{q}_c'' = (1 - A_{2f}) h_c (T_w - T_l)$$

$$\dot{q}_q'' = A_{2f} h_q (T_w - T_l)$$

$$\dot{q}_e'' = N'' f \left(\frac{\pi}{6} D_{dep}^3 \right) \rho_g h_{fg}$$



Sub models

Bubble departure diameter (D_{dep})

Bubble departure frequency (f)

Nucleation site density (N)

Numerical and Physical Models (2)

» Interfacial Non-drag Force Model

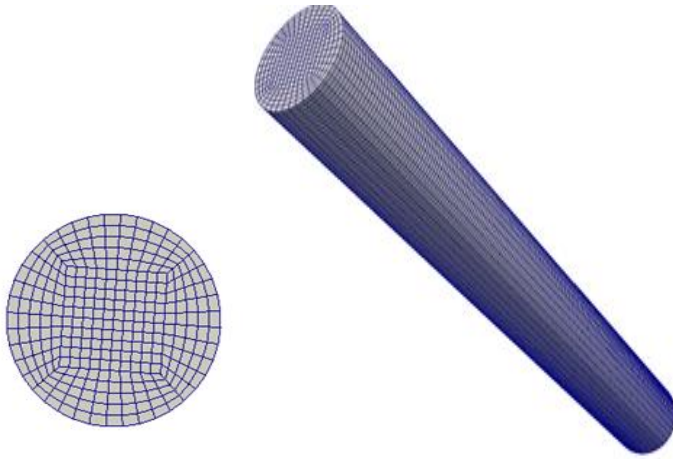
➤ Generated bubbles movement in radial direction

- ① **Bubble Lift force**: push the bubble in a direction orthogonal to the main flow
- ② **Turbulent dispersion force**: spread particles and smear gradients
- ③ **Wall lubrication force**: pushes the bubbles away from the wall

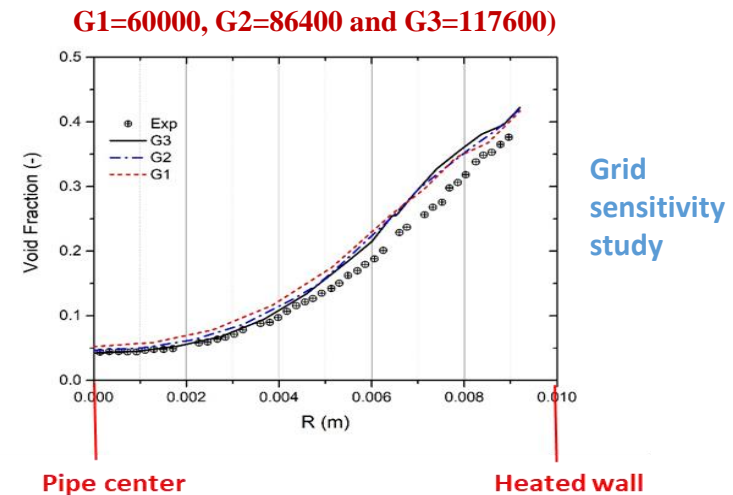
Parameters	Model
Wall Boiling	
Active nucleation site density	Hibiki-Ishii
Bubble departure diameter	Unal
Bubble departure frequency	Cole
Non-Drag forces	
Wall lubrication force	Antal
Bubble lift force	Tomiyaama
Turbulence dispersion force	Gosman
Others	
Turbulence	Standard $k-\epsilon$
Bubble induced turbulence	Kataoka
Bubble diameter (SMD)	Alatrash (KAERI)
Interfacial heat transfer	Ranz and Marshall

Mesh Generation

» Computational Mesh and Test Matrix



<Full representation of the CFD domain>

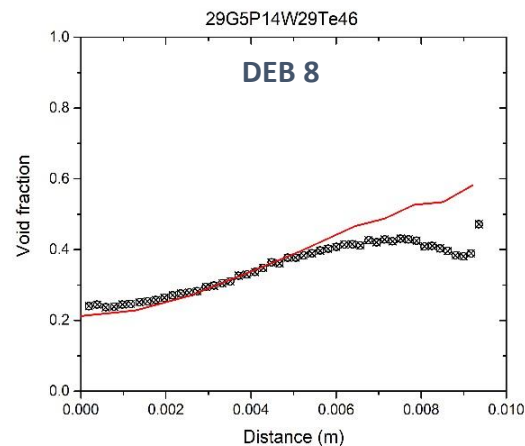
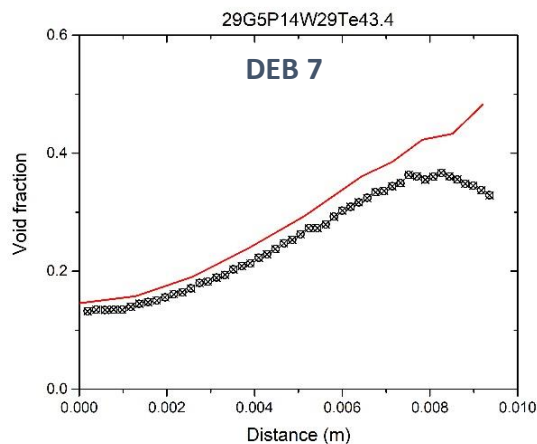
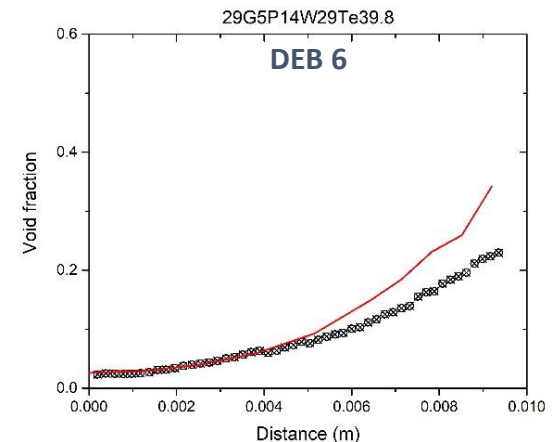
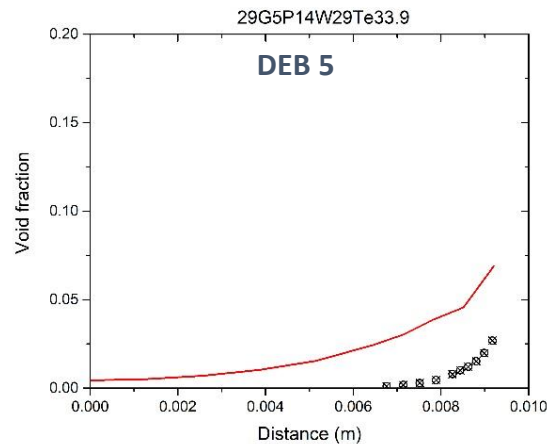
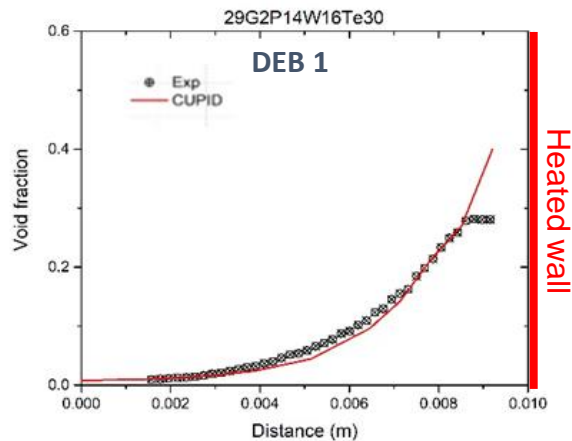


	Pressure (MPa)	Inlet subcooling (K)	Heat flux (W/m ²)	Mass flowrate (Kg/m ² s)	Test number
DEB 1	1.46	26.2	76240.0	2030	29G2P14W16Te30
DEB 2	1.46	14.4	76260.0	2022	29G2P14W16Te38.8
DEB 3	1.46	16.2	76260.0	2022	29G2P14W16Te40
DEB 4	1.46	12.5	76260.0	2024	29G2P14W16Te43.5
DEB 5	1.46	21.2	135000	5063	29G5P14W29Te33.9
DEB 6	1.46	15.7	135000	5085	29G5P14W29Te39.8
DEB 7	1.46	11.53	135000	5063	29G5P14W29Te43.4
DEB 8	1.46	9.53	135000	5070	29G5P14W29Te46

Position of the void
fraction peak
Shifted from
wall to the bulk

Calculation Results (1)

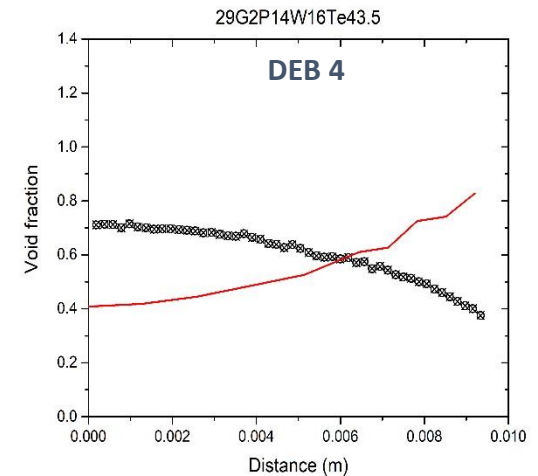
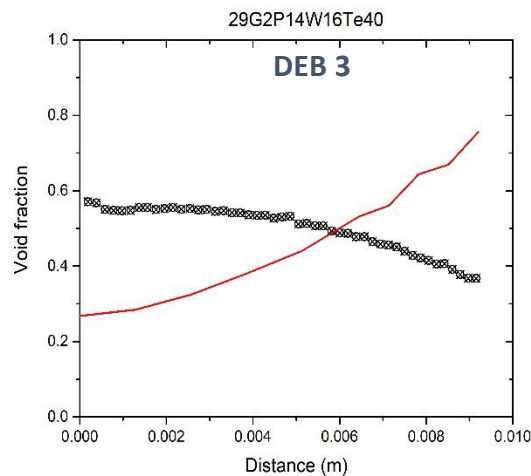
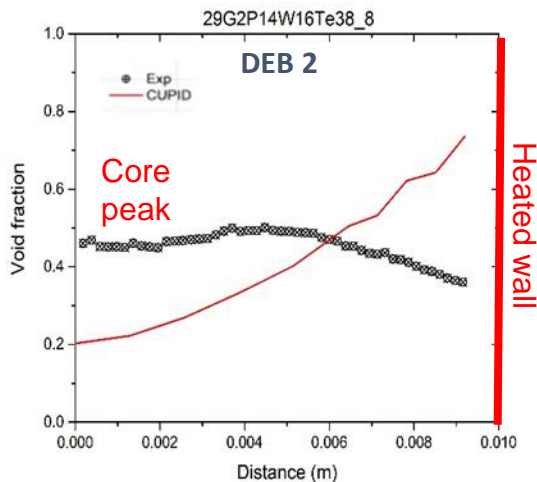
» Wall Peaking Cases



CUPID predicted the void fraction radial distribution well in the cases when the peak position is near the wall

Calculation Results (2)

» Core Peaking Cases

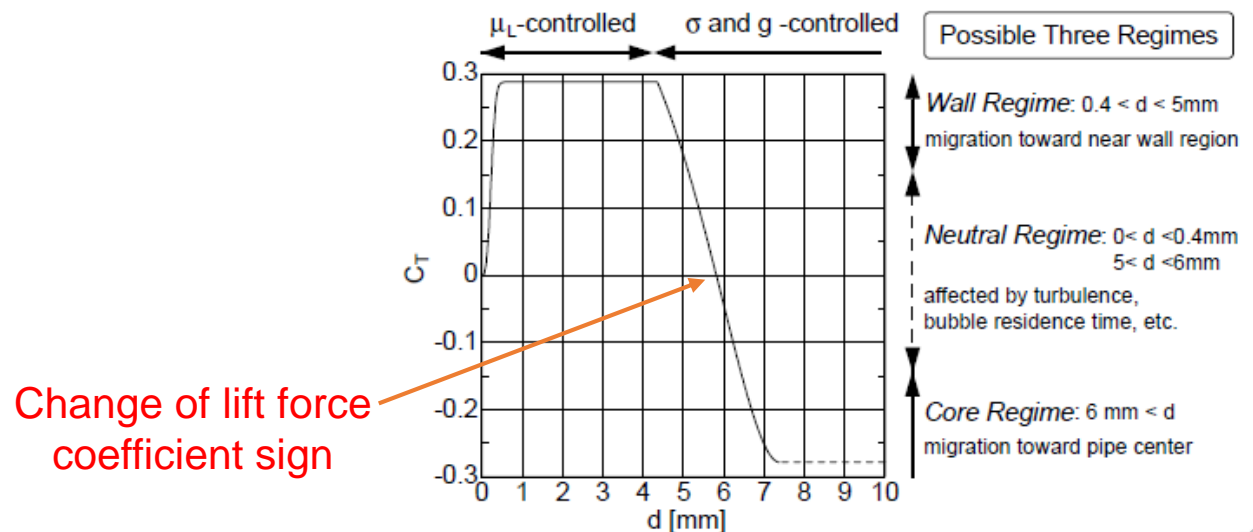


- Calculations still predict the wall peaking trend.
- Change of the void fraction maximum position is **caused by the lift force**.
- Void fraction shifting are not captured correctly using the default setting (**Original Tomiyama model**)

Modification of Lift Force Model

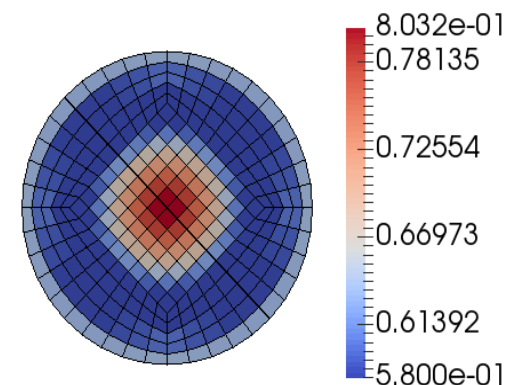
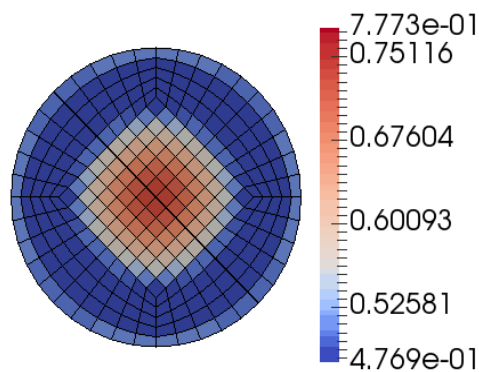
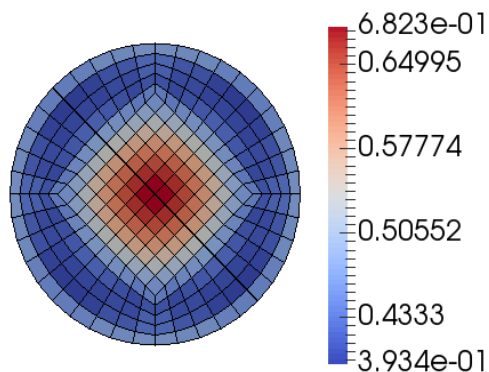
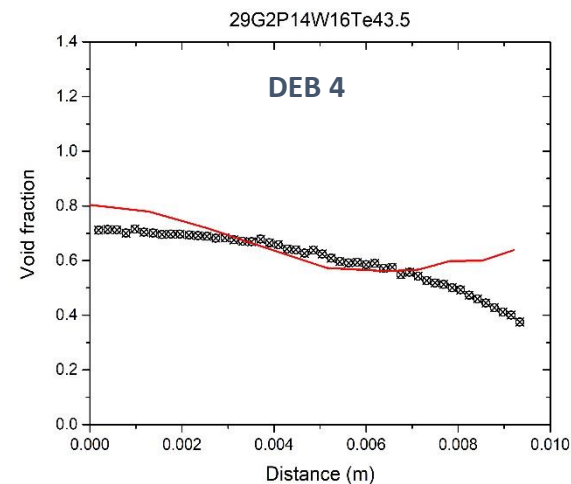
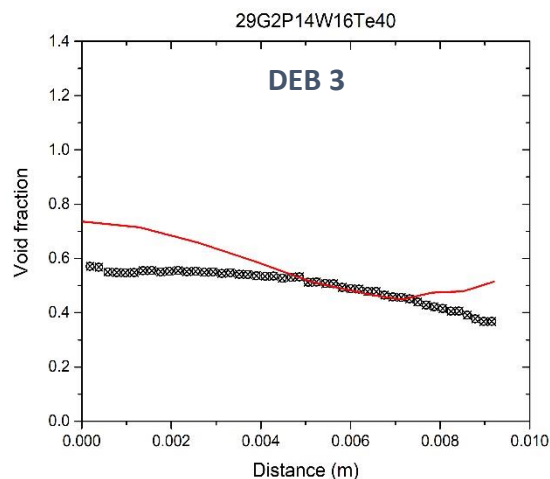
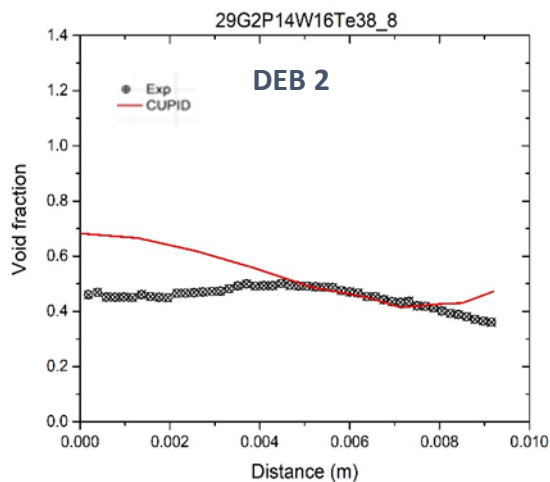
» Modifying Tomiyama model

- Change of the lift force coefficient sign: **bubble sizes larger than 5.8 mm**
- Tomiyama model: developed under **atmospheric pressure conditions**
- At high pressure bubble sizes are smaller.
- Modification of the Tomiyama model to change the sign of the lift force coefficient at bubble sizes **larger than 0.7 mm**



Improvement of Core Peak Prediction

» Effect of Modification



Conclusions

6



Conclusions

» Validation of CUPID via international benchmarks

- Radiation model, turbulence model, WFHP model, non-drag force models

» Summary

➤ OECD/NEA IBE-4

- Turbulence mixing due to the density difference
- Modified k-e model

➤ IAEA CRP

- Diffusion due to the concentration difference
- Turbulence mixing in complex geometries
- Low Reynolds number k-e model

➤ OECD/NEA HYMERES-2

- Thermal stratification with radiation model
- Turbulence mixing in complex geometries
- Standard k-e model with modified buoyancy term

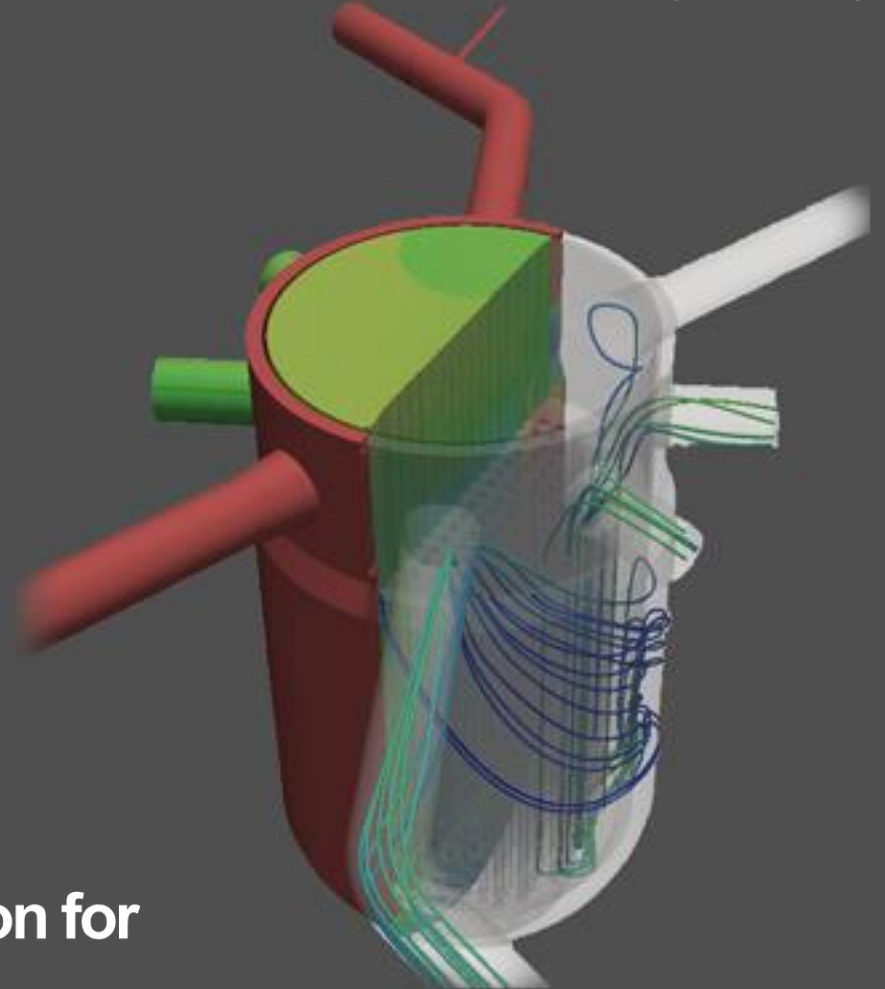
➤ DEBORA Benchmark

- Wall heat flux partitioning model
- Modification of bubble size criteria for bubble lift force

THANK YOU

yjcho@kaeri.re.kr





CUPID Workshop

Reactor Vessel 3D Mesh Generation for Safety Analysis

Seongju Do
March 04, 2022

CUPID Workshop

CONTENTS

- ▶ 01 WHY RV Mesh 3D?
- ▶ 02 Algorithms
- ▶ 03 Applications

WHY RV Mesh 3D?

1

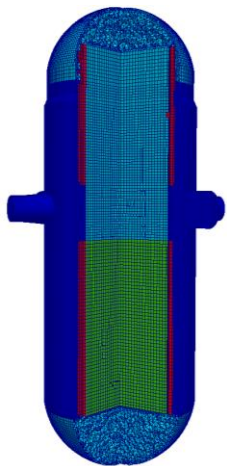


WHY 'RV Mesh 3D'?

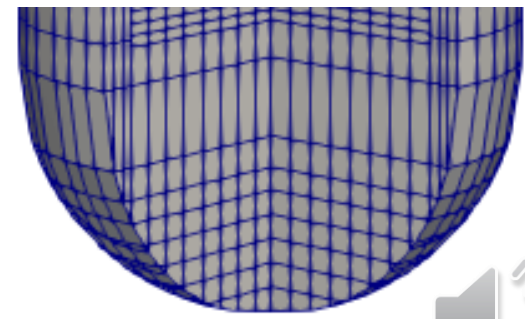
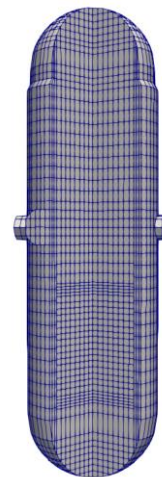
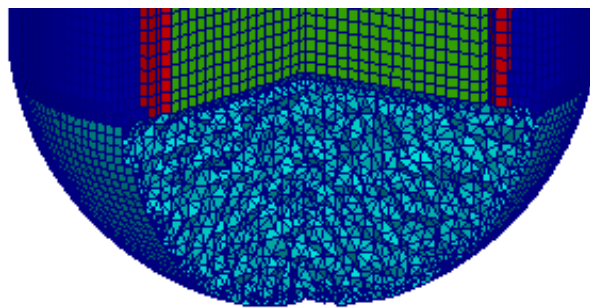
» 3D mesh generator dedicated to the PWR vessel geometry is vital.

- Include reactor core, downcomer(DC), upper/lower plenum(UP/LP) and hot/cold leg
- Practical number of meshes (less than **10 million**)
- Most importantly, maintain **structured mesh in the core region** for the application of **subchannel model**
- Applicable for **different PWR geometries**

It's hard to apply commercial pre-processors



<Generated by commercial pre-processor>



<Generated by RV Mesh 3D>

Algorithms

2

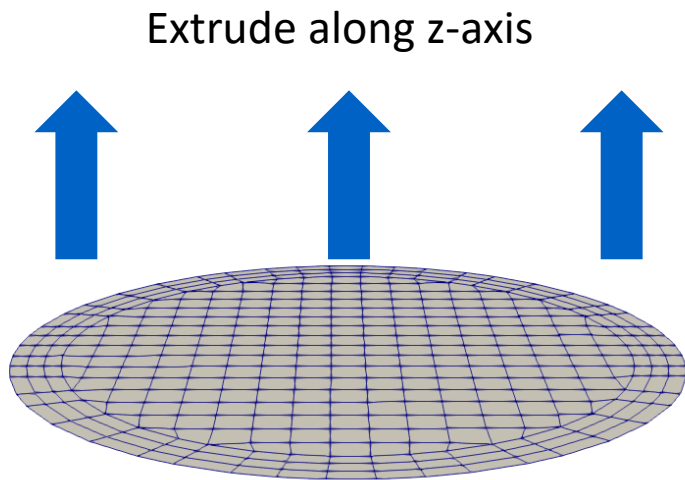
- Plane extrusion
- Cut-cell method
- Enhancement of mesh quality



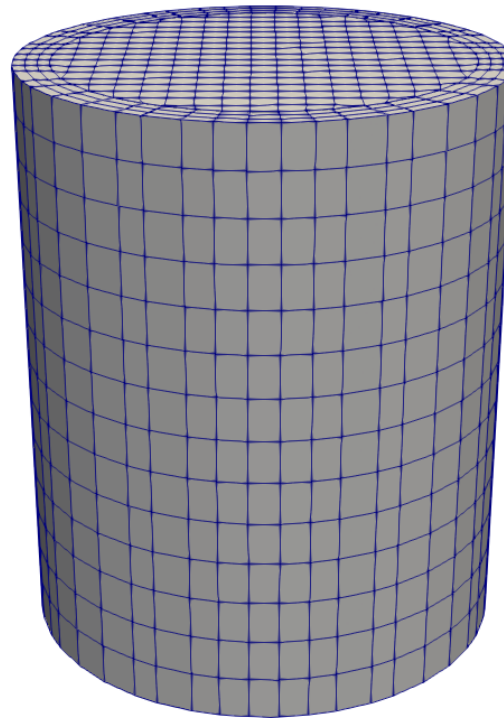
Plane extrusion

» Core / Downcomer(DC) region

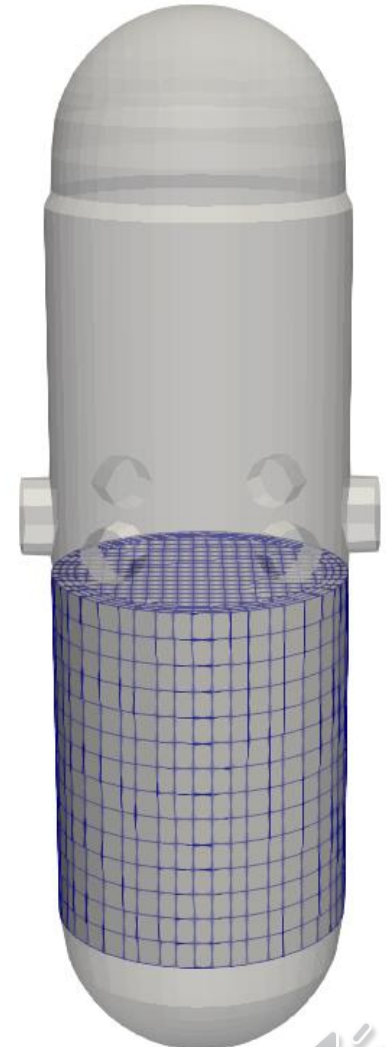
- 2D Mesh generation
- Plane extrusion along z-direction



<2D plane extrusion>



<3D volume mesh>

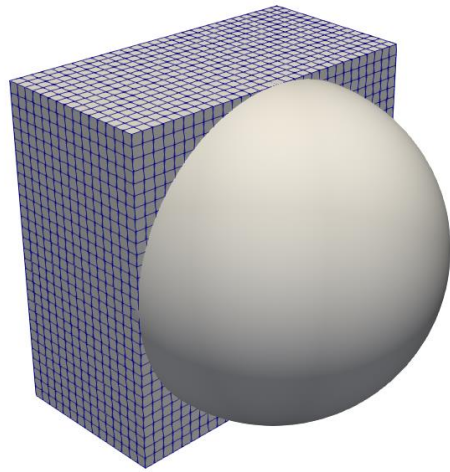


<Core / DC part>

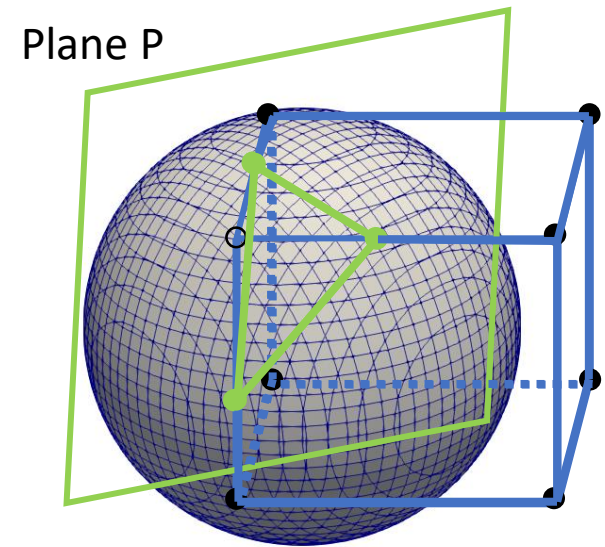
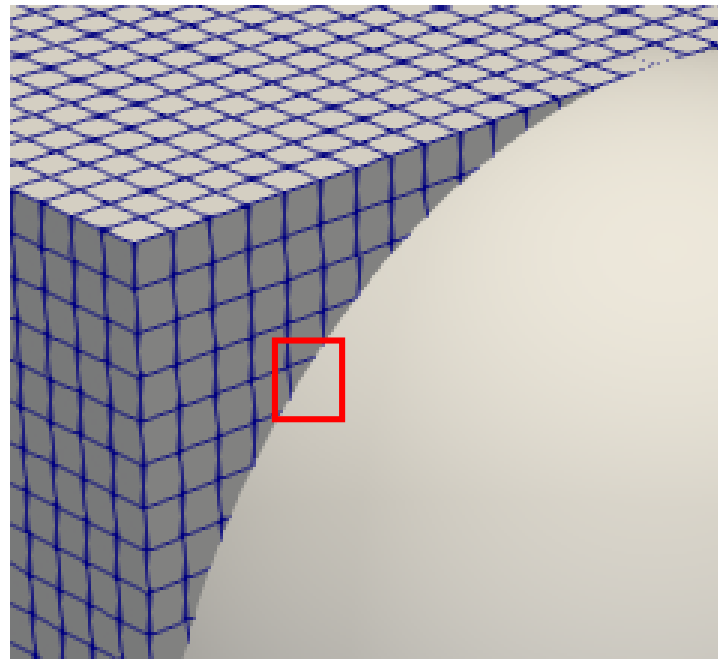
Cut-cell method

» Representation of the Curved Surfaces

- Upper / lower plenum
- **Cut-cell method** is applied for the curved faces
 - Cut-cell approach uses background Cartesian grid with special treatments being applied to cells which are cut by solid bodies.



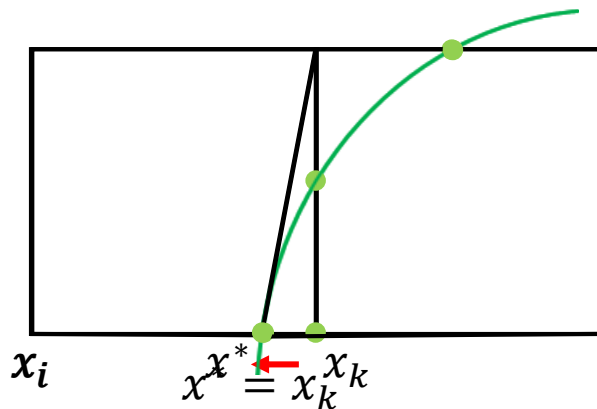
<Sphere is immersed in base mesh>



<After cut-cell algorithm>

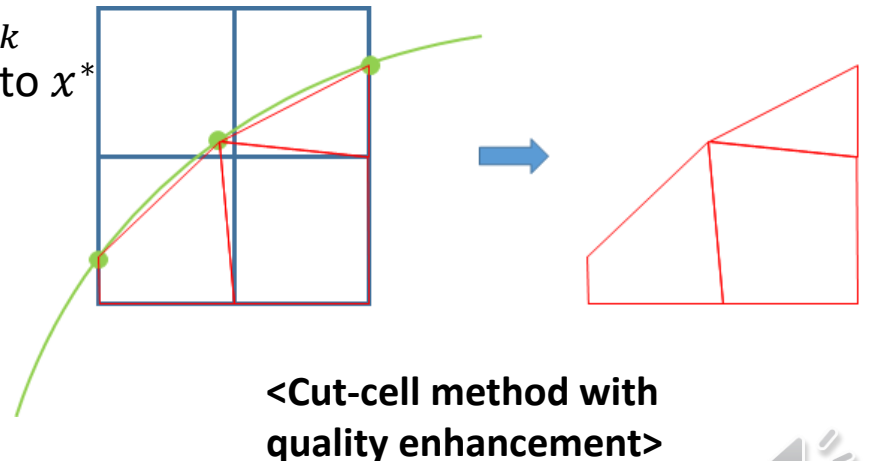
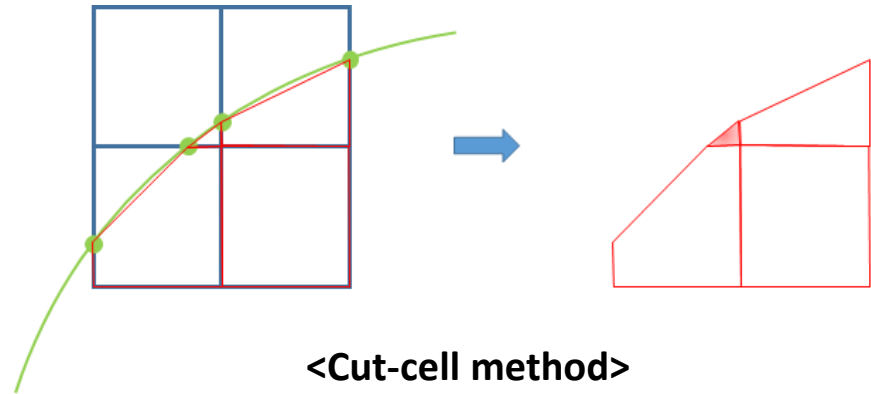
Enhancement of mesh quality

- » Cut-cell method may generate **small cells**
 - Small cells cause **numerical instability and small time step size.**
- » The generation of small cells can be suppressed by **transforming the base grid.**



<Quality enhancement approach>

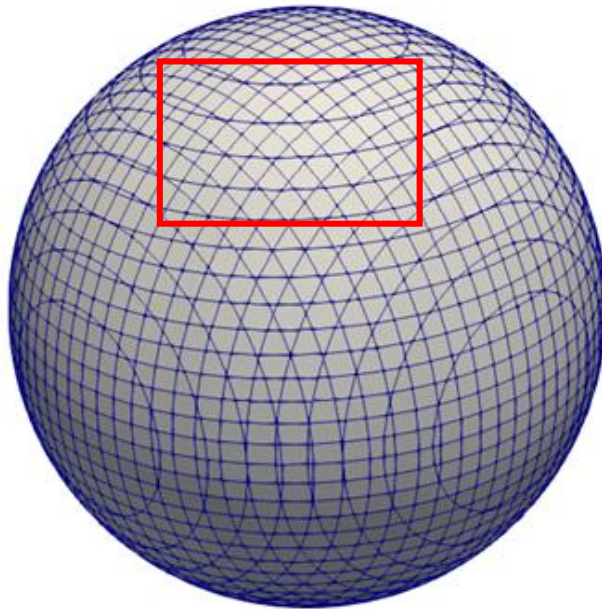
x^* is close to x_k
 \rightarrow move x_k to x^*



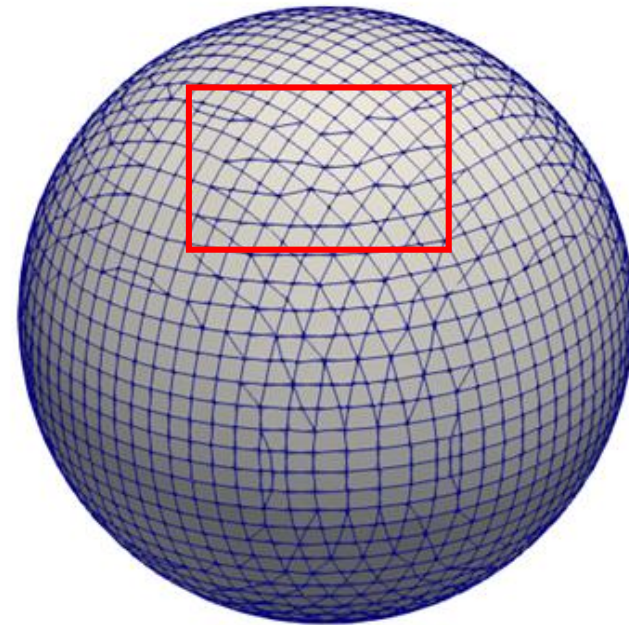
Enhancement of mesh quality

» Results after the enhancement

- Small cells are removed with the algorithm.
- There is no geometric distortion



<Before enhancement>



<After enhancement with $\varepsilon = 0.1$ >

Applications

3

- OPR1000/APR1400
- NuScale (TerraPower, US)
- iSMR (KHNP, Korea)



OPR1000/APR1400

» Mesh Generation Procedure

Generate 2D plane

Core / DC region

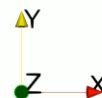
Extrude the 2D plane

LP/UP region

Cut-cell method

Hot/cold legs

Cell splitting

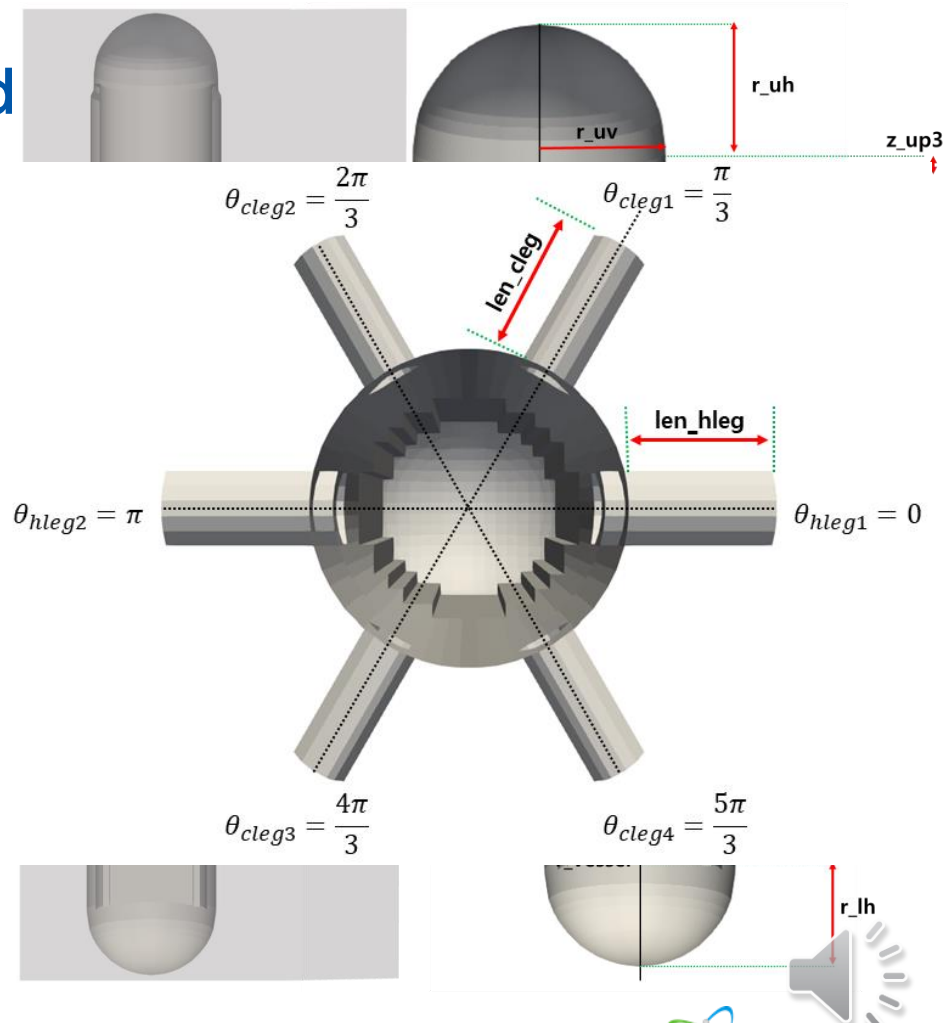


OPR1000/APR1400

» User-friendliness of RVMesh3D

- Text-based input
- User inputs are minimized

- Geometrical information
 - ✓ Heights
 - ✓ Radius
 - ✓ Angle/length of legs
 - ✓ FA configuration
- Mesh information
 - ✓ Mesh resolution (assembly/subchannel)



OPR1000/APR1400

» Mesh generation of OPR1000/APR1400

➤ Main geometrical differences

- Radius of vessel
- Assembly configuration
 - ✓ 15x15 Grid / 17x17 Grid

```

!-----MASTER nz = 28-----!
&PLANE 2D
  r_core = 1.7526d0 !3.505200d0*0.5d0
  drd = 0.208/40d0
  width_dc = 0.3048d0 !...r_vessel=r_core+width_dc
  rhlg = 0.6d0 !...'rhlg' is a just some sufficiently large value rather than 'real'
  n_layer_dc = 3
  nx_assem = 15
  ny_assem = 15
  nx_pin = 16
  ny_pin = 16
  pitch_rod_rod = 0.012852d0 ! pitch1, rod-to-rod pitch
  pitch_rod_wall = 0.007980d0 ! pitch2, rod-to-wall distance

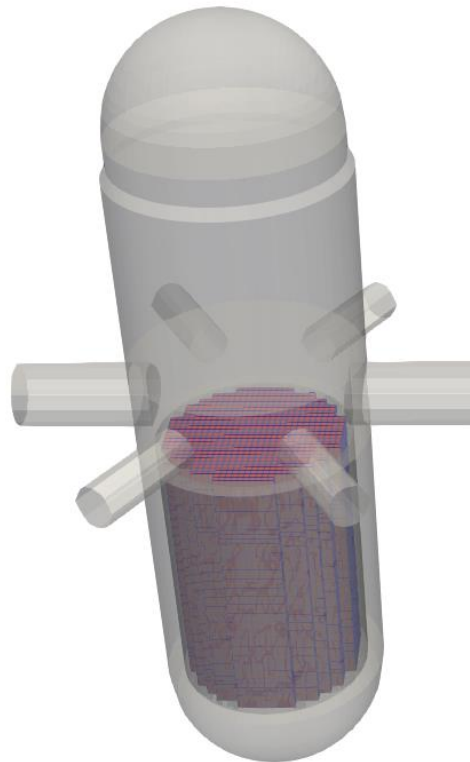
  resolution_base = 2 ! 1: 1x1, 2:2x2, 3:4x4, 4:8x8, 5:rod-rod.
  resolution_core = 2 ! 1: 1x1, 2:2x2, 3:4x4, 4:8x8, 5:rod-rod.
  MARS_coupling = .false.
/

&ASSEMBLY_MAP 2D
  mask_assem(1:15, 1) = 0, 0, 0, 0, 0, 0, 1, 1, 1, 1, 1, 0, 0, 0, 0, 0
  mask_assem(1:15, 2) = 0, 0, 0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 0, 0, 0, 0
  mask_assem(1:15, 3) = 0, 0, 0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 0, 0, 0
  mask_assem(1:15, 4) = 0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 0, 0
  mask_assem(1:15, 5) = 0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 0
  mask_assem(1:15, 6) = 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1
  mask_assem(1:15, 7) = 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1
  mask_assem(1:15, 8) = 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1
  mask_assem(1:15, 9) = 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1
  mask_assem(1:15, 10) = 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1
  mask_assem(1:15, 11) = 0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 0
  mask_assem(1:15, 12) = 0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 0
  mask_assem(1:15, 13) = 0, 0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 0, 0
  mask_assem(1:15, 14) = 0, 0, 0, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 0, 0
  mask_assem(1:15, 15) = 0, 0, 0, 0, 0, 0, 1, 1, 1, 1, 1, 1, 0, 0, 0, 0
  /

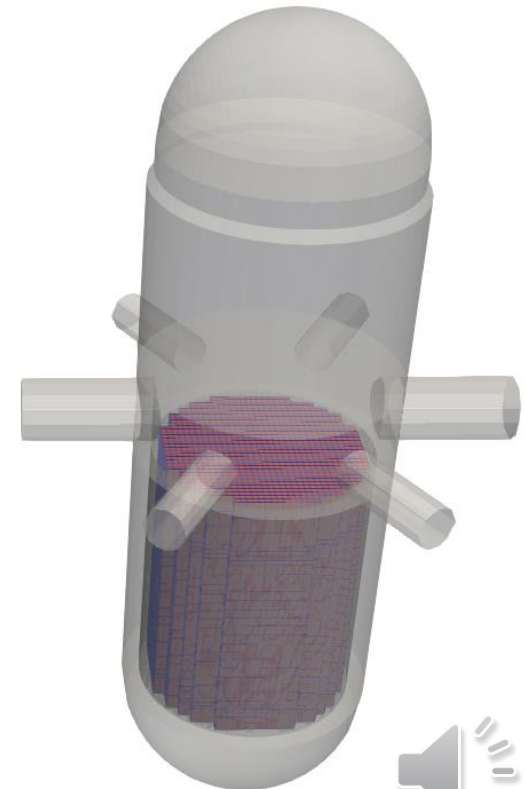
```

r_
nx
ny
m:

<OPR1000>

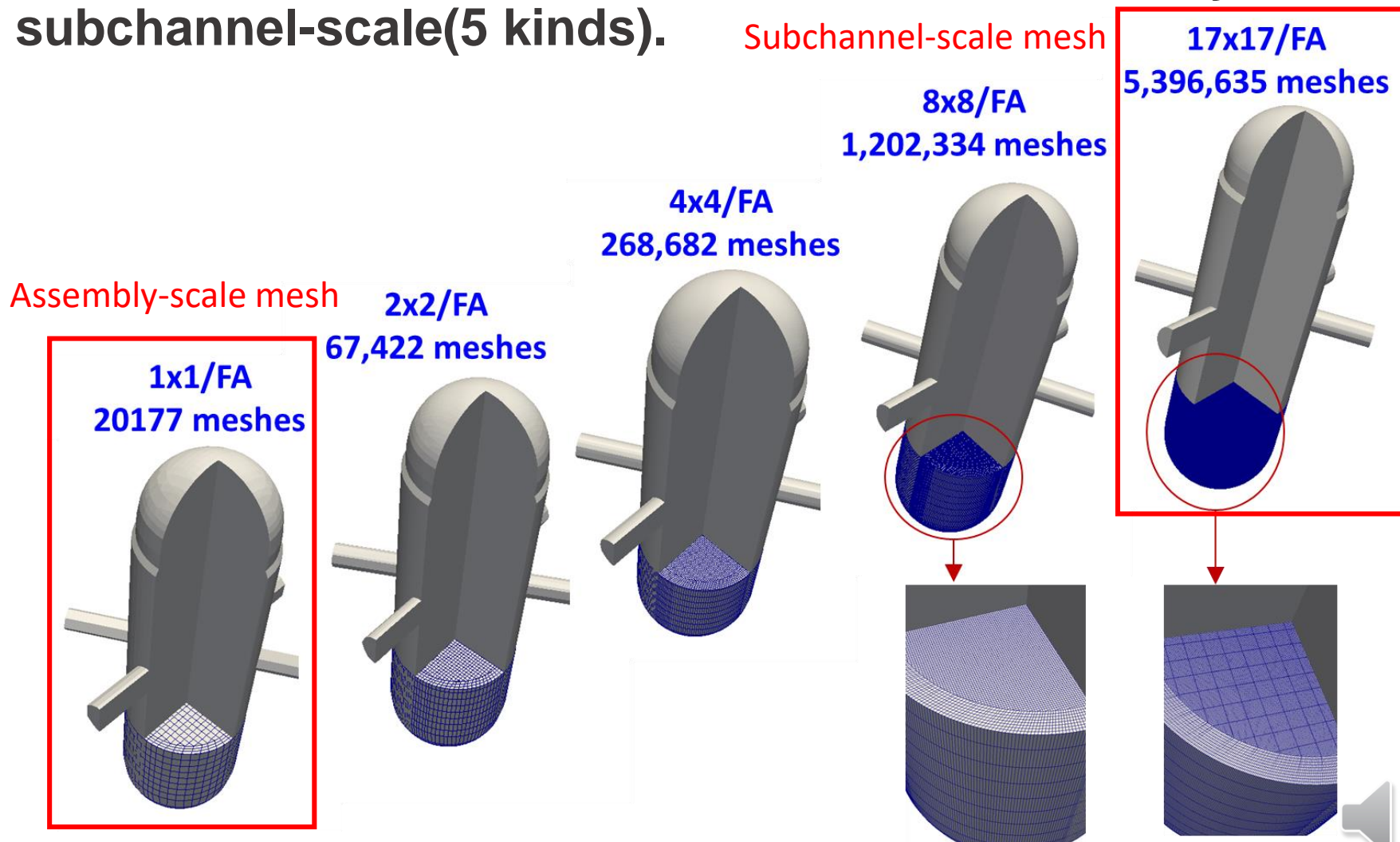


<APR1400>



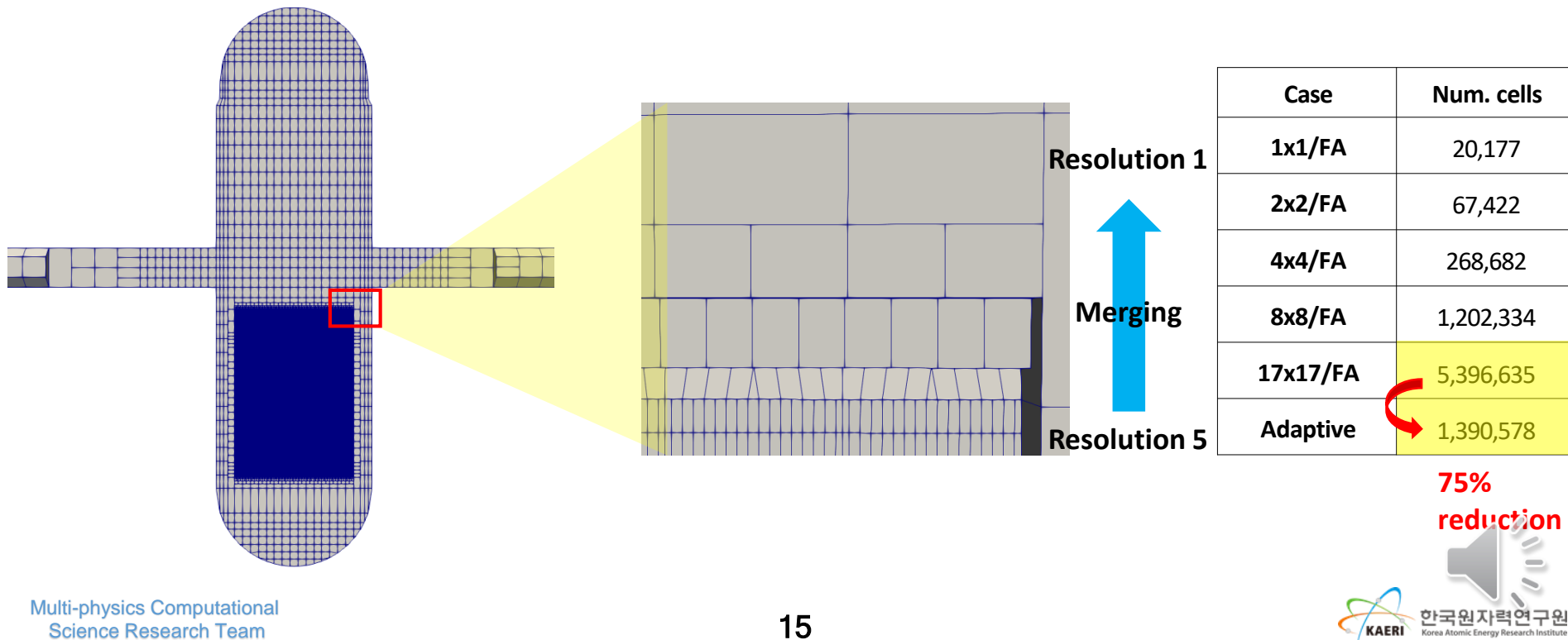
OPR1000/APR1400

» Mesh resolution can be controlled from assembly-scale to subchannel-scale(5 kinds).



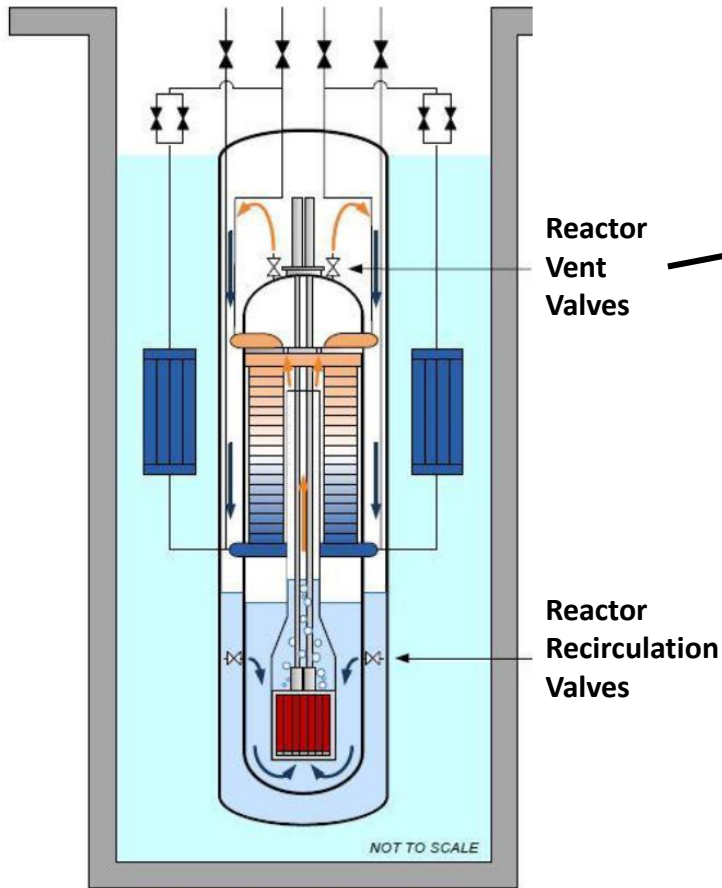
Mesh Optimization

- » To reduce simulation time, **mesh adaptation** technique is applied.
- » High resolution mesh is utilized in **core region** only.
- » The number of mesh is reduced by about **75%**.

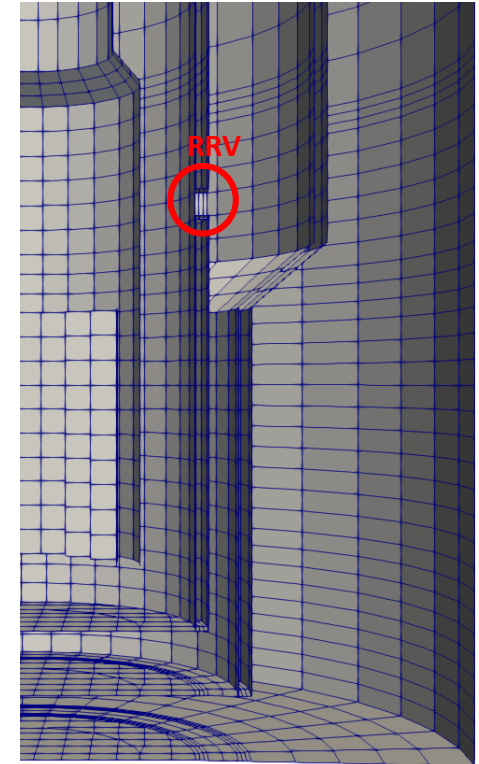
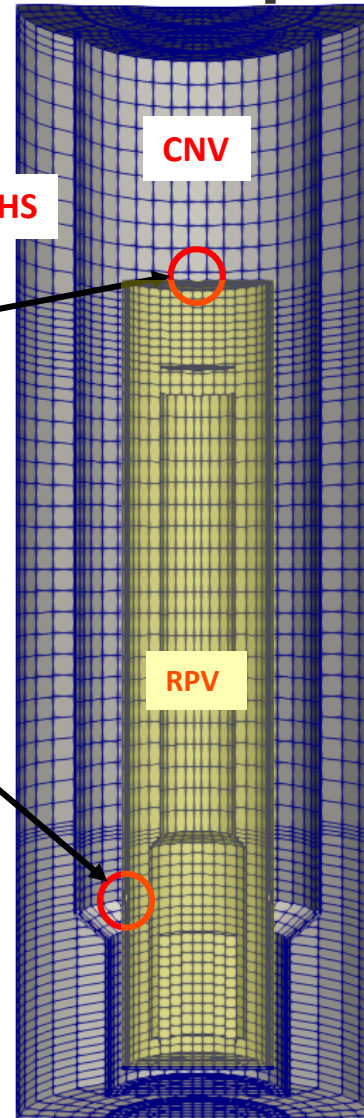


NuScale (US SMR)

» Schematic diagram



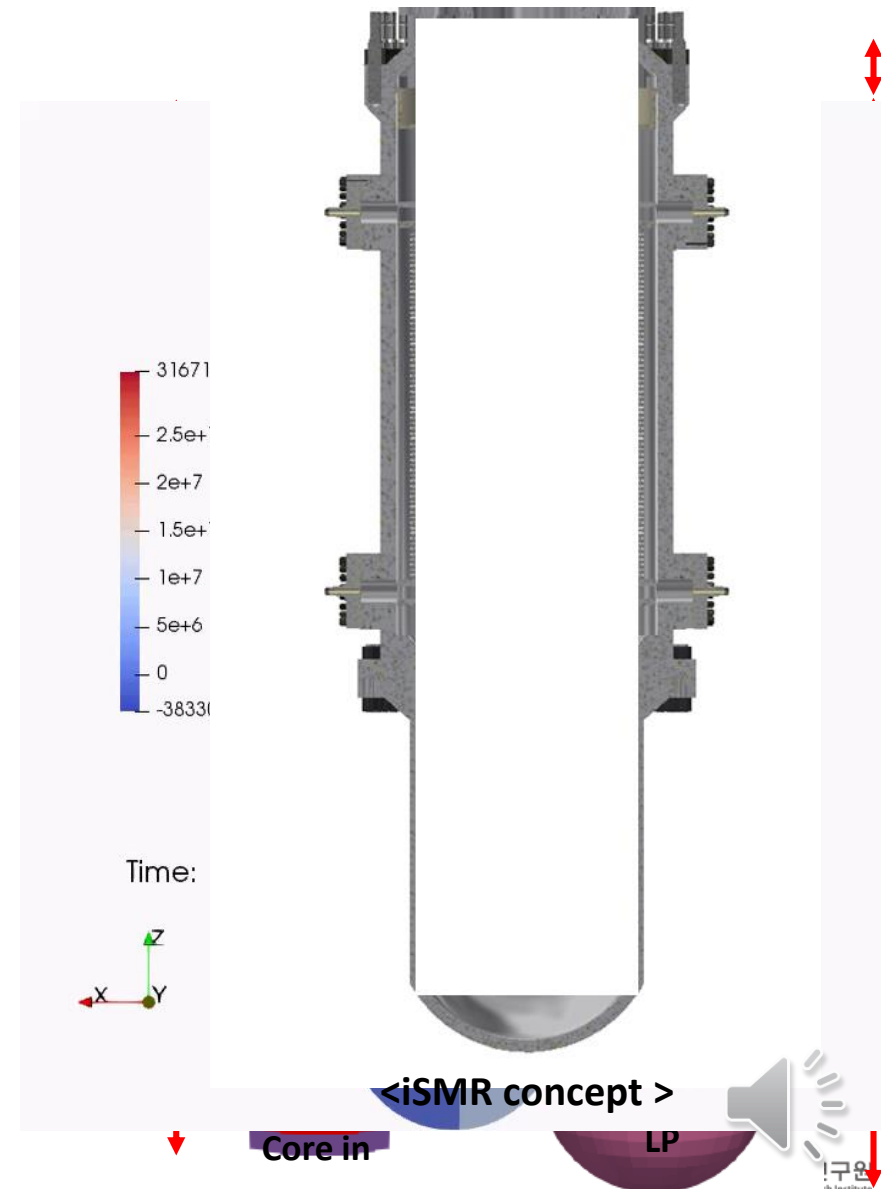
» Computational mesh



- RVV/RRV flow path is considered to simulate LOCA.
- 3D LOCA simulation is currently in progress.

iSMR(Korean SMR)

- » iSMR design is in progress in Korea.
- » CUPID and RVMesh3D are used to simulate **natural circulation** phenomenon.



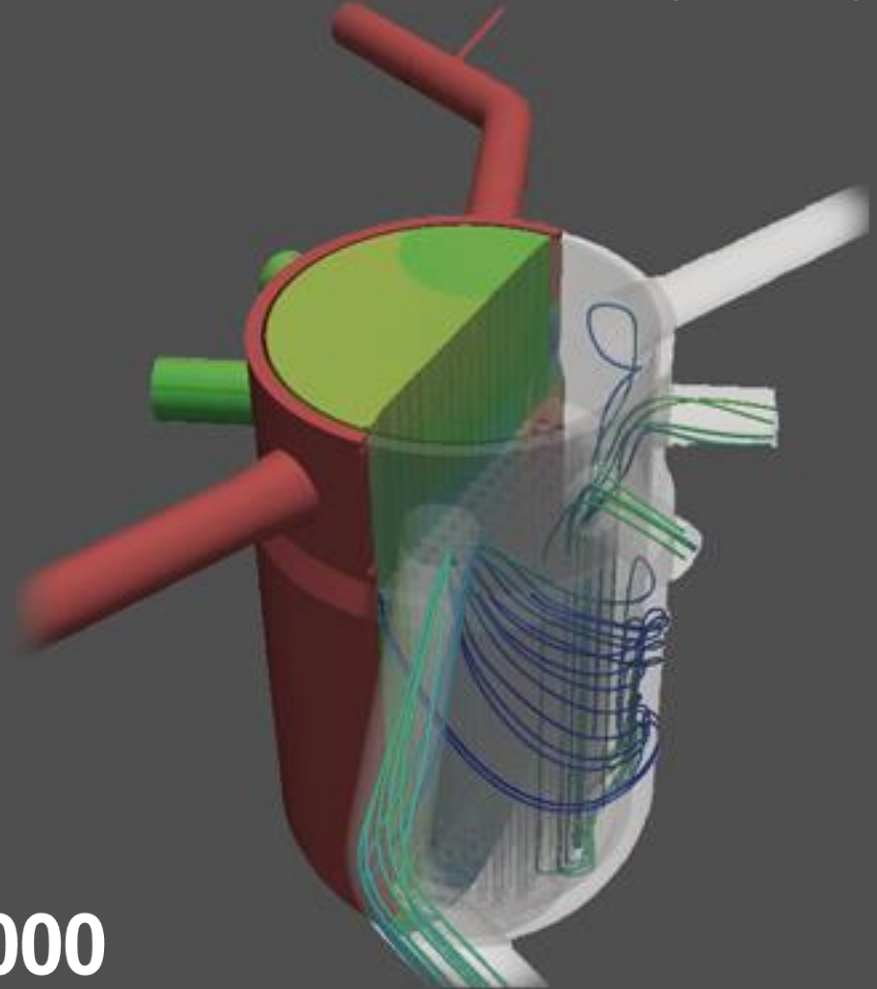
Summary

- » Maintain **structured mesh in the core region** for the application of **subchannel model**
- » Practical number of meshes (**1.5 million** for **subchannel scale**)
- » Applicable for **different PWR and SMR** geometries with **simple user input**

THANK YOU

sjdo@kaeri.re.kr





CUPID Workshop

Pin-wise Full Core Safety Analysis of OPR1000

Jae Ryong Lee
March 04, 2022

- ▶ **01** WHY 3D Safety Analysis ?
- ▶ **02** Multi-Scale and Multi-Physics (MSMP) Configuration
- 03** MSMP Safety Analysis of a PWR
- ▶ **04** Full core Pin-wise Fuel Performance
- ▶ **05** Summary

CUPID Workshop

CONTENTS

WHY 3D Safety Analysis ?

- 3D Safety Analysis Issues
- Multi-Scale & Multi-Physics (MSMP) Approach to Safety Analysis

3D Safety Analysis Issues

» Steam Line Break (SLB)

➤ Safety issue of SLB accident

- Increase of heat removal due to steam line break
- Local power increase and radially asymmetric distribution
- **DNBR** Margin ✕ DNBR: Departure from Nucleate Boiling Ratio

» System T/H Analysis for Non-LOCA

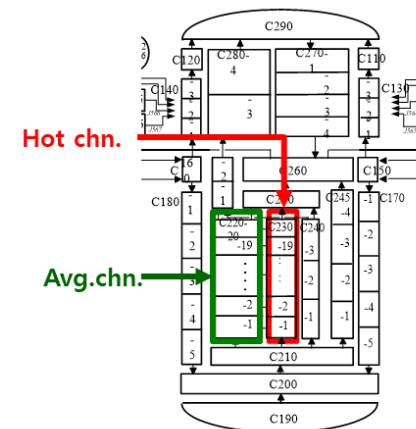
➤ 1D nodalization

- Hot channel modeling for DNBR evaluation

➤ Limitation of 1D approach

- **Axial flow** ONLY
- Neutron power using **point-kinetics**
- **Simplified geometric parameter**
 - ✓ Hydraulic diameter, heated diameter

➔ **Conservative safety analysis results**



System TH nodal for PWR

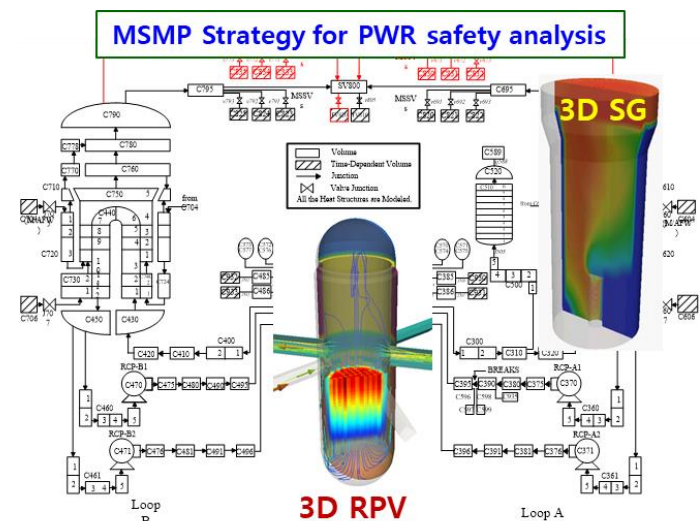
Multi-Scale & Multi-Physics (MSMP) approach

» Multi-Scale T/H

- **3D (subchannel T/H) resolution for region of interest**
 - **Reactor pressure vessel**, steam generator
 - Desirable spatial resolution for 3D resolution
 - ✓ Ex. **Subchannel scale** for core
 - Realistic multi-dimensional flow behavior
 - ✓ Radial flow behavior in core, two-phase flow in secondary side of SG
- **1D (Sys. T/H) resolution for the rest of RCS**

» Multi-Physics (N/K, F/P)

- **Pin-wise fuel behavior**
 - 3D power distribution
 - ✓ Neutron kinetics (N/K) code
 - Realistic fuel rod status
 - ✓ Fuel performance (F/P) code



Multi-Scale and Multi-Physics (MSMP) Configuration

2

- Multi-Scale & Multi-Physics (MSMP) Strategy

- MARU* Platform

※ MARU

(Multi-physics Analysiss Platform for Nuclear Reactor SimUlation)

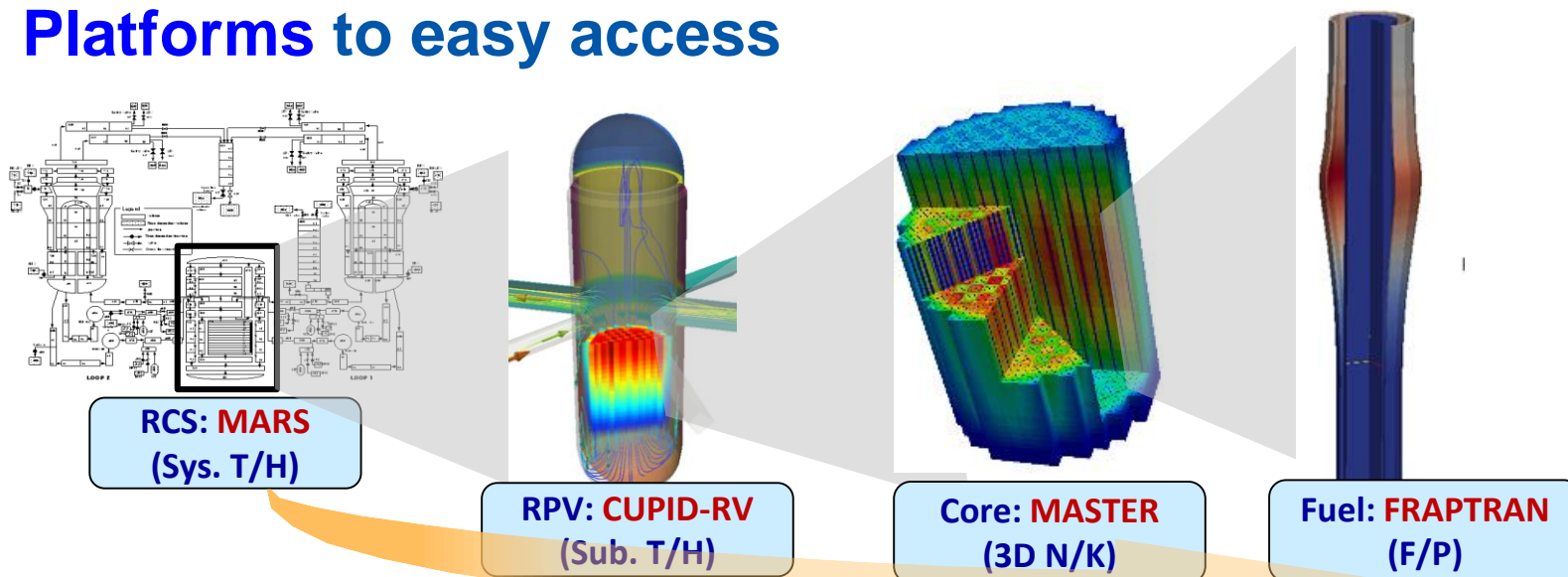
Multi-Scale & Multi-Physics (MSMP) Strategy

» MSMP Simulation Scope

➤ Entire RCS is considered

Region	features	Code	Coupling
RCS	System-scale T/H	MARS	Source-to-source
RPV	Subchannel-scale T/H	CUPID-RV	
Reactor core	Fuel performance	FRAPTRAN	
	3D neutron diffusion	MASTER	Dynamic Link Library (DLL)

➤ Platforms to easy access



MARU Platform

» Background

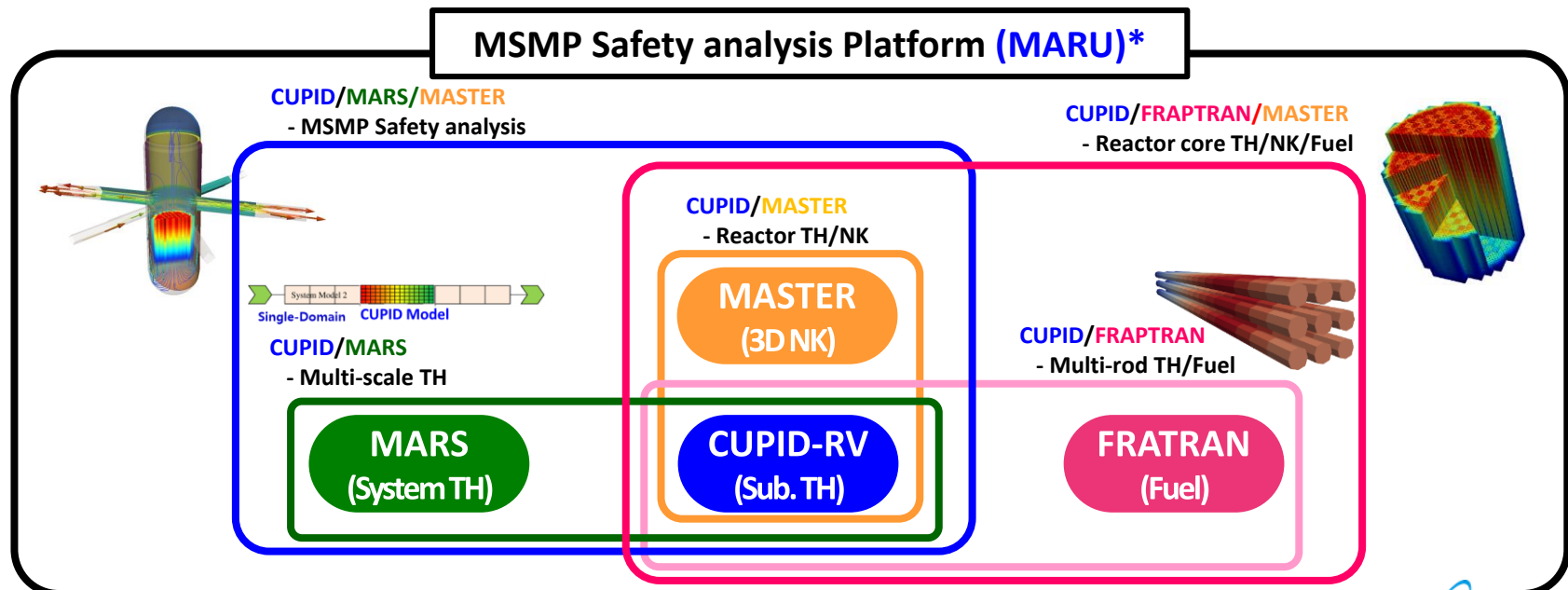
➤ Limited coupled simulation

- Multi-scale T/H , Multi-physics (T/H & N/K)
- Necessity for **integrated tools** for MSMP

Code	Physics	Ownership	Year
MARS	System T/H	KAERI	2006
CUPID-RV	Subchn. T/H	KAERI	2017 (Ver.2.5)
MASTER	Nodal N/K	KAERI	2013 (Ver.4)
FRAPTRAN	Fuel Per.	US NRC	2014 (Ver.2)

» MARU (Multi-physics Analysys Platform for Nuclear Reactor SimUlation)

➤ Platform for 3D MSMP Safety analysis



MARU Platform

» Platforms Structure

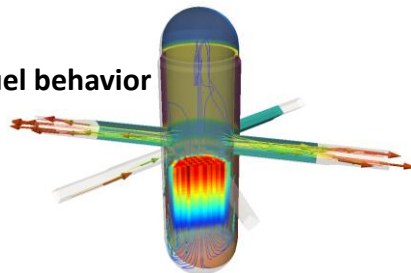
➤ TCP/IP socket communication

- Server (Linux) \leftrightarrow Client (Windows)

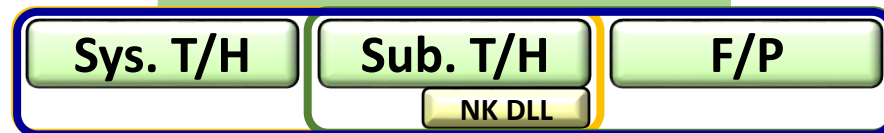
➤ Multiple source-to-source compilation among codes as user needs

- Equivalent source level between T/H and F/P
 - ✓ N/K is weak coupled by DLL

Full core pin-wise fuel behavior
With RCS status

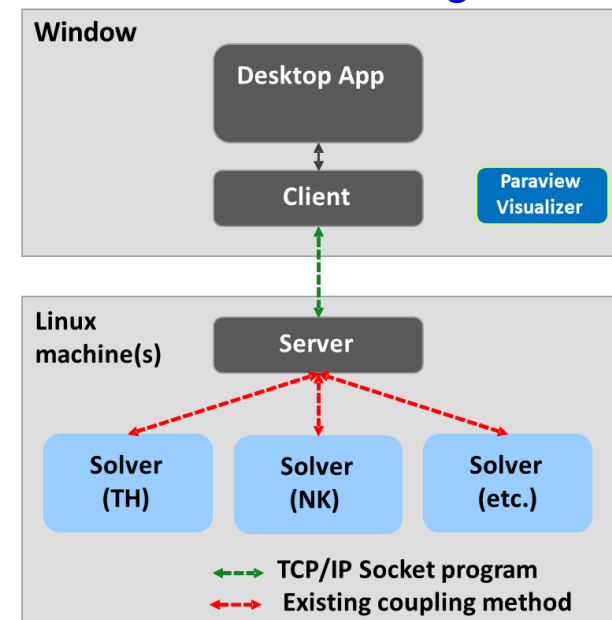


Multi-Scale & Multi-Physics compilation



Independent executable

MARU configuration



MSMP Safety Analysis

3

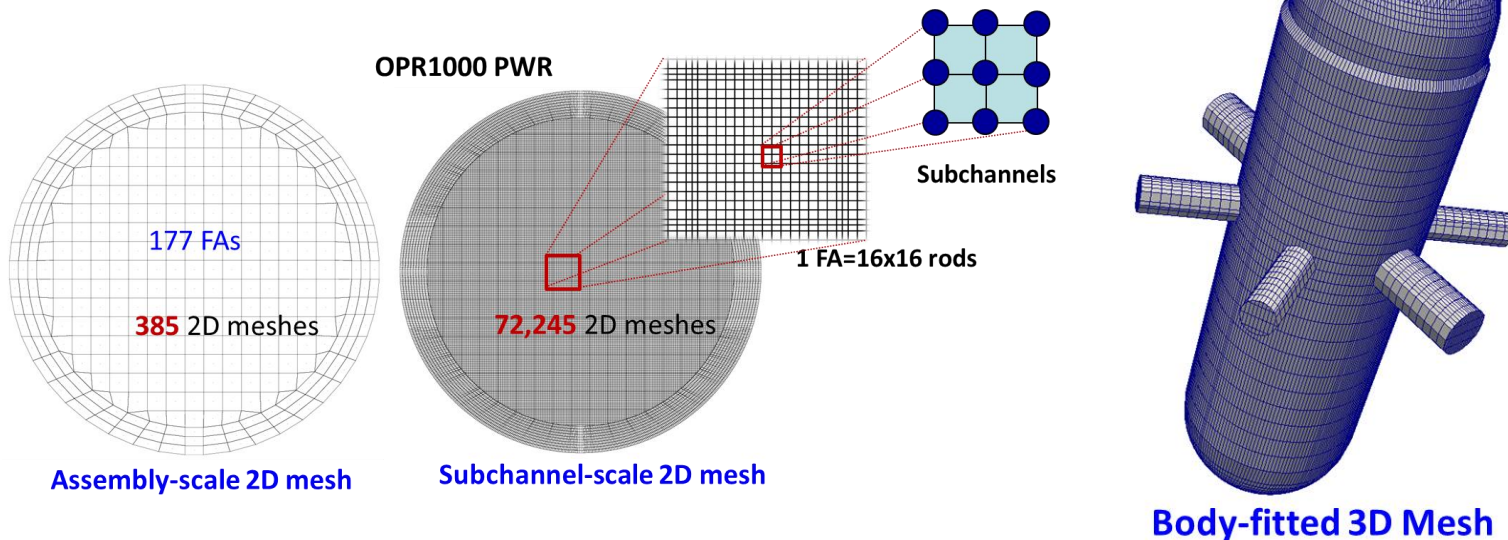
- MSMP Simulation of OPR1000 SLB Accident
- Improvement of Safety Margin (DNBR)

3D Reactor Pressure Vessel Modeling

» Subchannel-scale RPV Computational Geometry

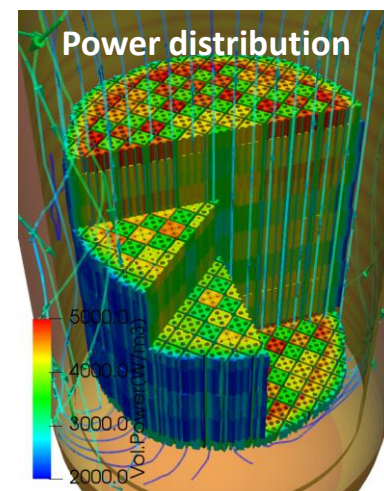
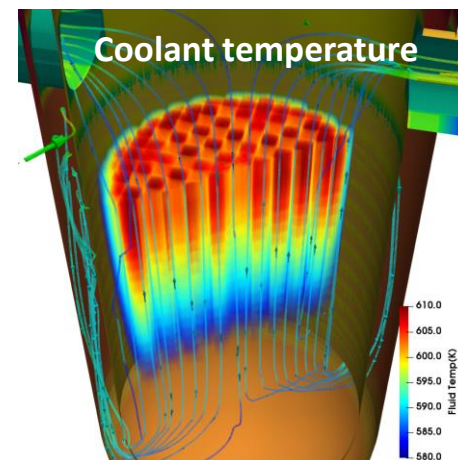
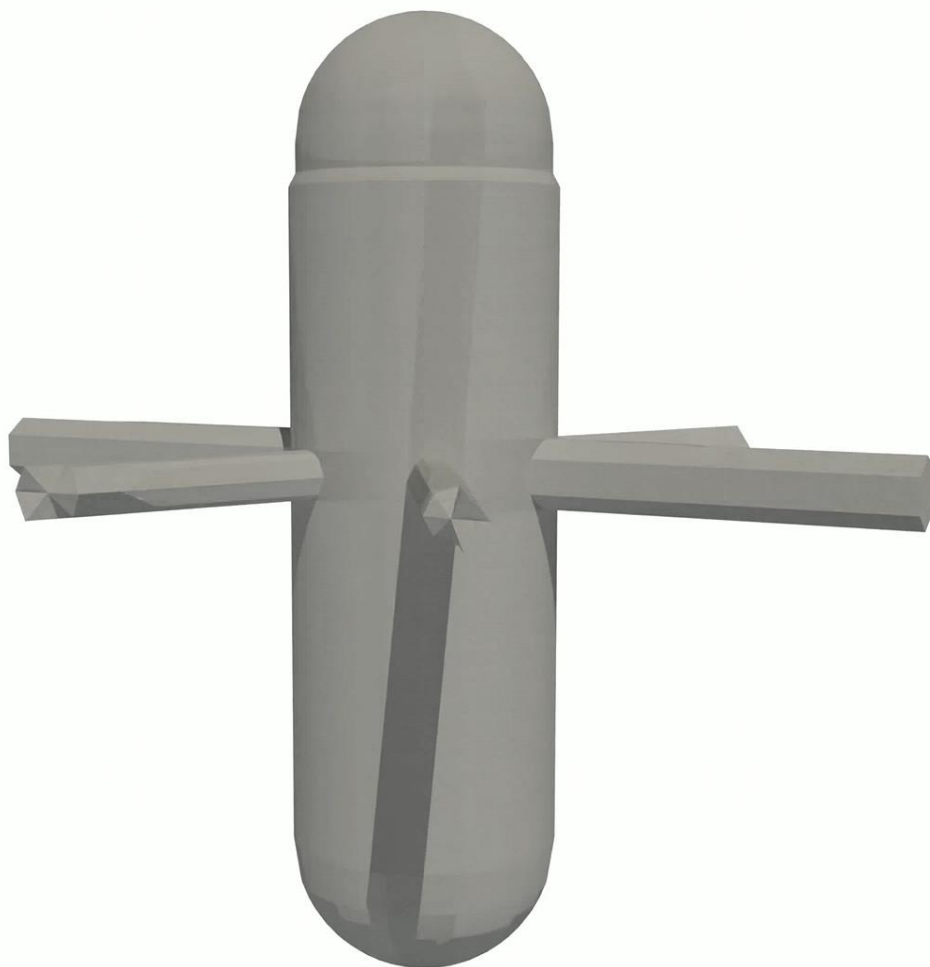
➤ Body-fitted RPV mesh

- **In-house** RPV mesh generator (*RVMesh3D*)
- Reactor core, downcomer, upper/lower plenum, and hot/cold leg
- Practical number of meshes (Currently **1.3M**)
- **Subchannel T/H resolution** for core region



MSMP Simulation of OPR1000 SLB Accident

» Steady State (End of Cycle Full Power)



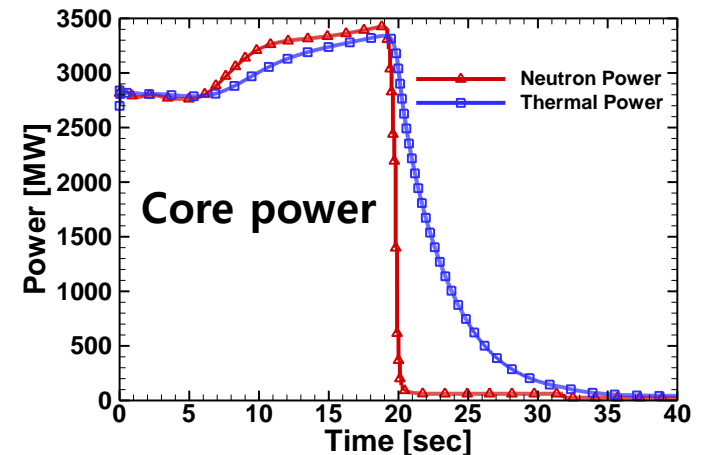
MSMP Simulation of OPR1000 SLB Accident

» Sequence of Events and Major Parameters

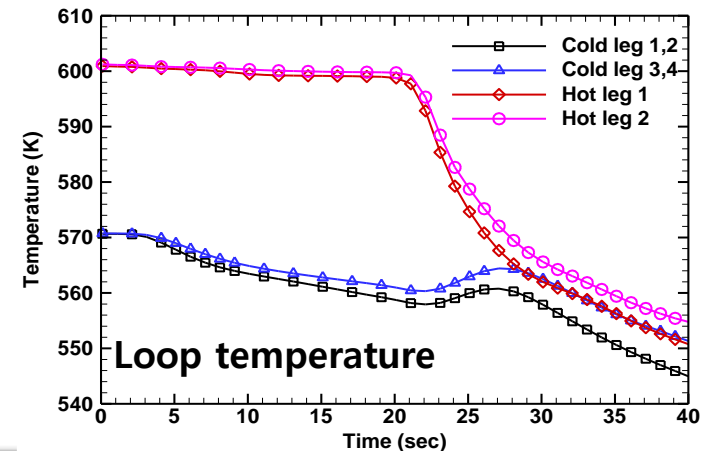
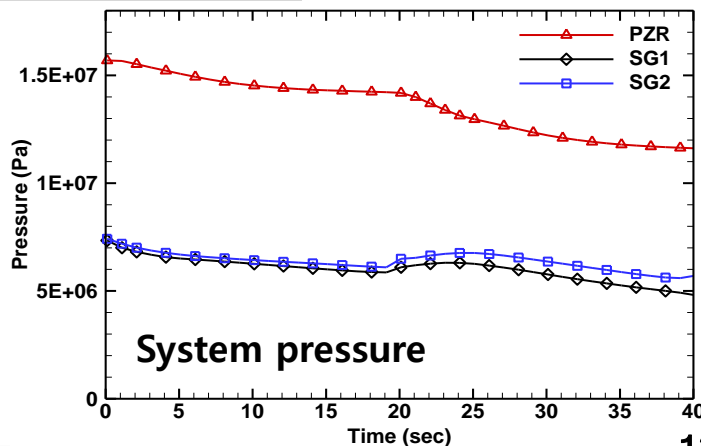
Sequence of events

Time(sec)	Event	Setpoint
0.0	Steam line break occurs	
18.4	Overpower trip setpoint reached	121 %
18.6	Turbine Trip	
19.1	Rod begins to drop	
34.0	Low SG1 setpoint reached	5.44 MPa
35.1	MSIV1 closed	

MSMP result

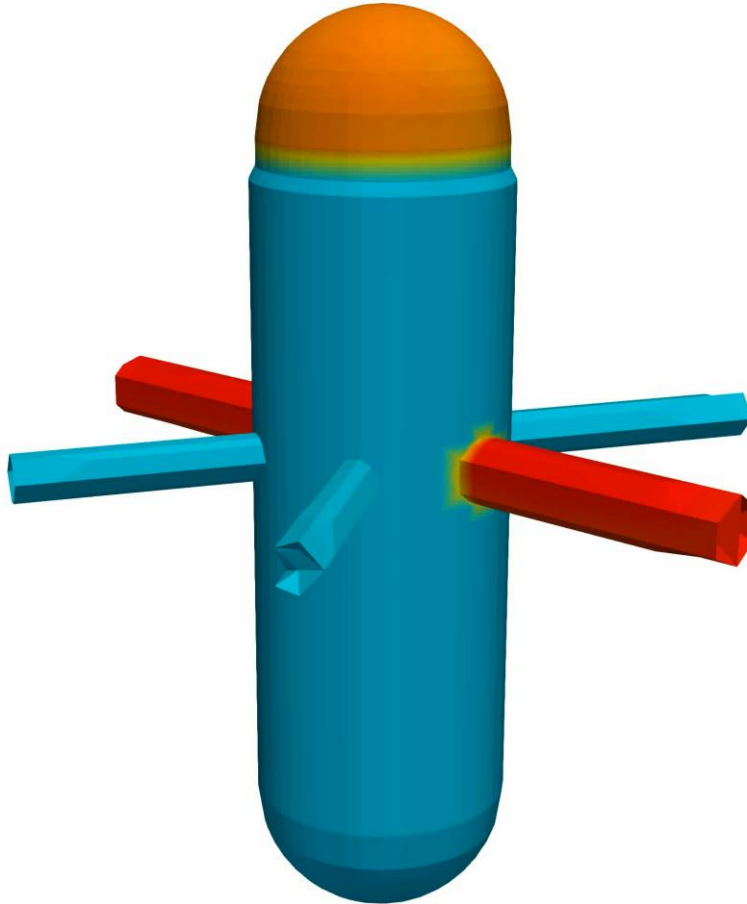


System TH result



MSMP Simulation of OPR1000 SLB Accident

» Power & DNBR Distribution



Sequence of events

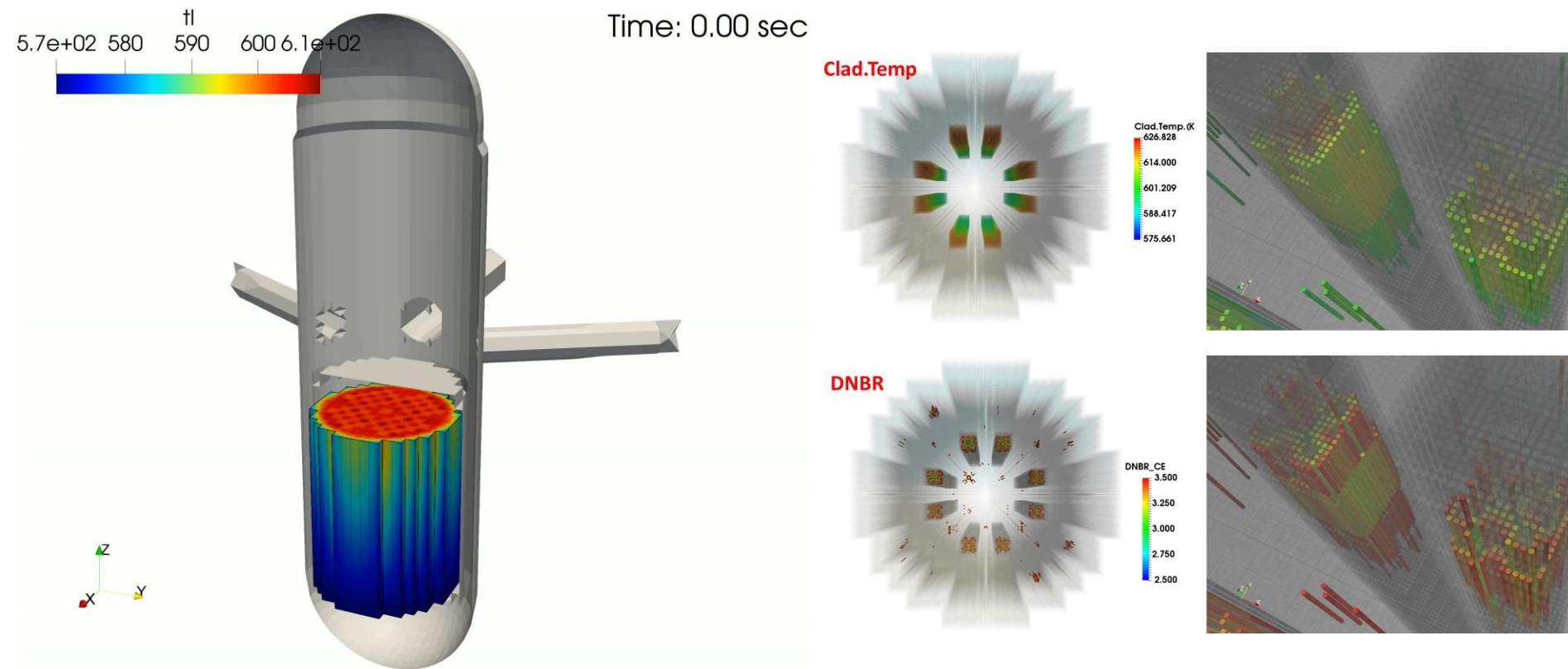
Time(sec)	Event
0.0	Steam line break occurs
18.4	Overpower trip setpoint reached
18.6	Turbine Trip
19.1	Rod begins to drop
31.0	Void begins to form in RV Upper P.
34.0	Low SG1 setpoint reached
35.1	MSIV1 closed

Performance

Problem time	100 sec
Resources	Intel® Xeon® Gold 6230R CPU @ 2.10GHz
Number of Procs	300
Computing time	120 min

MSMP Simulation of OPR1000 SLB Accident

» Fuel Rod Visualization (Clad temperature & DNBR)



Improvement of Safety Margin (DNBR)

» Safety Margin in SLB Accident

➤ Minimum DNBR in fuel assembly

※ DNBR: Departure from Nucleate Boiling Ratio

- Key parameter to ensure safety margin for SLB accident

➤ Enhancement of safety margin for MSMP approach

- 30% larger than 1D result

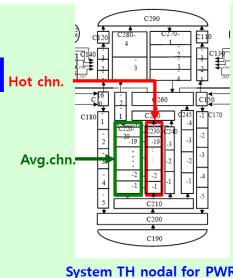
Methodology	MDNBR
1D System-scale TH	2.020
MSMP (without Turbulent mixing)	2.331
MSMP (with Turbulent mixing)	2.615



**Enhancement of
Safety Margin**

1D System-scale TH

- Axial flow ONLY
- Hot pin assumption
- Point kinetics



3D Full core rod-wise MSMP

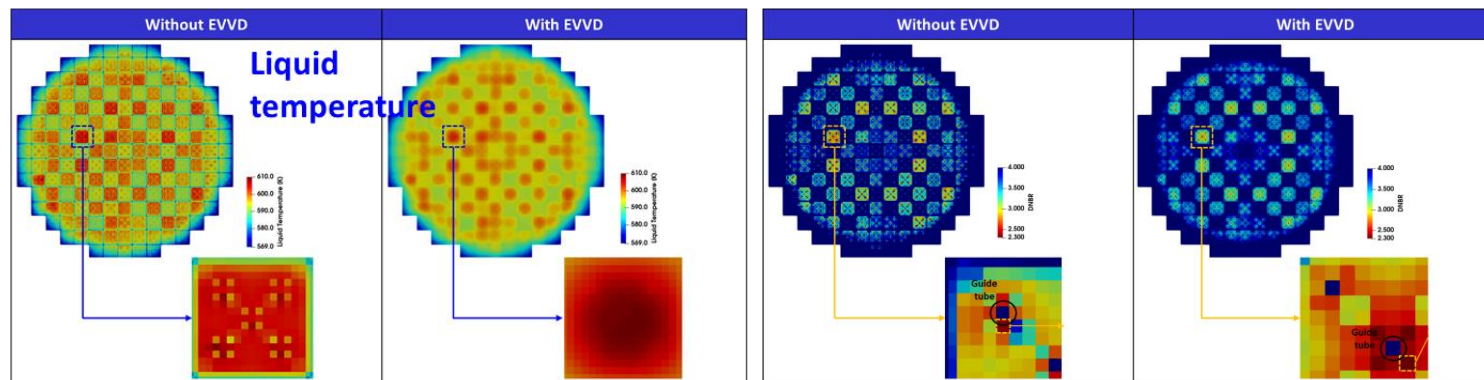
- Radial flow dispersion
- Pin-by-pin power distribution
- Channel-by-channel geometric parameters

Key parameters to enhance MDNBR in MSMP

» Key parameter 1: 3D Coolant Flow

➤ 3D radial flow dispersion with turbulent mixing

- Impossible to consider radial flow mixing in 1D safety analysis
- 3D Radial flow including turbulent mixing enhances coolability
- **Ensure additional safety margin**

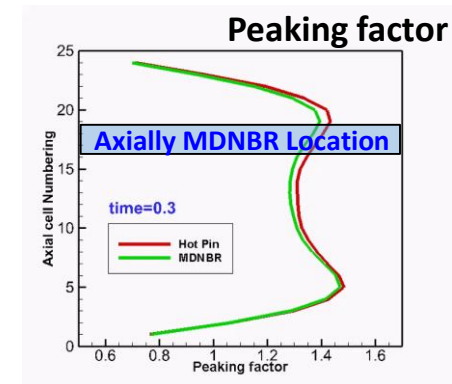
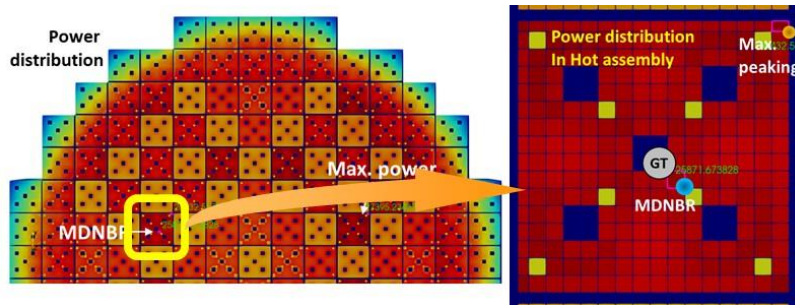


Key parameters to enhance MDNBR in MSMP

» Key parameter 2: Realistic fuel power (with N/K code)

➤ Power output of fuel assembly (pin-wise power)

- Co-simulation with N/K produces detailed rod-scale power
- MDNBR does not meet the Hot Pin assumption
 - ✓ 1D Safety analysis: Hot pin assumption to occur MDNBR
- Mitigate 1D conservative assumption
- **Ensure additional safety margin**



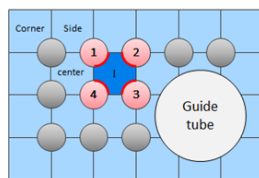
Key parameters to enhance MDNBR in MSMP

» Key parameter 3: Non-identical geometric parameters

➤ Various subchannel information

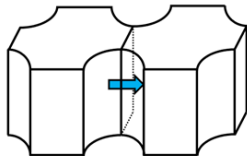
- Subchannel-scale resolution yields various geometric parameters
- CHF can be evaluated according to subchannel type
- **Ensure additional safety margin**

Various heated diameters

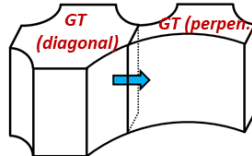


Subchannel type	Heated dia. [m]
Rod-to-Rod	0.012637
1D System TH	0.013012
Rod-to-GT (perpendicular)	0.013855
Rod-to-GT (diagonal)	0.016922

Rod-to-Rod



Rod-to-GT



MDNBR distribution for subchannel type

Subchannel type	Heated dia. [m]	K1	q''_{CHF}	MDNBR
Rod-to-Rod	0.012637	↑	↓	↓
1D System TH	0.013012			
Rod-to-GT (perpendicular)	0.013855		↓	↓
Rod-to-GT (diagonal)	0.016922		↓	↓

Full core Pin-wise Fuel Performance

4

- Pin-wise F/P code Coupling
- Evaluation of Pin-wise Fuel Performance in SLB Accident

Pin-wise Fuel Performance code Coupling (1/4)

» Fuel Performance Code

➤ US NRC FRAPTRAN code

- Single fuel rod behavior
- Coupled with system T/H code

» How to Couple for Source Level Multiple Fuels

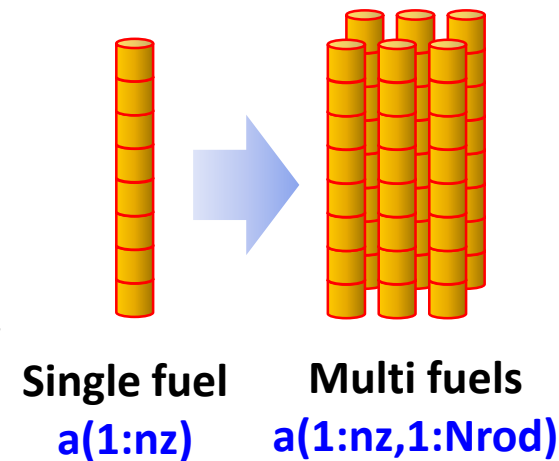
➤ Mapping between fuel's cell and fluid cell

- **CUPID** (sub. T/H): Fuel nodes of Internal heat structure model
- **FRAPTRAN** (F/P): Single-rod Fuel nodes

➤ Extend fuel code for multiple fuels

- **Extend coupling variables** for multi-rods
 - ✓ Including modification of F/P code (variables' array)
- **Call fuel code** as many as the number of fuels

```
DO i=1,Nrods
  Call FRAPTRAN(i)
ENDDO
```



Pin-wise Fuel Performance code Coupling (2/4)

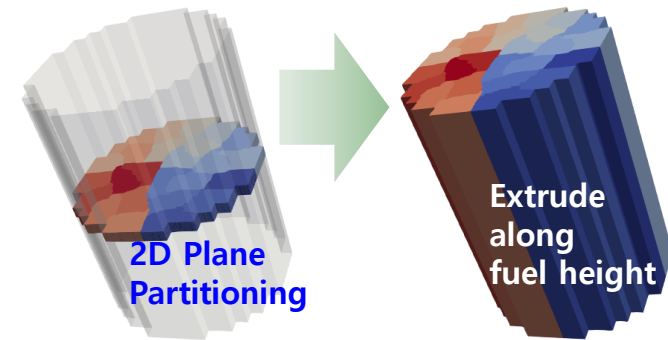
» Parallel for Pin-wise Full Core Simulation

➤ Prerequisite for simple mapping

- Single fuel is not partitioned

➤ Domain partitioning by METIS

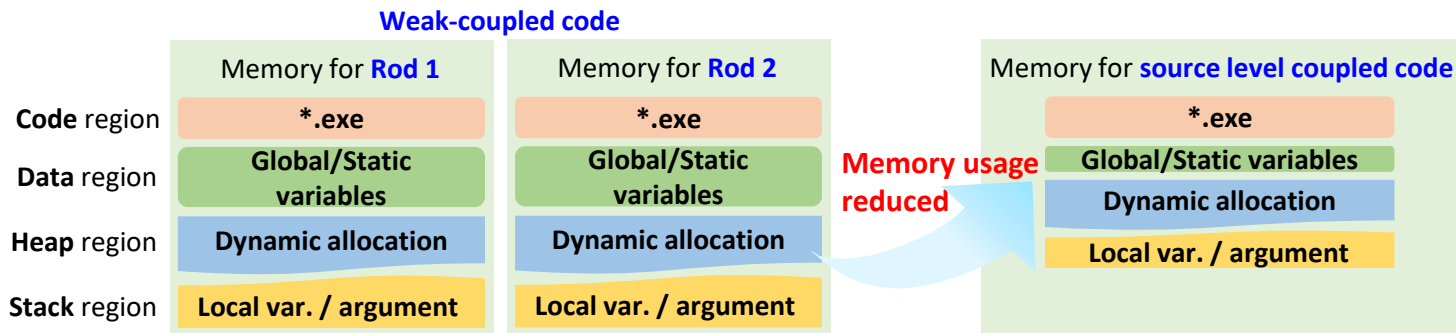
- Partitioned **2D** plane
- **Extrude** along fuel height



» Parallel Computing in HPC Environment

➤ SPMD (Single Program, Multiple Data)

- Source-to-source compilation
- **Efficient memory usage** for massive multiple fuels calculation.

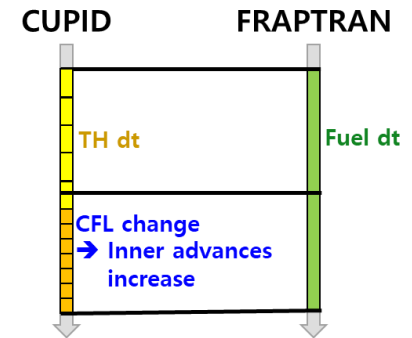


Pin-wise Fuel Performance code Coupling (3/4)

» Time Advance

➤ Time-step control between TH and Fuel code

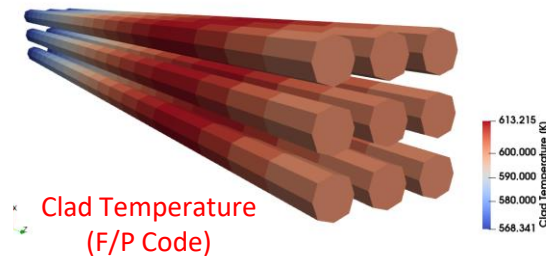
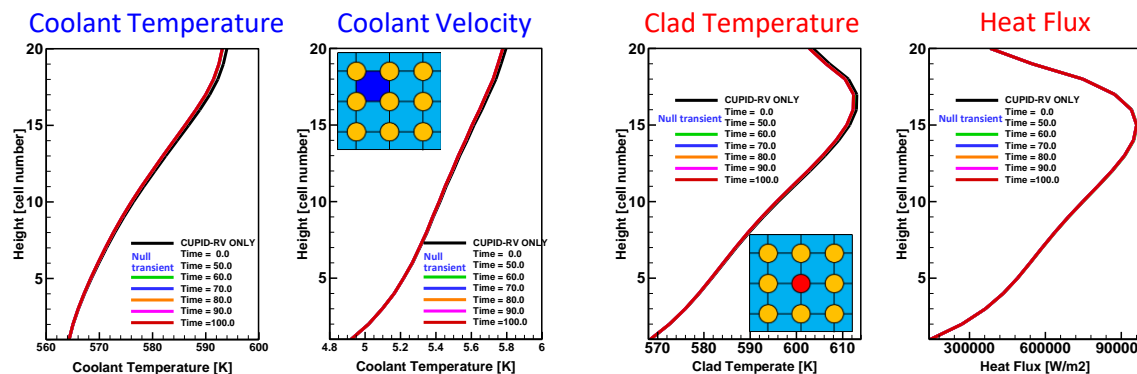
- Time-marching scheme is implemented
 - ✓ Time marching between CUPID and FRAPTRAN
 - ✓ The number of **inner advances** determined
- Final time step determined by system T/H (MARS) and sub. T/H (CUPID)



» Verification(1) – 3x3 Fuel Rods

➤ CUPID-RV/FRAPTRAN

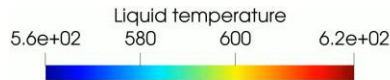
- Fuel behavior from FRAPTRAN



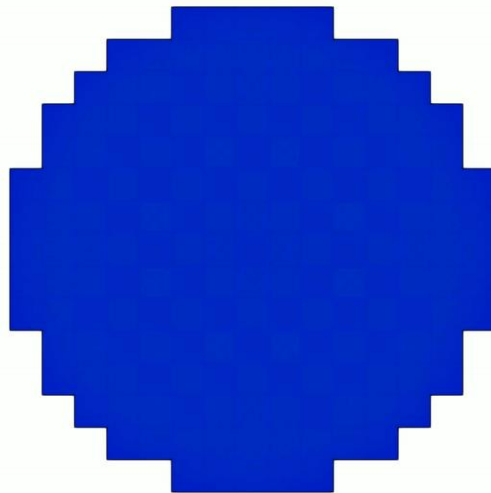
Pin-wise Fuel Performance code Coupling (4/4)

» Verification(2) – LWR Full Core

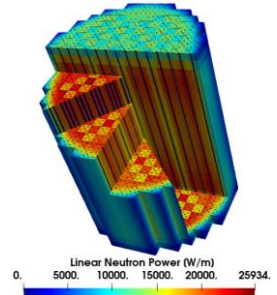
- Steady state of OPR1000 core region
- CUPID-RV/MASTER/FRAPTRAN
 - Sub. T/H & N/K & F/P coupled simulation



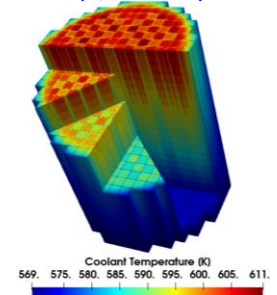
T/H (CUPID)



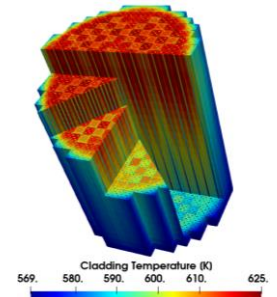
Neutron Power
(N/K Code)



Coolant Temperature
(T/H Code)



Clad Temperature
(F/P Code)



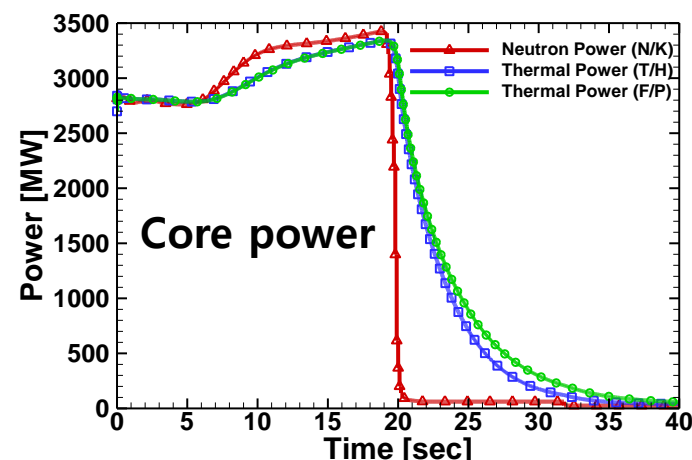
Evaluation of Pin-wise F/P in SLB Accident

» Evaluation by Fuel code

➤ Steam line break accident (SLB)

- Fuel behavior calculated by FRAPTRAN
- Radial conduction is dominant
- Similar pattern with simple heat structure model of T/H code
- MDNBR expected lower slightly

Methodology	MDNBR
1D System-scale TH	2.020
MSMP (w/o F/P)	2.615
MSMP (w/i F/P)	2.563



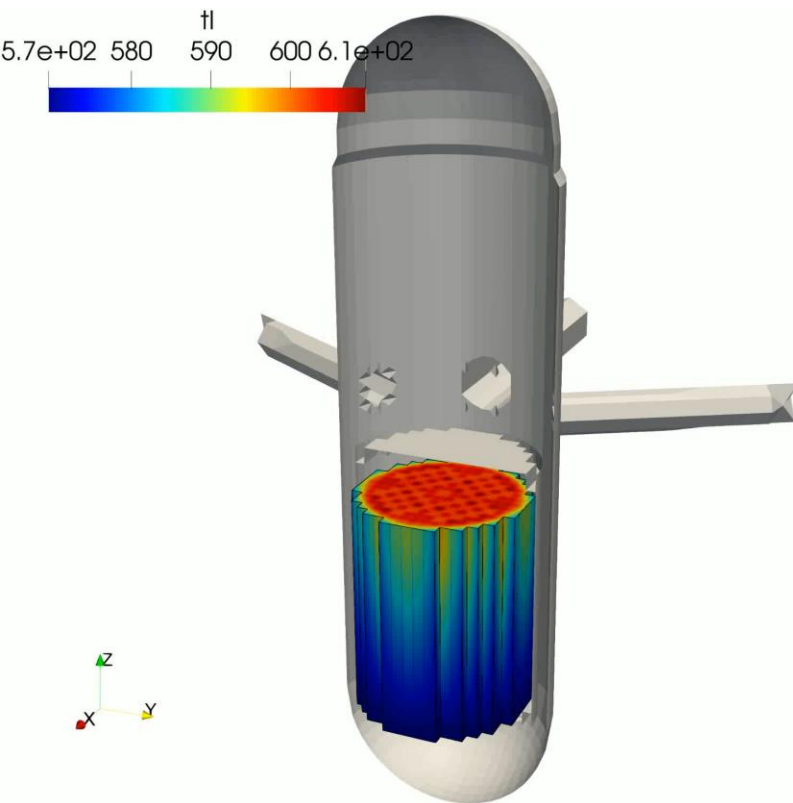
➤ Capability for pin-wise fuel behavior

- Other accidents such as RIA can be accessed (On-going)
 - ✓ F/P code becomes considerably important in safety analysis for RIA accident

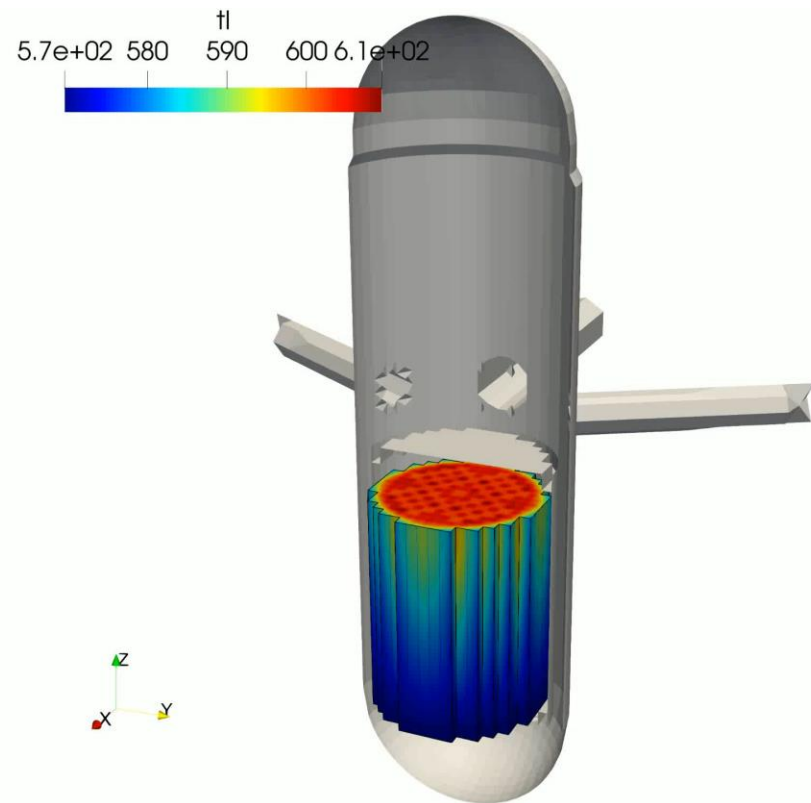
Evaluation of Pin-wise F/P in SLB Accident

» Fuel Rod Visualization (Clad temperature & DNBR)

Without F/P code



With F/P code



Evaluation of Pin-wise F/P in SLB Accident

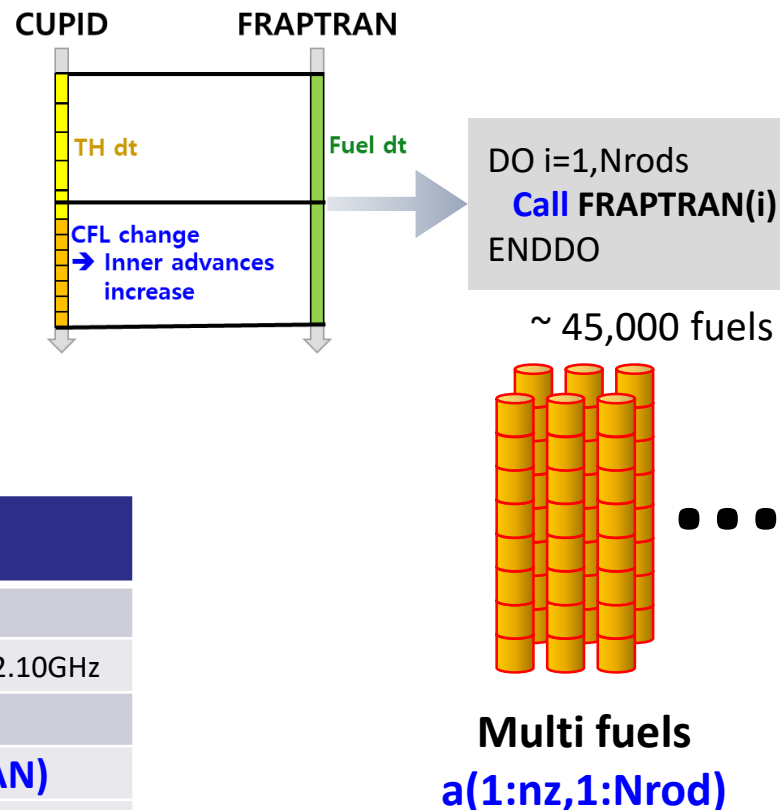
» Performance of F/P-Coupled Code

➤ Pin-wise F/P calculation

- OPR1000 → about 45,000 fuels
- 45,000 F/P calls

➤ SLB accident safety analysis

- **33% increase** of computing time
- **Needs to optimize** (On-going)



Performance	
Problem time	100 sec
Resources	Intel® Xeon® Gold 6230R CPU @ 2.10GHz
Number of Procs	300
Computing time	160 min (w/I FRAPTRAN)
	120 min (w/o FRAPTRAN)

Summary

4

– Summary



Summary

» 3D Safety Analysis for SLB

- **MSMP (Multi-scale & Multi-Physics) approach**
- **Realistic RPV modeling with in-house mesh generator**
- **Platform for T/H & N/K & F/P code**

» Necessity for 3D MSMP Simulation

- **Detailed Visualization inside of RPV**
 - **3D** Visualization of **full core fuel power** distribution
- **Enhancement of safety margin**
 - Realistic **MDNBR evaluation**
 - **Improvement of MDNBR** designed by 1D safety analysis
- **Pin-wise fuel evaluation by F/P code coupling**
 - Extend F/P code to **pin-wise full core** fuel analysis of LWR
 - Qualitatively reasonable fuel behavior
 - Should be applied to RIA

THANK YOU

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